

## Standard ECMA-74

21st Edition / June 2025

Measurement of
Airborne Noise emitted
by Information
Technology and
Telecommunications
Equipment

Melan





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## Introduction

ECMA-74 specifies methods for the measurement of airborne noise emitted by information technology and telecommunications equipment. Hitherto, a wide variety of methods have been applied by individual manufacturers and users to satisfy particular equipment or application needs. These diverse practices have, in many cases, made comparison of noise emission difficult. This Standard simplifies such comparisons and is the basis for declaration of the noise emission level of information technology and telecommunications equipment.

In order to ensure accuracy, validity and acceptability, this Standard is based on the basic Standards for determining the sound power level and for determining the emission sound pressure level at the operator position(s) and bystander position(s). Furthermore, implementation is simplified by conformance with these International Standards.

In many cases free-field conditions over a reflecting plane are realised by hemi-anechoic rooms. These rooms may be particularly useful during product design to locate and to improve individual contributing noise sources. Reverberation test rooms may be more economical for production control and for obtaining sound power levels for noise emission declaration purposes.

The method for measuring the emission sound pressure level at the operator or bystander positions (based on ISO 11201) is specified in a separate clause, as this level is not considered to be primary noise emission declaration information. The measurements can, however, be carried out in conjunction with those for sound power determination in a free field over a reflecting plane.

For comparison of similar equipment it is essential that the installation conditions and mode of operation are the same. In Annex C these parameters are standardized for many categories of equipment.

The first edition of this Standard was issued in September 1981. It was contributed to ISO/TC 43 and formed the base for ISO 7779:1988, first edition. The second edition of ECMA-74 was issued in December 1987. The third edition was issued in December 1992 and was submitted to ISO for fast-track processing as a revision to ISO 7779 in the spring of 1993. The document was balloted by ISO from November 1994 to May 1995 and was approved with 18 of 20 P members in favour and 2 of 22 member bodies opposed. The fourth edition was issued in December 1996, taking into account most of the comments that accompanied the voting. The fifth edition was issued December 1997 to add a new equipment category – CD- and DVD-ROM drives as C.19.

ISO 7779, second edition, was published August 1<sup>st</sup>, 1999. The sixth edition of ECMA-74 was adapted to the final wording of new ISO 7779 and also included additional provisions for CD- and DVD-ROM drives as C.19. Now C.19 with minor modifications was adopted as ISO/DIS 7779 Amendment 1.

The C.19 changes that are in ISO/DIS 7779 Amendment 1 along with a revised Annex B and a revised Annex D are included in the seventh edition of ECMA-74, which was approved in December, 2002. The Annex B includes a provision allowing the use of a 0,5 m radius hemispherical surface for measuring the sound power emitted by small noise sources such as disk drives. Annex B also allows the use of a cylindrical measurement surface. The revised Annex D in the seventh edition includes prominence ratio in addition to tone-to-noise ratio, provides improved figures illustrating the tone-to-noise and prominence ratio calculations, and contains new criteria for prominent discrete tones. The new criteria are a result of a three-year study by Ecma TC26 and ITI TC6.

For the eighth edition, the reference list was updated and some text modified to account for the changes. The cylindrical measurement surface section of Annex B was re-worded to more closely follow the wording used in the draft of ISO 3744. Annex C contains additional figures in section C.15 on personal computers and workstations. A new equipment category, C.20, for data projectors was added. Also Annex D was expanded with additional figures, equations and examples.

For the ninth edition, only Annex D was modified. Changes were made in part to better define the critical band edges, including changing from geometric critical bands to arithmetic critical bands for frequencies below 500 Hz. Also, curves were fitted to the band edges for the lower and upper critical bands when calculating prominence ratio, thus eliminating the need to use iteration for the calculations. Clarifications were added on frequency range of interest and elsewhere. The criteria for prominence did not change.



For the 10<sup>th</sup> edition, changes were made to the main body of the Standard to be in agreement with upcoming changes in the underlying standards: ISO 3741, ISO 3744, ISO 3745 and ISO 11201. Two new equipment categories were added to Annex C: 1) multi-function devices (MFDs) and 2) hand-held computing and media playback devices. The addition of these categories included some changes in the main body of the Standard as well as some of the other print-related categories. Annex D was revised to give clearer direction on determining the prominence of tones as well as introducing the concept of Threshold of Hearing when analyzing very low-noise equipment.

For the 11<sup>th</sup> edition, changes were made to the Standard to align more closely with ISO 7779:2010, 3<sup>rd</sup> edition. A new equipment category was added to Annex C, Digital media recorders and playback units for consumer use. Also the document was reformatted with the new Ecma standards template.

For 12<sup>th</sup> edition, there were several updates as follows:

- In Clause 3, the wording of some definitions was updated to be more consistent with the basic standards (ISO 3741, ISO 3744, ISO 3745, ISO 11201).
- In 7.3.1 and related sections, an expanded criteria on the environmental correction  $K_2$  was added to address its more detailed treatment in the basic standards.
- In Annex B, the minimum number of fixed microphone positions on the cylindrical measurement surface was made consistent with ISO 3744 Annex D.
- In Annex C, the clarity and consistency of procedures for imaging equipment under C.3, C.13, C.16 and C.21 were improved. Inkjet printers were categorized under C.16. Procedures for measuring idle mode noise were made uniform. The measurement of functional operations under C.13, C.16 and C.21 were aligned with one another and with the typical use prescription of C.1. The consistency of media use and reporting procedures across C.13, C.16 and C.21 was improved. Hand-held computing and media playback devices under C.22 having neither air moving devices nor a hard disk drive were generally exempted from reporting requirements.
- In Annex D, bibliographical references [40], [41] and [42] were replaced by ISO 28961<sup>[9]</sup>.

For 13<sup>th</sup> edition, there were several updates as follows:

- In 6.4.6 and 7.4.6, the microphone calibration procedures were amended to be consistent to those of the basic standards (ISO 3741 and 3744, respectively).
- In 7.3.1, the procedure for test environment qualification was amended to clarify that any frequency bands, typically low in frequency, not significantly affecting A-weighted sound power level need not meet the hemi-anechoic room qualification criteria for the purposes of determining A-weighted sound power level.
- In Annex B, B.2, a procedure for reducing the microphone positions on cylindrical measurement surface was introduced. This procedure is not presently in ISO 3744 but is expected in future versions of ISO 3744. In addition, editorial improvements were made, and equations were renumbered.
- In Annex D, some editorial improvements were made, and references to content within the annex were corrected (no technical changes).
- In Annex E, the method for detecting impulsive noise was removed. Because, by the recent update of IEC 61672-1:2013, the time-weighting I, which was the technical basis of the previous detection method in Annex E, had been removed. However, for historical reasons and also for the possibility of future development of another method detecting for impulsive noise, this informative Annex E remains with the same title, at least, in the 13<sup>th</sup> edition.

For 14<sup>th</sup> edition, there were several updates as follows:

 Annex C, C.21 Multi-function devices and its related categories were updated to harmonize their grammages and to refine MFD's mandatory test conditions.

For 15<sup>th</sup> edition, there were several updates as follows:

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- In Annex D descriptions were amended to clarify that Annex D permits using FFT data below 89,1 Hz and above 11 200 Hz to calculate tone-to-noise ratio and prominence ratio. Notes were added to indicate that new metrics are under development for detecting prominent discrete tones for small fans whose noise emissions consist of many harmonic components and other discrete tones.
- A new Annex F was included on a hearing model approach to calculate psychoacoustic parameters such as prominent tonalities contained in the new Annex G and other psychoacoustic parameters.
- A new Annex G was included on the identification and evaluation of prominent tonalities using a
  psychoacoustic tonality calculation method, which is based on the hearing model approach in Annex
  F. This method complements the procedures for determining prominent discrete tones contained in
  Annex D.

For the 16<sup>th</sup> edition, changes were made to the Standard to align more closely with ISO 7779:2018, 4<sup>th</sup> edition<sup>[14]</sup>. In addition, Annex C was revised to add a new product category "Large Format Printers, and the product category "multi-function devices" (MFD) was renamed to "multi-function printers" (MFP). There were several updates as follows:

- In Clause 3, 3.1 General definitions and 3.2 Acoustical definitions were updated to be consistent with those of International counterpart, ISO 7779 which relies on basic standards, such as ISO/TR 25417, ISO 80000-8 etc., 3.3 Definitions related to uncertainty was newly added, corresponding to new Clause 9.
- In Clause 7, 7.3.1 was divided into 7.3.1.1 to 7.3.1.3, and amended to clarify that this Standard permits applying either ISO 3744 or ISO 3745 for hemi-anechoic room qualification.
- In Clause 8, 8.6, new 8.6.1 was inserted to clarify the method of defining operator position and bystander positions. And, references to new 8.6.2 (operator position) and new 8.6.3 (bystander positions) were amended accordingly
- In Clause 9, Measurement uncertainty was newly inserted.
- In relation to Clause 9, 3.3 was also added, and the descriptions of Tables 1, 5 and 6 (in 6.2, 7.2 and 8.2 respectively), and 10.2 were amended.
- In Annex B, B.2.3 was amended to make the descriptions of measurement surface and the number of microphone positions consistent with those of International counterpart, ISO 7779.
- In Annex C, C.24 Large format printers was newly standardized, with related updates to C.1, C.16 and C.21. C.21 Multi-function devices (MFD) was renamed to "Multi-function printers (MFP)", and mandatory mode of operation was revised, with related updates to C.1. Relating to the above, distinctions between printing devices C.3, C.16, C.21 and C.24 were improved.
- In Annex D, in D.9.7 and D.10.7, NOTES were amended to mention that new metrics proposed by ECMA TR/108 for detecting prominent discrete tone, (1) total tone-to-noise ratio and (2) total prominence ratio are under development.

For the 17<sup>th</sup> edition, there were several updates as follows:

- The rounding of recorded sound pressure levels and sound power levels in 10.1.5 was changed to 0,1 dB deleting the option permitting rounding to 0,5 dB. A similar change was made for reported levels in 10.2.
- Two definitions were added in Clause 3.2: Prominent Discrete Tones and Prominent Tonality.
- Annex C, C.24 Large format printers was revised to clarify the definitions of professional printers which are excluded from scope of this category. And acceptable grammage of paper for graphics applications was expanded to 200-300 g/m².
- Annex F, Modified outer and middle-/inner ear transfer function (Figure F.3, Table F.1) and the LTQ (Figure F.4, Table F.3) have been introduced in order to simulate the equal loudness contours according to ISO 226-2003 for all frequencies. In the 15<sup>th</sup> edition, for frequencies above 1 kHz the simulated equal loudness contours were matching the ISO 226-2003 values and for lower frequencies

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the ISO 226-1987 values. The newer data corresponds better to results of recent listening tests. The filters used in the 15<sup>th</sup> edition lead to an overestimation of tonalities at frequencies below 500 Hz.

 Annex G, Corrections of two mathematical formulations ((G.1) and (G.4)); constraints for searching tonal components were removed (Formula (G.6) in 15<sup>th</sup> edition) to improve the algorithm, and some variables were renamed for reasons of clarity.

For the 18<sup>th</sup> edition, there were several updates related to the creation of the psychoacoustic standards ECMA-418-1 and ECMA-418-2, the introduction of new operating conditions for personal computers and workstations in Annex C.15, and the introduction of operator positions for rack-mountable units and rack-enclosed systems in Annex C.18:

- In Clause 3 the term operator was defined.
- In 8.6.2, Figure 1 was divided into three figures by category: floor-standing equipment, table-top equipment, and hand-held equipment.
- Clause 10 was changed to require reporting of the maximum of the measured operator sound pressure levels when multiple operator positions are measured for rack-mountable units or rackenclosed systems.
- New operating conditions for personal computers and workstations in Annex C.15.3. The modes of operation were designed to represent typical use of the whole system for the relevant segments. The idle mode remains, and four (4) new operating conditions were defined. These are system level tests, but a note is included with references to component level tests."
- Table C.1 was altered to require measurement of sound pressure level at either operator or bystander positions for rack-mountable units and rack-enclosed systems. Procedures for measuring and reporting sound pressure levels at operator positions for rack equipment were introduced in C.18.
- In Annex C.18, figures were renumbered to accommodate new figures illustrating operator positions for rack-mountable units and rack-enclosed systems. Figure C.5 of the 17<sup>th</sup> edition showing a print test pattern was renamed as Figure C.8.
- Annex D was reduced to a single page citing the new standard ECMA-418-1, Psychoacoustic metrics for ITT equipment - Part 1 (prominent discrete tones). The technical content of Annex D in the 17<sup>th</sup> edition was moved to ECMA-418-1.
- Annex F was reduced to a single page citing the hearing model content in the new standard ECMA-418-2, Psychoacoustic metrics for ITT equipment Part 2 (models based on human perception). The hearing model content of Annex F in the 17<sup>th</sup> edition was moved to ECMA-418-2.
- Annex G was reduced to a single page citing the prominent tonality content in the new standard ECMA-418-2, Psychoacoustic metrics for ITT equipment - Part 2 (models based on human perception). The prominent tonality content of Annex G in the 17<sup>th</sup> edition was moved to ECMA-418-2.
- Annex H was introduced citing the roughness content in the new standard ECMA-418-2,
   Psychoacoustic metrics for ITT equipment Part 2 (models based on human perception).

For the 19<sup>th</sup> edition, there were revisions related to Annex C.16. The title of C.16 was revised to "Single-function printers", and the scope of C.16 was revised to allow equipment capable of printing rolled stationery and to include inkjet and laser printers explicitly. Specifications were introduced for rolled stationary grammage along with print pattern and print area for paper sizes smaller than A4.

For the 20th edition, there were revisions related to headless PC's and printers.

- Annex C.15 was expanded to accommodate headless PC's, which are PC's not intended to physically support a monitor.
- The scopes of printer related Annexes C.3, C.16, and C.24 were clarified for character and line printers, single-function printers, and large format printers by revised formatting and presentation

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order and introducing descriptions of printer technologies to be included and excluded from C.16 scope.

For the 21<sup>st</sup> edition revisions pertained to measurements of equipment with noise emissions that change due to environmental or operational thresholds, and there was a reduction in the number of sheets of paper required for the measurement of a slow printer.

- Clauses 6, 7 and 8 were revised to permit supplemental measurements under meteorological conditions representative of the equipment's operation for equipment whose noise emissions vary with ambient temperature and/or altitude in a prescribed manner. Supplemental measurements permit testing equipment, for which noise varies with temperature, at temperatures outside of the 23 °C ± 2 °C range. Sound power and bystander/operator sound pressure level computations have been updated to make reference to ISO 3745 and ISO 11201 respectively for corrections due to different meteorological conditions. A barometric formula is included to provide a means to convert altitude to barometric pressure. Since this is the first formula in the main body, all other formulae in the main body were renumbered.
- Clause 10 was revised to add recording and reporting requirements that correspond to the new
  potential measurement cases for time-varying equipment added to Clauses 6, 7 and 8. Consequently,
  the ambient temperature and/or altitude must now be recorded and reported, when applicable,
  including as it pertains to simulated operation.
- A requirement was added to Annexes C.15 and C.18 to operate the system from idle to improve repeatability by controlling for hysteresis effects.
- Annexes C.16 and C.21 reduced the measurement time interval from three sheets to one sheet related in slow printing operations in case of printing over 30 second per one sheet for one-sided simplex printing.

This Ecma Standard was developed by Technical Committee 26 and was adopted by the General Assembly of June 2025.



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# Measurement of Airborne Noise emitted by Information Technology and Telecommunications Equipment

## 1 Scope

This Ecma Standard specifies procedures for measuring and reporting the noise emission of information technology and telecommunications equipment.

NOTE 1 This Standard is considered part of a noise test code (see 3.1.2) for this type of equipment, and is based on basic noise emission standards (see 3.1.1) ISO 3741, ISO 3744, ISO 3745 and ISO 11201.

The basic emission quantity is the A-weighted sound power level which can be used for comparing equipment of the same type but from different manufacturers, or for comparing different equipment.

Three basic noise emission standards for determination of the sound power levels are specified in this Ecma Standard in order to avoid undue restriction on existing facilities and experience. ISO 3741 specifies comparison measurements in a reverberation test room; ISO 3744 and ISO 3745 specify measurements in an essentially free field over a reflecting plane. Any one of these three basic noise emission standards can be selected and used exclusively in accordance with this Standard when determining sound power levels of a machine.

The A-weighted sound power level is supplemented by the A-weighted emission sound pressure level determined at the operator position or the bystander positions, based on the basic noise emission standard ISO 11201. This sound pressure level is not a worker's noise immission at a work station (see 3.2.12), but it can assist in identifying any potential problems that could cause annoyance, activity interference or hearing damage to operators and bystanders.

Method for determination of whether the noise emission includes prominent discrete tones is specified in Annex D.

Annexes G and H reference psychoacoustic methods described in ECMA-418-2 on the identification and evaluation of prominent tonalities and prominent roughness generated by information technology and telecommunications equipment

This Standard is suitable for type tests and provides methods for manufacturers and testing laboratories to obtain comparable results.

The methods specified in this Standard allow the determination of noise emission levels for a functional unit (see 3.1.4) tested individually.

The procedures apply to equipment which emits broad-band noise, narrow-band noise and noise which contains discrete-frequency components, or impulsive noise.

The sound power levels and emission sound pressure levels obtained can serve noise emission declaration and comparison purposes (see ECMA-109).

NOTE 2 The sound power levels and emission sound pressure levels obtained are not intended to be considered as installation noise immission levels; however they can be used for installation planning (see ECMA TR/27<sup>[16]</sup>).

If sound power levels obtained are determined for a number of functional units of the same production series, they can be used to determine a statistical value for that production series (see ECMA-109).



## 2 Normative references

The following referenced documents are indispensable for the application of this Standard. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ECMA-108 Determination of High-frequency Sound Power Levels Emitted by Information Technology and Telecommunications Equipment

NOTE ISO 9295<sup>[3]</sup> is ISO counterpart of ECMA-108. It is noted that, after the revision in 2015, the scope of ISO 9295 covers machinery and equipment in general, not limited to information technology and telecommunications equipment.

ECMA-418 Psychoacoustic metrics for ITT equipment - Part 1 (prominent discrete tones)

ECMA-418 Psychoacoustic metrics for ITT equipment - Part 2 (models based on human perception)

ISO 3741 Acoustics — Determination of sound power levels and sound energy levels of noise sources using sound pressure — Precision methods for reverberation test rooms

ISO 3744 Acoustics — Determination of sound power levels and sound energy levels of noise sources using sound pressure — Engineering methods for an essentially free field over a reflecting plane

ISO 3745 Acoustics — Determination of sound power levels and sound energy levels of noise sources using sound pressure — Precision methods for anechoic test rooms and hemi-anechoic test rooms

ISO 6926 Acoustics — Requirements for the performance and calibration of reference sound sources used for the determination of sound power levels

ISO 10302-1 Acoustics — Method for the measurement of airborne noise emitted and structure-borne vibration induced by small air-moving devices — Part 1: Airborne noise measurement

ISO 10302-2 Acoustics — Method for the measurement of airborne noise emitted and structure-borne vibration induced by small air-moving devices — Part 2: Structureborne vibration measurement

ISO 11201 Acoustics — Noise emitted by machinery and equipment — Determination of emission sound pressure levels at a work station and at other specified positions in an essentially free field over a reflecting plane with negligible environmental corrections

ISO 11203 Acoustics — Noise emitted by machinery and equipment — Determination of emission sound pressure levels at a work station and at other specified positions from the sound power level

IEC 60942 Electroacoustics — Sound calibrators

IEC 61183 Electroacoustics — Random-incidence and diffuse-field calibration of sound level meters

IEC 61260-1 Electroacoustics — Octave-band and fractional-octave-band filters — Part 1: Specifications

IEC 61672-1 Electroacoustics — Sound level meters — Part 1: Specifications

ISO/IEC 10561:1999 Information technology — Office equipment — Printing devices — Method for measuring throughput — Class 1 and Class 2 printers

NOTE 1 C.3 refers to ISO/IEC 10561:1999.

ISO/IEC 11160-1:1996 Information technology — Office equipment — Minimum information to be included in specification sheets — Printers — Part 1: Class 1 and Class 2 printers

NOTE 2 C.3 refers to ISO/IEC 11160-1:1996.



## 3 Terms and definitions

For the purposes of this Ecma Standard, the terms and definitions given in ISO 3744, and ISO 11201, and the following apply.

NOTE If a definition is identical to that in another standard, that standard and definition number is given in brackets.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at https://www.iso.org/obp
- IEC Electropedia: available at http://www.electropedia.org/

#### 3.1 General definitions

#### 3.1.1

## basic noise emission standard

## **B-type standard**

standard which specifies a procedure for determining the noise emission of machinery and equipment in such a way as to obtain reliable, reproducible results with a degree of accuracy

[SOURCE: ISO 12001:1996[8], 3.1]

#### 3.1.2

## noise test code

## C-type standard

standard that is applicable to a particular class, family or type of machinery or equipment which specifies all the information necessary to carry out efficiently the determination, declaration and verification of the noise emission characteristics under standardized conditions

[SOURCE: ISO 12001:1996<sup>[8]</sup>, 3.2, modified — NOTE 1 to entry was added.]

NOTE This Standard (ECMA-74) together with ECMA-109<sup>[15]</sup> comprises the noise test code for ITT Equipment. These Standards are Ecma counterparts of ISO 7779<sup>[14]</sup> and ISO 9296<sup>[4]</sup>, respectively. Both set of noise test codes (Ecma and ISO) are consistent with guidelines specified in ISO 12001.

#### 3.1.3

## information technology and telecommunications equipment ITT equipment

equipment for information processing, and components thereof, used in homes, offices, server installations, telecommunications installations, or similar environments

NOTE Annex C, which specifies particular requirements for use with this Standard, may be useful in identifying many of the categories of ITT equipment.

## 3.1.4

#### functional unit

unit of information technology and telecommunications equipment, either with or without its own end-use enclosure, that is tested or intended to be tested according to the procedures of this Standard

NOTE 1 A functional unit can comprise more than one unit of ITT equipment when such units are to be tested together in accordance with the methods of this Standard. A functional unit can also comprise one or more units of ITT equipment coupled to one or more units of non-ITT equipment, such as power modules, water pumps, or refrigeration units, when such equipment is necessary for the normal operation of the ITT equipment.

NOTE 2 Functional units of ITT equipment can take on a wide range of forms, including commercially-available products, prototype units under development, or sub-assemblies and components thereof.



#### 3.1.5

## work station

## operator's position

position in the vicinity of the equipment under test which is intended for the operator

NOTE 1 Adapted from ISO 11201:2010, 3.11.

NOTE 2 This term does not refer to a computer "workstation", which denotes a high-performance, single-user computer.

#### 3.1.6

#### operator

individual whose work station is in the vicinity of equipment and who is performing a work task associated with that equipment

NOTE Adapted from ISO 11201:2010, 3.12.

#### 3.1.7

#### operating mode

condition in which the equipment being tested is performing its intended function(s)

#### 3.1.8

## idle mode

one or more steady-state conditions in which the equipment being tested is energized but is not operating

#### 3.1.9

#### floor-standing equipment

functional unit which is intended to be installed on the floor

## 3.1.10

## table-top equipment

functional unit which has a complete enclosure and which is intended to be installed or used on a table, desk or separate stand

## 3.1.11

## wall-mounted equipment

functional unit which is normally mounted against or in a wall and which does not have a stand of its own

## 3.1.12

## sub-assembly

functional unit, generally without its own end-use enclosure, intended to be installed in another unit of ITT equipment or assembled together with other sub-assemblies or units of ITT equipment into a single end-use enclosure

## 3.1.13

#### rack-mountable unit

functional unit that is designed to be installed in an end-use enclosure in the form of a rack, frame, or cabinet, either fully-enclosed, partially-enclosed, or open-frame

## 3.1.14

## rack-enclosed system

functional unit in the form of a rack, frame, or cabinet containing one or more rack-mountable units

NOTE Rack-enclosed systems represent a wide variety of ITT equipment, depending on the particular configuration of the rack-mountable units in the rack or enclosure. These can be server systems, storage systems, I/O systems, networking systems, or "integrated" systems of these or other types of rack-mountable units.

#### 3.1.15

## hand-held equipment

functional unit, generally small and lightweight, intended to be supported in one's hand(s) during operation



#### 3.1.16

## standard test table

rigid table having a top surface of at least 0,5 m<sup>2</sup> and length of the top plane not less than 700 mm

NOTE The design for the standard test table is shown in A.1.

#### 3.2 Acoustical definitions

#### 3.2.1

#### emission

#### noise emission

airborne sound radiated by a well-defined noise source (e.g. the equipment under test)

NOTE Noise emission descriptors can be incorporated into a product declaration and/or product specification. The basic noise emission descriptors are the sound power level of the source itself and the emission sound pressure levels at an operator position (work station) and/or at bystander positions (if no operator position is defined) in the vicinity of the source.

## 3.2.2

sound pressure

p

difference between instantaneous total pressure and static pressure

NOTE 1 Sound pressure is expressed in pascals.

NOTE 2 The symbol p for instantaneous sound pressure, is often used without modification to represent a root-mean-square (RMS) sound pressure.

NOTE 3 See ISO 80000-8:2007<sup>[10]</sup>, 9.2.

#### 3.2.3

sound pressure level,

 $L_p$ 

ten times the logarithm to the base 10 of the ratio of the square of the sound pressure, p, to the square of a reference value,  $p_0$ 

$$L_p = 10 \lg \frac{p^2}{p_0^2}$$

NOTE 1 Sound pressure level,  $L_p$ , is expressed in decibels with a reference value,  $p_0$ , of 20  $\mu$ Pa (20 × 10<sup>-6</sup> Pa).

NOTE 2 This definition is technically in accordance with ISO 80000-8:2007<sup>[10]</sup>, 8.22.

[ISO/TR 25417:2007<sup>[11]</sup>, 2.2, modified — NOTES to entry were removed.]

## 3.2.4

time-averaged sound pressure level

 $L_{p,T}$ 

ten times the logarithm to the base 10 of the ratio of the time average of the square of the sound pressure, p, during a stated time interval of duration, T (starting at  $t_1$  and ending at  $t_2$ ), to the square of a reference value,  $p_0$ , expressed in decibels

$$L_{p,T} = 10 \lg \left[ \frac{1}{T} \int_{t_1}^{t_2} \frac{p^2(t)}{p_0^2} dt \right]$$

where the reference value,  $p_0$ , is 20  $\mu$ Pa

NOTE 1 Because of practical limitations of the measuring instruments,  $p^2$  is always understood to denote the square of a frequency-weighted and frequency-band-limited sound pressure. If a specific frequency weighting as specified in



IEC 61672-1 and/or specific frequency bands are applied, this should be indicated by appropriate subscripts; e.g.  $L_{p,A,10}$  s denotes the A-weighted time-averaged sound pressure level over 10 s.

NOTE 2  $L_{p,T}$  can be interpreted as the sound pressure level of a stable and permanent noise that will have the same average energy as the noise under study.

#### 3.2.5

emission sound pressure level

 $L_p$ 

sound pressure level at a specified position near a machine, when the machine is in operation under specified operating and mounting conditions on a reflecting plane surface, but excluding the effects of background noise as well as the effect of reflections other than those from the plane or planes permitted for the purpose of the test

- NOTE 1 The emission sound pressure level is expressed in decibels with a reference value,  $p_0$ , of 20  $\mu$ Pa (20 × 10<sup>-6</sup> Pa).
- NOTE 2 Clause 8 specifies the method for determination of emission sound pressure level.

[SOURCE: ISO 11205:2003<sup>[6]</sup>, 3.6, modified — NOTE 1 to entry was elaborated and NOTE 2 to entry was added.]

#### 3.2.6

time-averaged emission sound pressure level

 $L_{nea7}$ 

emission sound pressure level of a continuous steady sound that, within a measurement time interval, T, has the same mean-square sound pressure as a sound under consideration which varies with time

$$L_{peqT} = 10 \lg \int_0^T \frac{p^2(t)}{p_0^2} dt$$

- NOTE 1 The time-averaged emission sound pressure level is expressed in decibels with a reference value,  $p_0$ , of 20  $\mu$ Pa (20 × 10<sup>-6</sup> Pa).
- NOTE 2 The emission sound pressure level is determined at the specified position(s) required by the noise test code (i.e. this Standard, for specific families of ITT equipment).
- NOTE 3 Clause 8 of this Standard specifies the method for the determination of time-averaged A-weighted emission sound pressure level,  $L_{pA}$ , for ITT equipment defined in 3.1.3.
- NOTE 4 In general, the subscripts "eq" and "T" are omitted since time-averaged emission sound pressure levels are necessarily determined over a certain measurement time interval.

#### 3.2.7

C-weighted peak emission sound pressure level

 $L_{p}$ Cpeak

highest instantaneous value of the C-weighted emission sound pressure level determined over an operational cycle

NOTE The C-weighted peak sound pressure level is expressed in decibels with a reference value,  $p_0$ , of 20  $\mu$ Pa (20 × 10<sup>-6</sup> Pa).

#### 3.2.8

sound power

D

through a surface, product of the sound pressure, p, and the component of the particle velocity,  $u_n$ , at a point on the surface in the direction normal to the surface, integrated over that surface

- NOTE 1 Sound power is expressed in watts.
- NOTE 2 The symbol, P, is often used without modification for the mean value (over time) of the sound power.



NOTE 3 The quantity relates to the rate per unit time at which airborne sound energy is radiated by a source.

[SOURCE: ISO/TR 25417:2007[11], 2.8]

#### 3.2.9

sound power level

 $L_{W}$ 

ten times the logarithm to the base 10 of the ratio of the sound power, P, radiated by the sound source under test to the reference value,  $P_0$ 

$$L_W = 10 \lg \frac{P}{P_0}$$

NOTE 1 Sound power level  $L_W$  is expressed in decibels with a reference value of 1 pW (10<sup>-12</sup> W).

NOTE 2 Clauses 6 and 7 of this standard specify the method for the determination of the A-weighted sound power level,  $L_{WA}$ , for ITT equipment defined in 3.1.3.

[SOURCE: ISO/TR 25417:2007<sup>[11]</sup>, 2.9, modified — NOTE 2 to entry was added.]

#### 3.2.10

## reference sound source

device which is intended for use as a stable source of sound, which has a known, broad-band sound power spectrum determined in full conformance with ISO 6926 over the frequency range of interest.

## 3.2.11

## frequency range of interest

range of one-third-octave bands with centre frequencies from 100 Hz to 10 000 Hz inclusive

NOTE For equipment which emits discrete tone(s) in the 16 kHz octave band, the procedures specified in ECMA-108 are used; see Table 4.

#### 3.2.12

## noise immission at a work station

any noise that arrives, whether or not a worker is present, over a specific time period T, at a measuring point (work station) in the actual situation; i.e. noise coming from the machine, noise coming from the other sound sources and noise reflected by the ceiling, the walls and any fittings

[SOURCE: ISO 11690-1:1996 $^{[7]}$ , 3.3.1, modified — NOTE 1 to entry and the reference to Figure 1b) were deleted.]

## 3.2.13

## prominent discrete tone

a discrete tone is one of many causes of tonality, Annex D describes two methods to evaluate whether prominent discrete tones are contained in a measurement.

## 3.2.14

## prominent tonality

tonality arises from discrete tones, elevated or sloped noise spectra, and conjunctions of these phenomena. Annex G describes a psychoacoustic method to evaluate the prominence of these sources of tonality (including discrete tones) based on the hearing model in Annex F.



## 3.3 Definitions related to uncertainty

#### 3.3.1

## standard deviation of repeatability

 $\sigma_{\rm r}$ 

standard deviation of noise emission values obtained under repeatability conditions, that is the repeated application of the same noise emission measurement method on the same noise source within a short interval of time under the same conditions (same laboratory, same operator, same apparatus)

[SOURCE: ISO 7574-1:1985<sup>[2]</sup>, 3.16]

#### 3.3.2

## standard deviation of reproducibility

 $\sigma_{R0}$ 

standard deviation of noise emission values obtained under reproducibility conditions, that is the repeated application of the same noise emission measurement method on the same noise source at different times and under different conditions (different laboratory, different operator, different apparatus)

NOTE 1 The standard deviation of reproducibility, therefore, includes the standard deviation of repeatability (see 3.3.1).

NOTE 2 An estimate of  $\sigma_{R0}$  to be given in the measurement test code for the family of machines should preferably be derived from an interlaboratory test. In the absence of such a test,  $\sigma_{R0}$  may be agreed upon provisionally.

[SOURCE: ISO 7574-1:1985<sup>[2]</sup>, 3.17, modified — The last part of the definition was moved to a new NOTE 1 to entry and NOTE 1 to entry was renumbered as NOTE 2 to entry.]

#### 3.3.3

#### round robin testing

testing of identical materials at different test facilities for the comparison of results

[SOURCE: ISO 14624-3:2005<sup>[34]</sup>, 3.7]

#### 3.3.4

## coverage factor

K

numerical factor used as a multiplier of the combined standard uncertainty in order to obtain an expanded uncertainty

NOTE A coverage factor is typically in the range from 2 to 3.

[SOURCE: ISO/IEC Guide 98-3:2008<sup>[13]</sup>]

## 4 Conformity requirements

Measurements are in conformity with this Standard if they meet the following requirements:

- a) the measurement procedures, the installation and the operating conditions specified by this Standard shall be taken fully into account.
- b) for the determination of sound power levels, one (and only one) of the methods specified in Clause 6 or Clause 7 is shall be used.
- c) for the determination of emission sound pressure level at the operator or bystander positions, the method specified in Clause 8 shall be used.



## 5 Installation and operating conditions

## 5.1 Equipment installation

## 5.1.1 General

The equipment shall be installed in accordance with its intended use. Requirements are given in this clause for general types of equipment. Specific installation conditions for many different categories of ITT equipment are specified in Annex C, and these shall be followed insofar as they represent the intended use of the equipment. If the normal installation associated with intended use is unknown or ambiguous or if several possibilities exist, a representative condition shall be selected for the measurements and reported.

Care shall be taken to ensure that any electrical conduits, piping, air ducts or other auxiliary equipment connected to the equipment being tested do not radiate significant amounts of sound energy into the test room. If practicable, all auxiliary equipment necessary for the operation of the equipment shall be located outside the test room and the test room shall be free from all objects which can interfere with the measurements.

NOTE If the equipment is mounted near one or more reflecting planes, the sound power radiated by the equipment can depend upon its position and orientation. It is possible that the determination of the radiated sound power is of interest either for one particular equipment position and orientation or from the average value for several positions and orientations.

## 5.1.2 Floor-standing equipment

## 5.1.2.1 Requirements for reverberation test rooms

Floor-standing equipment (see 3.1.9) shall be located at least 1,5 m from any wall of the room and no major surfaces shall be parallel to a wall of the reverberation test room.

## 5.1.2.2 Requirements for hemi-anechoic rooms

Floor-standing equipment (see 3.1.9) shall be installed on the reflecting (hard) floor at a sufficient distance (more than 2 m, if possible) from the walls, unless otherwise specified in Annex C.

The equipment shall be installed in a way which allows access to all sides except the reflecting plane(s). The dimensions of the reflecting plane(s) shall extend beyond the test object by at least the measurement distance. Information on reflection is given in 7.3.1.1, NOTE 1. The plane(s) shall not contribute to the sound radiation due to their own vibrations.

## 5.1.2.3 Common requirements

If the equipment being tested consists of several frames bolted together in an installation or is too large for testing purposes, the frames may be measured separately. In such circumstances, additional covers can be required for the frames during the acoustical evaluation. These additional covers shall be acoustically comparable with the other covers on the equipment. If a unit is mechanically or acoustically coupled to another unit so that the noise emission levels of one are significantly influenced by the other, the equipment being tested shall, where practicable, include all units coupled together in this way.

Floor-standing equipment which is to be installed only in front of a wall shall be placed on a hard floor in front of a hard wall (information on reflection are given in 7.3.1.1, NOTE 1). The distance from the wall shall be in accordance with the manufacturer's instructions or as specified in Annex C. If such information is not available there, the distance shall be 0,1 m.



## 5.1.3 Table-top equipment

## 5.1.3.1 Requirements for reverberation test rooms

Table-top equipment (see 3.1.10) shall be placed on the floor at least 1,5 m from any wall of the room unless a table or stand is required for operation in accordance with Annex C (e.g. printers which take paper from or stack paper on the floor). Such equipment shall be placed in the centre of the top plane of the standard test table in accordance with A.1.

## 5.1.3.2 Requirements for hemi-anechoic rooms

Table-top equipment (see 3.1.10) shall be placed on the floor, unless a table or stand is required for operation in accordance with Annex C (e.g. printers which take paper from or stack paper on the floor). Such equipment shall be placed in the centre of the top plane of the standard test table in accordance with A.1. In any case the measurement surface defined in 7.6 terminates on the floor.

## 5.1.4 Wall-mounted equipment

Wall-mounted equipment (see 3.1.11) shall be affixed to a wall of the reverberation test room at least 1,5 m from any other reflecting surface, unless otherwise specified. Alternatively, if operation permits, the equipment may be laid with its mounting surface on the floor at least 1,5 m (more than 2 m, if possible, in hemi-anechoic rooms) from any wall of the room.

If the equipment is usually installed by being recessed into a wall or other structure, a representative structure shall be used for mounting during the measurements and described in the test report.

## 5.1.5 Rack-mounted equipment

Rack-mounted equipment includes both individual rack-mountable units (see 3.1.13) and rack-enclosed systems (see 3.1.14). Rack-mountable units shall either be tested outside of the rack or installed in a rack enclosure in accordance with the requirements of C.18.2. Rack-enclosed systems shall be tested either as floor-standing equipment (see 5.1.2) or as table-top equipment (see 5.1.3) in accordance with the type and size of system. The specific installation and operation requirements of C.18.2 and C.18.3, respectively, shall be followed.

For rack-enclosed systems that are available in more than one configuration of rack-mountable units, the particular configuration to be measured is usually governed by the purposes of the test and is thus not specified in this Standard (see C.18.1 for more information).

## 5.1.6 Hand-held equipment

Hand-held equipment (see 3.1.15) shall be supported 0,25 m  $\pm$  0,03 m above the reflecting plane by a vibration-isolating stand or fixture, or by appropriate vibration-isolating elements. If a hemispherical measurement surface is used with any radius less than 1 m (see B.1), the hand-held equipment support height shall be reduced to 0,125 m  $\pm$  0,015 m. The method of supporting the hand-held equipment shall not interfere with the propagation of airborne sound from the equipment or generate any additional sound radiation.

## 5.1.7 Sub-assemblies

A sub-assembly (see 3.1.12) shall be supported 0,25 m  $\pm$  0,03 m above the reflecting plane by a vibration-isolating stand or fixture, or by appropriate vibration-isolating elements. If a hemispherical measurement surface is used with any radius less than 1 m (see B.1), the sub-assembly support height shall be reduced to 0,125 m  $\pm$  0,015 m. The method of supporting the sub-assembly shall not interfere with the propagation of airborne sound from the sub-assembly or generate any additional sound radiation.

If the above-specified support height is not adequate to allow the manufacturer's recommended air flow at the sub-assembly's air inlet, the height may be adjusted accordingly but shall not exceed 0,5 m. The new height shall be documented in the test report.



## 5.2 Input voltage and frequency

The equipment shall be operated at its nominal rated voltage and the rated power line frequency.

Phase-to-phase voltage variations shall not exceed 5 %.

## 5.3 Equipment operation

During the acoustical measurements the equipment shall be operated in a manner typical of normal use.

Annex C specifies such conditions for many categories of equipment and shall be followed. However, if the specified conditions are clearly contrary to the objective of providing uniform conditions closely corresponding to the intended use of the product, then an additional mode or modes closely related to the intended use shall be defined, tested and described in the test report. Any subsequent declaration shall either:

- declare both values, indicating that one is based on Annex C and that the other is declared by the manufacture to be typical use for intended application; or
- declare only the latter, indicating that it is not based on Annex C but is declared by the manufacturer to be typical use for intended application.

When there are multiple operating modes specified in Annex C, at a minimum, the most typical operating mode shall be chosen for the measurement. This mode shall be clearly described in the test report.

The equipment shall be operated for a sufficient period of time before proceeding with the acoustical test to allow temperature and other pertinent conditions to stabilize.

The noise shall be measured with the equipment in both the idle and operating modes. If the equipment is designed to perform different functions, such as manual typing and automatic printing of stored information, or for printing in different print qualities, unless otherwise specified in Annex C, the noise of each individual mode shall be determined and recorded. For equipment which, in normal functional operation, performs several operating modes, such as document insertion, reading, encoding, printing and document eject, and for which a typical operation cycle has not been defined in Annex C, such a typical cycle shall be defined for the measurements. This mode shall be clearly described in the test report.

For rack-mounted equipment in which the operation of several functional units is possible, the units intended to operate together shall do so during the test; all other units shall be in idle mode. In the absence of operational specifications provided by Annex C or by the manufacturer, an operating mode that represents the most typical usage shall be defined and tested. This mode shall be clearly described in the test report.

Some equipment does not operate continuously because of its mechanical design or its mode of operation under program control. Long periods can occur during which the equipment is idle. The operating mode measurements shall not include these idle periods. If it is not possible to operate the equipment continuously during the acoustical evaluation, the time interval during which measurements have to be made shall be defined and clearly described in the test plan, equipment specifications or other documentation.

Some equipment has operational cycles that are too short to allow reliable determination of the noise emissions. In such cases, a typical cycle shall be repeated several times.

If the equipment being tested produces attention signals, such as tones or bells, such intermittent sound shall not be included in an operating mode. During the acoustical evaluation in the operating mode(s), such attention signals shall be inoperative or, if this is not possible, they shall be set to a minimum.

NOTE For certain applications, such signals as well as the maximum response of feedback signals of keyboards can be of interest. Such measurements can be made, but they are not part of the methods specified in this Standard.



## 6 Method for determination of sound power levels of equipment in reverberation test rooms

## 6.1 General

The method specified in this clause provides a comparison procedure for determination of the sound power levels of ITT equipment in a reverberation test room, in accordance with the comparison method specified in ISO 3741. It applies to equipment which radiates broad-band noise, narrow-band noise, noise which contains discrete frequency components or impulsive noise.

It is strongly recommended that the room be qualified for discrete-frequency components in accordance with the relevant procedure specified in ISO 3741. This avoids the need to determine the number of microphone positions and equipment locations each time equipment is measured.

## 6.2 Measurement uncertainty

Measurements carried out in accordance with this method yield standard deviations of reproducibility for the frequency range of interest of this Standard which are equal to, or less than, those given in Table 1.

Table 1 — Typical upper bound values of the standard deviation of reproducibility in determining sound power levels in a reverberation test room in accordance with Clause 6

Octave band centre frequencies	One-third-octave band centre frequencies	Standard deviation of reproducibility, $\sigma_{R^0}$
Hz	Hz	dB
125	100 to 160	3,0
250	200 to 315	2,0
500 to 4 000	400 to 5 000	1,5
8 000	6 300 to 10 000	3,0

NOTE 1 For most ITT equipment, the A-weighted sound power level is determined by the sound power levels in the 250 Hz to 4 000 Hz octave bands. The A-weighted sound power level is determined with a standard deviation of approximately 1,5 dB. A larger standard deviation can result when the sound power levels in other bands determine the A-weighted sound power level.

NOTE 2 The standard deviations of reproducibility,  $\sigma_{R0}$  (see 3.3.2), given in Table 1, reflect the cumulative effects of all causes of measurement uncertainty, including variations from laboratory to laboratory, but excluding variations in the sound power level from equipment to equipment or from test to test which can be caused, for example, by changes in the installation or operating conditions of the equipment. In quantitative sense, the repeatability,  $\sigma_r$  (see 3.3.1), of the test results for the same piece of equipment and the same measurement conditions can be considerably better (i.e. smaller standard deviations) than indicated by the values given in Table 1.

NOTE 3 If the method specified in this clause is used to compare the sound power levels of similar equipment that are omnidirectional and radiate broad-band noise, this comparison yields a standard deviation which is less than that given in Table 1, provided that the measurements are carried out in the same environment.

#### 6.3 Test environment

## 6.3.1 General

Guidelines specified in ISO 3741 for the design of the reverberation test room, as applicable, shall be used. Criteria for room absorption and the procedure for room qualifications, specified in ISO 3741 shall be used.

ISO 3741 shall be followed with regard to the following:



- a) test room volume;
- b) level of background noise.

## 6.3.2 Meteorological conditions

The requirements of ISO 3741 shall be followed.

The following conditions are recommended:

- a) ambient pressure: 86 kPa to 106 kPa;
- b) ambient temperature: within the range defined by the manufacturer for the equipment, if a range is defined; if no range is so defined by the manufacturer, the recommended range is 15 °C to 30 °C;
- c) relative humidity: within the range defined by the manufacturer for the equipment, if a range is defined; for processing of paper and card media only, if no range is so defined by the manufacturer, the recommended range is 40 % to 70 %.

For equipment whose noise emissions vary with ambient temperature in a prescribed manner (e.g. by varying the speeds of air-moving devices), the ambient temperature shall be 23 °C  $\pm$  2 °C for at least one measurement. Supplemental measurements at temperatures relevant to the equipment's expected use may be performed by controlling the ambient temperature or by simulating the equipment's operation. If there is spatial variation in the ambient temperature, the temperature shall be measured near where the equipment is most sensitive to the ambient temperature, such as an airflow inlet.

For equipment whose noise emissions vary with altitude (i.e. ambient pressure) in a prescribed manner (e.g. by varying the speeds of air-moving devices), either the altitude of the test room shall be less than or equal to 500 m above sea level, or the equipment shall be tested under conditions simulating its operation at an altitude less than or equal to 500 m above sea level. Supplemental measurements at different altitudes relevant to the equipment's expected use may be performed at such altitudes or by simulating the equipment's operation.

NOTE 1 This variation of speed of air-moving devices does not refer to the changing speed that is already accounted for in the correction for ambient pressure described in 6.10.1, NOTE.

NOTE 2 The altitude is identified as a determiner of some varying noise emissions for simplicity and ease of communication. However, while it is the primary factor, it is not the only factor in determining the ambient pressure, which is the root cause of such varying noise emissions. It is the ambient pressure that has a direct effect on the acoustical noise emission. Both the altitude and the ambient temperature are necessary to calculate the more precise ambient pressure.

## 6.4 Instrumentation

## 6.4.1 General

The requirements of this subclause (6.4), as well as the instrumentation requirements of ISO 3741, shall be followed.

Digital integration is the preferred method of averaging.

## 6.4.2 The microphone and its associated cable

The instrument system, including the microphone and its associated cable, shall meet the requirements of ISO 3741. If the microphone is moved, care shall be exercised to avoid introducing acoustical or electrical noise (e.g. from gears, flexing cables, or sliding contacts) that could interfere with the measurements.

## 6.4.3 Frequency response of the instrumentation system

The requirements of ISO 3741 shall be followed.



#### 6.4.4 Reference sound source

The reference sound source shall meet the requirements specified in ISO 6926 over the frequency range of interest.

#### 6.4.5 Filter characteristics

The requirements for an instrument specified in accordance with IEC 61260, class 1 shall be followed.

## 6.4.6 Meteorological instrumentation

The requirements of ISO 3741 shall be followed except for equipment whose noise emissions vary with ambient temperature in a prescribed manner, in which case the temperature variation limits shall be  $\pm$  1 °C.

#### 6.4.7 Calibration

The microphones shall be calibrated for random incidence as specified in IEC 61183.

Before and after each series of measurements, a sound calibrator meeting the requirements of IEC 60942, class 1 shall be applied to each microphone to verify the calibration of the entire measuring system at one or more frequencies within the frequency range of interest. Without any further adjustment, the difference between the readings made before and after each series of measurements shall be less than or equal to 0,5 dB. If this value is exceeded, the results of the series of measurements shall be discarded.

NOTE A "series" of measurements does not require that this verification be conducted "daily". Other methods for checking the calibration of the measurement system to ensure this requirement will be met can be available. For example, see JBMIA-TR-28<sup>[18]</sup>.

The calibration of the sound calibrator, the compliance of the instrumentation system with the requirements of IEC 61672-1, the compliance of the filter set with the requirements of IEC 61260-1 and, if used, the compliance of the reference sound source with the requirements of ISO 6926 shall be verified at intervals in a laboratory making calibrations traceable to appropriate standards preferably by meeting the requirements of ISO/IEC 17025<sup>[12]</sup>. The sound calibrator should be calibrated at intervals not exceeding 1 year, the reference sound source should be calibrated at intervals not exceeding 2 years, the compliance of the instrumentation system with the requirements of IEC 61672-1 should be verified at intervals not exceeding 2 years, and the compliance of the filter set with the requirements of IEC 61260-1 should be verified at intervals not exceeding 2 years.

## 6.5 Installation and operation of equipment: General requirements

See Clause 5.

## 6.6 Microphone positions and source locations

## 6.6.1 General

The major cause of uncertainty in determining sound power level in a reverberation test room is the spatial irregularity of the sound field. The extent of this irregularity and, hence, the effort required to determine the time-averaged sound pressure level accurately are greater for discrete-frequency sound than for broad-band sound.

It is strongly recommended that the room be qualified for the measurement of discrete-frequency components in accordance with the relevant procedures of ISO 3741. This avoids the need to determine the number of microphone positions and equipment locations each time equipment is measured.

If the room has not been qualified for the measurement of discrete-frequency components, the procedures specified in ISO 3741 shall be used to determine the minimum number of microphone positions and to evaluate the need for additional noise source locations prior to each measurement. The results of these procedures depend on the presence or absence of significant discrete-frequency components or narrow bands of noise in



the sound emitted by the source. When these are present, the number of microphone positions and equipment locations may be large.

## 6.6.2 Number of microphone positions, reference sound source locations and equipment locations

The requirements of ISO 3741shall be followed.

## 6.6.3 Microphone arrangement

The requirements of ISO 3741shall be followed.

## 6.7 Measurement of sound pressure level

#### 6.7.1 General

The requirements of ISO 3741 shall be followed, as applicable.

NOTE Depending on the purposes of the test, it may be the case that one or more repeated measurements are taken for either the sound pressure levels of the reference sound source (see 6.8) or the source under test (see 6.9), or both. Provided that each of the measurements in the repeated set represent identical conditions for the reference sound source or the source under test, and that they are each valid measurements in accordance with the requirements of this Standard, the arithmetic average of the measured sound pressure levels, in decibels, should be taken as the measurement result from this clause.

#### 6.7.2 Measurement time interval

The requirements below in addition to those of ISO 3741 shall be followed, as applicable.

For equipment which performs repetitive operation cycles (e.g. enveloping machines), the measurement time interval shall include at least three operation cycles. For equipment which performs a sequence of varying operation cycles, the measurement time interval shall include the total sequence. Annex C specifies additional requirements for many categories of equipment.

## 6.7.3 Corrections for background noise

The requirements of ISO 3741 shall be followed, as applicable.

NOTE When the background noise levels in the test room are extremely low and very controlled, it is possible that the environment satisfies the absolute and/or relative criteria for background noise in accordance with ISO 3741.

## 6.8 Measurement of the sound pressure level of the reference sound source

The requirements below in addition to those of ISO 3741 shall be followed.

For the purposes of determining the sound power level of the equipment by means of reverberation test rooms, this Standard uses exclusively the comparison method specified in ISO 3741. This method has the advantage that it is not necessary to measure the reverberation time of the test room. The comparison method requires the use of a reference sound source with characteristics and calibration in accordance with ISO 6926 and for which the sound power levels have been determined in full conformance with ISO 6926 over the frequency range of interest (see 3.2.12). The reference sound source shall be operated, as described in its calibration chart, in the presence of the equipment being tested and in the presence of the operator, if required to operate the equipment.

## 6.9 Calculation of the mean time-averaged band sound pressure levels

The requirements of ISO 3741 shall be followed.



## 6.10 Determination of sound power level

## 6.10.1 Calculation of band sound power levels

The sound power level, under reference meteorological conditions, of the equipment in each one-third-octave band within the frequency range of interest (see 3.2.11) is obtained by using the comparison method of ISO 3741.

NOTE 1 The procedures in ISO 3741 are used to determine the sound power level under reference meteorological conditions (ambient pressure 1,013  $25 \times 10^5$  Pa, temperature 23,0 °C, relative humidity 50 %).

For supplemental measurements of equipment that has varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, the sound power level for each one-third-octave band within the frequency range of interest shall be determined under meteorological conditions representing the measurement by using the approach for different meteorological conditions described in ISO 3745. If the ambient pressure cannot be measured, it may be computed using a barometric formula given in Formula (1)<sup>[78]</sup>:

$$P_a = P_s e^{-Mgh_a/R_gT} (1)$$

where

- $P_a$  is the ambient pressure, in Pa, of the measurement at altitude  $h_a$  and ambient temperature T;
- $P_s$  is the ambient pressure at sea level, 1,013 25 × 10<sup>5</sup> Pa;
- g is the standard gravity constant, 9,806 65 m/s<sup>2</sup>;
- M is the molar mass of air, 0,028 964 4 kg/mol;
- $h_a$  is the altitude above sea level of the measurement, in metres;
- $R_g$  is the universal gas constant, 8,314 46 J/(mol·K);
- T is the ambient temperature of the measurement, in kelvin.

NOTE 2 The approach in ISO 3745 is identified because ISO 3741 does not explicitly state an approach for calculating the sound power level under different meteorological conditions. Though it is not provided directly, the same approach used in ISO 3745 can be deduced based on the radiation impedance correction,  $C_2$ , in ISO 3741.

The sound power level in the k-th octave band,  $L_{Woct, k}$  in decibels, if needed, shall be based on one-third-octave band data, and calculated from:

$$L_{W \ oct,k} = 10 \lg \sum_{j=3k-2}^{3k} 10^{0,1L_{W1/3,j}}$$
 (2)

where

- k is an identification number of octave band within the frequency range of interest (see Table 2);
- $L_{W^{7/3},i}$  is the sound power level in the *j*-th one-third-octave band, in decibels (see Table 3);
- j is an identification number lying within the range of (3k 2) and 3k, which identifies the three one third-octave bands which make up the k-th octave band.



## 6.10.2 Calculation of A-weighted sound power level

The A-weighted sound power level,  $L_{WA}$  in decibels shall be based on the frequency range of interest, and calculated as per Formula (3):

$$L_{WA} = 10 \lg \sum_{j=1}^{21} 10^{0,1(L_{W1/3,j} + A_j)}$$
(3)

where

 $L_{W^{1/3},j}$  is the sound power level, in decibels, in the *j*-th one-third-octave band;

- $A_i$  is the A-weighting value corresponding to the *j*-th one-third-octave band (see Table 3);
- *j* is an identification number of a one-third-octave band within the frequency range of interest (see Table 3).

NOTE Formulae (2) and (3), as well as Tables 2 and 3, are intended for common use for not only Clause 6, but also Clause 7.

Table 2 — Identification number, k for octave bands

k	Octave-band centre frequency	
	Hz	
1	125	
2	250	
3	500	
4	1 000	
5	2 000	
6	4 000	
7	8 000	



Table 3 — Values of A-weighting,  $A_j$ , for one-third-octave bands

j	One-third-octave-band centre frequency	A-weighting $A_j$
	Hz	dB
1	100	- 19,1
2	125	- 16,1
3	160	- 13,4
4	200	- 10,9
5	250	- 8,6
6	315	- 6,6
7	400	- 4,8
8	500	- 3,2
9	630	- 1,9
10	800	- 0,8
11	1 000	0,0
12	1 250	0,6
13	1 600	1,0
14	2 000	1,2
15	2 500	1,3
16	3 150	1,2
17	4 000	1,0
18	5 000	0,5
19	6 300	- 0,1
20	8 000	- 1,1
21	10 000	- 2,5

Some ITT equipment emits high-frequency noise in the 16 kHz octave band. Depending upon the nature of noise emissions, Table 4 shows how to handle each situation.

For the determination of A-weighted sound power levels from band levels, this Standard does not extend the frequency range of interest to include the 16 kHz octave band.



For equipment which emits discrete tone(s) in the 16 kHz octave band, each frequency and level of the tone(s) that is (are) within 10 dB of the highest tone level in the band shall be determined in accordance with the procedures specified in ECMA-108 (see Table 4). The derived levels are not frequency weighted.

**CAUTION** The 16 kHz octave band contribution is not included in the determination of the A-weighted level.

Table 4 — Type of noise and determination of sound power levels

Type of noise in the frequency range of the octave bands centred at		Sound power level to be determined
125 Hz to 8 kHz 16 kHz		
	No significant noise	A-weighted level (consisting of contribution from 125 Hz to 8 kHz octave bands) in accordance with this Standard
	Broad-band noise	A-weighted level (consisting of contribution from 125 Hz to 8 kHz octave bands) in accordance with this Standard and one-third-octave-band sound power levels in 16 kHz octave band in accordance with the procedure of ECMA-108
Broad-band or narrow-band noise <sup>a</sup>	Discrete tone	A-weighted level (consisting of contribution from 125 Hz to 8 kHz octave bands) in accordance with this Standard and the level and frequency of the discrete tone in accordance with ECMA-108
	Multiple tones	A-weighted level (consisting of contribution from 125 Hz to 8 kHz octave bands) in accordance with this Standard and the levels and frequencies of all tones in the 16 kHz octave band that are within 10 dB of the highest tone level in the band in accordance with ECMA-108
	Discrete tone	Level and frequency of the discrete tone in the 16 kHz octave band in accordance with ECMA-108
No significant noise <sup>b</sup>	Multiple tones	Levels and frequencies of all tones in the 16 kHz octave band that are within 10 dB of the highest tone level in the band in accordance with ECMA-108

For noise in 125 Hz to 8 kHz octave bands, sound power level in one-third-octave bands and in octave bands may also be reported.

## 7 Method for determination of sound power levels of equipment under essentially free-field conditions over a reflecting plane

## 7.1 General

The method specified in this clause provides a direct procedure for determination of the sound power levels of ITT equipment using essentially free-field conditions over a reflecting plane as specified in ISO 3744 or ISO 3745. It applies to equipment which radiates broad-band noise, narrow-band noise, noise which contains discrete frequency components or impulsive noise.

The measurement shall be carried out in an environment qualified in accordance with ISO 3744 or ISO 3745.

A significant noise contribution not within the 125 Hz to 8 kHz octave band lies outside the scope of this Standard; in that case, only ECMA-108 is applicable.



## 7.2 Measurement uncertainty

Measurements carried out in accordance with this method yield standard deviations of reproducibility for the frequency range of interest of this Standard which are less than or equal to those given in Table 5.

Table 5 — Typical upper bound values of the standard deviation of reproducibility in determining sound power levels in a free field over a reflecting plane in accordance with Clause 7

Octave band centre frequencies	One-third-octave band centre frequencies	Standard deviation of reproducibility, $\sigma_{R0}$
125	100 to 160	3,0
250 to 500	200 to 630	2,0
1 000 to 4 000	800 to 5 000	1,5
8 000	6 300 to 10 000	2,5

NOTE 1 For most ITT equipment, A-weighted sound power level is determined by the sound power levels in the 250 Hz to 4 000 Hz octave bands. The A-weighted sound power level is determined with a standard deviation of approximately 1,5 dB. A larger standard deviation can result when the sound power levels in other bands determine the A-weighted sound power level.

NOTE 2 The standard deviations of reproducibility,  $\sigma_{R0}$  (see 3.3.2), given in Table 5, reflect the cumulative effects of all causes of measurement uncertainty, including variations from laboratory to laboratory but excluding variations in the sound power level from equipment to equipment or from test to test which can be caused, for example, by changes in the installation or operating conditions of the equipment. In quantitative sense, the repeatability,  $\sigma_r$  (see 3.3.1), of the test results for the same piece of equipment and the same measurement conditions can be considerably better (i.e. smaller standard deviations) than the uncertainties given in Table 5 indicate.

NOTE 3 If the method specified in this clause is used to compare the sound power levels of similar equipment that are omnidirectional and radiate broad-band noise, this comparison yields a standard deviation which is less than that given in Table 5, provided that the measurements are carried out in the same environment.

## 7.3 Test environment

## 7.3.1 Essentially free field over a reflecting plane

#### 7.3.1.1 General

The test environment shall provide an essentially free field over a reflecting plane. Criteria for suitable test environments are defined in ISO 3744 and ISO 3745.

NOTE 1 A plane (floor, wall) is considered to be reflecting (hard) if its absorption coefficient  $\alpha$  is less than 0,06 over the frequency range of interest (e.g. concrete floor:  $\alpha < 0.01$ , plastered wall:  $\alpha \approx 0.04$ , tiled wall:  $\alpha \approx 0.01$ ).

NOTE 2 It is ideal for the test environment (an essentially free field over a reflecting plane, such as a hemi-anechoic room) to be qualified in accordance with the latest edition of ISO 3744 and/or ISO 3745 as applicable. In practice, however, in case of the existing test environment, it will take some years (so called, transition period) to complete the re-qualification testing according to applicable updated standards. Such a testing can be needed for test laboratories which meet the requirements of ISO/IEC 17025<sup>[12]</sup>.

#### 7.3.1.2 Qualification in accordance with ISO 3744

For test environments qualified in accordance with ISO 3744, the environmental correction,  $K_2$ , shall be equal to or less than 2 dB in each one-third octave band over the frequency range of interest.



The above requirement for  $K_2$  may not be achievable in all frequency bands, even if the test environment is suitable for determining A-weighted sound power levels. Therefore, if the A-weighted sound power level is to be determined from one-third-octave band levels, the following steps shall be followed to determine whether this quantity meets the environmental correction criteria of this Standard:

- a) the A-weighted sound power level is computed in accordance with the procedures in ISO 3744 using the data from every one-third-octave band within the frequency range of interest and corrected for  $K_2$  using the values determined from Annex A in ISO 3744 even when those values exceed  $K_2$  = 2,0 dB;
- b) the computation is repeated, but excluding those bands for which  $K_2$  exceeds 2 dB.

If the difference between these two levels is less than 0,5 dB, the A-weighted sound power level determined from the data for all bands can be considered as conforming to the test environmental correction criteria of this Standard.

## 7.3.1.3 Qualification in accordance with ISO 3745

For test environments qualified in accordance with ISO 3745, the environmental correction,  $K_2$  is assumed to be 0 dB in each one-third octave band over the frequency range of interest. The above requirement for qualification in accordance with ISO 3745 may not be achievable in all frequency bands, even if the test environment is suitable for determining A-weighted sound power levels. Therefore, if the A-weighted sound power level is to be determined from one-third-octave band levels, the following steps shall be followed to determine whether this quantity meets the environmental qualification criteria of this Standard:

- a) the A-weighted sound power level is computed in accordance with the procedures in ISO 3744 using the data from every one-third-octave band within the frequency range of interest for which the chamber qualifies in accordance with ISO 3745;
- b) the computation is repeated, but excluding those bands for which the chamber does not qualify in accordance with ISO 3745.

If the difference between these two levels is less than 0,5 dB, the A-weighted sound power level determined from the data for all bands can be considered as conforming to the test environmental qualification criteria of this Standard.

## 7.3.2 Meteorological conditions

The requirements of ISO 3744 as applicable shall be followed.

The following conditions are recommended:

- a) ambient pressure: 86 kPa to 106 kPa;
- b) ambient temperature: within the range defined by the manufacturer for the equipment, if a range is defined; if no range is so defined by the manufacturer, the recommended range is 15 °C to 30 °C;
- c) relative humidity: within the range defined by the manufacturer for the equipment, for processing of paper and card media only, if no range is so defined by the manufacturer, the recommended range is 40 % to 70 %.

For equipment whose noise emissions vary with ambient temperature in a prescribed manner (e.g. by varying the speeds of air-moving devices), the ambient temperature shall be 23 °C  $\pm$  2 °C for at least one measurement. Supplemental measurements at temperatures relevant to the equipment's expected use may be performed by controlling the ambient temperature or by simulating the equipment's operation. If there is spatial variation in the ambient temperature, the temperature shall be measured near where the equipment is most sensitive to the ambient temperature, such as an airflow inlet.

For equipment whose noise emissions vary with altitude (i.e. ambient pressure) in a prescribed manner (e.g. by varying the speeds of air-moving devices), either the altitude of the test room shall be less than or equal to 500 m above sea level, or the equipment shall be tested under conditions simulating its operation at an altitude less



than or equal to 500 m above sea level. Supplemental measurements at different altitudes relevant to the equipment's expected use may be performed at such altitudes or by simulating the equipment's operation.

NOTE 1 This variation of speed of air-moving devices does not refer to the changing speed that is already accounted for in the correction for ambient pressure specified in 7.9.1.

NOTE 2 The altitude is identified as a determiner of some varying noise emissions for simplicity and ease of communication. However, while it is the primary factor, it is not the only factor in determining the ambient pressure, which is the root cause of such varying noise emissions. It is the ambient pressure that has a direct effect on the acoustical noise emission. Both the altitude and the ambient temperature are necessary to calculate the more precise ambient pressure.

## 7.4 Instrumentation

## 7.4.1 General

The requirements of 7.4, as well as the instrumentation requirements of ISO 3744 or ISO 3745, shall be followed.

Digital integration is the preferred method of averaging.

## 7.4.2 The microphone and its associated cable

The instrument system, including the microphone and its associated cable, shall meet the requirements of ISO 3744 or ISO 3745, as applicable. If the microphone is moved, care shall be exercised to avoid introducing acoustical or electrical noise (e.g. from wind, gears, flexing cables or sliding contacts) that could interfere with the measurements.

## 7.4.3 Frequency response of the instrumentation system

The requirements of ISO 3744 or ISO 3745, as applicable, shall be followed.

## 7.4.4 Reference sound source

The reference sound source shall meet the requirements specified in ISO 6926 over the frequency range of interest.

## 7.4.5 Filter characteristics

The requirements for an instrument specified in accordance with IEC 61260-1, class 1 shall be followed.

## 7.4.6 Meteorological instrumentation

The requirements of ISO 3745 shall be followed.

## 7.4.7 Calibration

Before and after each series of measurements, a sound calibrator meeting the requirements of IEC 60942, class 1 shall be applied to each microphone to verify the calibration of the entire measuring system at one or more frequencies within the frequency range of interest. Without any adjustment, the difference between the readings made before and after each series of measurements shall be less than or equal to 0,5 dB. If this value is exceeded, the results of the series of measurements shall be discarded.

NOTE A "series" of measurements does not require that this verification be conducted "daily". Other methods for checking the calibration of the measurement system to ensure this requirement will be met can be available. For example, see JBMIA-TR-28<sup>[18]</sup>.

The calibration of the sound calibrator, the compliance of the instrumentation system with the requirements of IEC 61672-1, the compliance of the filter set with the requirements of IEC 61260-1 and, if used, the compliance



of the reference sound source with the requirements of ISO 6926 shall be verified at intervals in a laboratory making calibrations traceable to appropriate standards preferably by meeting the requirements of ISO/IEC 17025 [12]. The sound calibrator should be calibrated at intervals not exceeding 1 year, the reference sound source should be calibrated at intervals not exceeding 2 years, the compliance of the instrumentation system with the requirements of IEC 61672-1 should be verified at intervals not exceeding 2 years, and the compliance of the filter set with the requirements of IEC 61260-1 should be verified at intervals not exceeding 2 years.

### 7.5 Installation and operation of equipment: General requirements

See Clause 5.

### 7.6 Measurement surface and microphone positions

### 7.6.1 General

Except as specified in Annex B, the requirements of ISO 3744 or ISO 3745 shall be followed as applicable. For most ITT equipment, the preferred measurement surface is hemispherical. If a hemispherical surface is used, then one of the following shall be applied:

- a) B.1;
- b) relevant annex of ISO 3745; or
- c) relevant annex of ISO 3744 (but, with a minimum of five different microphone heights).

However, for equipment with tall aspect ratios, such as equipment racks, frames, or cabinets, the cylindrical measurement surface specified in B.2 may be preferred. For sources which have a relatively large footprint, the parallelepiped measurement surface can be more practical than a hemispherical measurement surface. The conditions of Clause 5 above shall however be followed. The number and location of the microphone positions shall be as specified in ISO 3744 or ISO 3745, as applicable, except as specified in Annex B of this Standard.

In some cases, e.g. when small equipment emits very low-level noise, it can be helpful to use a hemispherical measurement surface with a smaller radius. For such situations, B.1 defines measurement conditions with a hemisphere radius less than 1 m, but at least 0,5 m.

In order to facilitate the location of the microphone positions, a hypothetical reference surface is defined. This reference surface, or "reference box", is the smallest possible rectangular box (i.e. rectangular parallelepiped) that just encloses the equipment and terminates on the reflecting plane(s). It has length  $l_1$ , width  $l_2$  and height  $l_3$ . Elements protruding from the equipment being tested which are unlikely to contribute to the noise emission may be disregarded. The microphone positions lie on the measurement surface, a hypothetical surface of area S, which envelops the equipment as well as the reference box and terminates on the reflecting plane.

The location of the equipment being tested, the measurement surface and the microphone positions are defined by a co-ordinate system with horizontal axes x and y in the ground plane parallel to the length and width of the reference box and with the vertical axis z passing through the geometric centre of the reference box. The x axis points towards the front of the equipment. The position of the origin for the coordinates of the microphone positions is:

- a) for floor-standing equipment: on the floor in the centre of the plane of the reference box which is coplanar with the room floor:
- b) for table-top equipment on a table or on the floor: as for a);
- c) for wall-mounted equipment: in the centre of that plane of the reference box which is coplanar with the mounting surface;
- d) for rack-mounted equipment: as for a);



- e) for hand-held equipment: as for a);
- f) for sub-assemblies: as for a).

NOTE For fixed microphone arrays, either a single microphone can be moved from one position to the next sequentially or a number of fixed microphones can be used and their outputs sampled sequentially or simultaneously. Alternatively, a continuous microphone traverse can be used as specified in ISO 3744.

Near air exhausts, the microphone position shall be selected in such a way that the microphone is not exposed to the air stream, otherwise a windscreen shall be used.

The microphones shall be oriented in such a way that the angle of sound incidence is the same as the angle for which the microphone has the most uniform frequency response as specified by the manufacturer. For most practical cases this will be an orientation towards the origin of the co-ordinate system on the floor.

### 7.6.2 Microphone positions on the measurement surface

Except as stated in the next paragraph, microphone positions shall meet the requirements of ISO 3744 or ISO 3745, as applicable, including the requirements for additional microphone positions and for the reduction in the number of microphone positions, where applicable.

If large equipment is to be measured in small rooms providing free-field conditions over a reflecting plane in accordance with ISO 3745, it can be easier to place the equipment not in the centre of the room but closer to a corner and to arrange the microphone positions in the free field of the room. The equipment should be turned around so that noise radiation from the different sides of the machine can be determined sequentially.

## 7.7 Measurement of sound pressure levels

### 7.7.1 General

Measurements of the sound pressure levels shall be carried out in accordance with ISO 3744 or ISO 3745 and with the following requirements.

Measurements of the sound pressure level shall be carried out at the microphone positions specified in 7.6 with A-weighting and/or for each frequency band within the frequency range of interest, if required. Record:

- the A-weighted sound pressure levels and/or the one-third-octave band sound pressure levels, for the specified modes of operation of the equipment;
- the A-weighted sound pressure levels and/or the one-third-octave band sound pressure levels of the background noise (including noise from support equipment).

When using a sound level meter, the person reading the meter shall not disturb the sound field at the microphone.

NOTE Depending on the purposes of the test, it may be the case that one or more repeated measurements are taken for the source under test. Provided that each of the measurements in the repeated set represent identical conditions for the source under test, and that they are each valid measurements in accordance with the requirements of this Standard, the arithmetic average of the measured sound pressure levels, in decibels, should be taken as the measurement result from 7.7.

### 7.7.2 Measurement time interval

The requirements below, in addition to those of ISO 3744, shall be followed, as applicable.

For equipment which performs repetitive operational cycles (e.g. enveloping machines), the measurement time interval shall include at least three operational cycles. For equipment which performs a sequence of varying operational cycles, the measurement time interval shall include the total sequence. Annex C specifies additional requirements for many types of equipment.



### 7.7.3 Corrections for background noise

The requirements of ISO 3744 shall be followed, as applicable.

NOTE When the levels of the background noise in the test room are extremely low and very controlled, it is possible that the environment satisfies the absolute and/or relative criteria for background noise in accordance with ISO 3744.

### 7.8 Calculation of surface time-averaged sound pressure level

Calculation of surface time-averaged sound pressure level over the measurement surface shall be in accordance with the relevant procedure of ISO 3744. This includes corrections for background noise,  $K_1$ , and test environment,  $K_2$ . For hemi-anechoic rooms meeting the qualification requirements of ISO 3745, no  $K_2$  correction is applied.

### 7.9 Determination of sound power levels

### 7.9.1 Calculation of band time-averaged sound power levels

When band data are required, the sound power level, under reference meteorological conditions, of the equipment in each one-third-octave band within the frequency range of interest shall be based on the surface time-averaged sound pressure level and determined in accordance with the procedure of ISO 3744.

NOTE The procedures given in ISO 3744 is used to determine the sound power level under reference meteorological conditions (ambient pressure 1,013 25  $\times$  10<sup>5</sup> Pa, temperature 23,0 °C, relative humidity 50 %).

For supplemental measurements of equipment that has varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, the sound power level for each one-third-octave band within the frequency range of interest shall be determined under meteorological conditions representing the measurement by using the approach for different meteorological conditions described in ISO 3745. If the ambient pressure cannot be measured, it may be computed using the Barometric Law according to Formula (1).

The sound power level in the k-th octave band,  $L_{Woct, k}$ , in decibels, if needed, shall be based on one-third-octave band data,  $L_{W1/3, j}$ , and calculated from Formula (2).

# 7.9.2 Calculation of A-weighted sound power level

For the purposes of this Standard, the A-weighted sound power level,  $L_{WA}$ , in decibels, under reference meteorological conditions, can be derived either directly from A-weighted sound pressure levels, or by calculation from one-third-octave-band data using the A-weighting values for each band in accordance with the procedures of ISO 3744.

NOTE The procedures given in ISO 3744 are used to determine the sound power level under reference meteorological conditions (ambient pressure  $1,013\ 25 \times 10^5\ Pa$ , temperature  $23,0\ ^{\circ}C$ , relative humidity  $50\ \%$ ).

In the latter case, the A-weighted sound power level,  $L_{WA}$ , in decibels, shall be based on the frequency range of interest, and calculated from Formula (3).

For supplemental measurements of equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, the A-weighted sound power level shall be determined under meteorological conditions representing the measurement by using the approach described in ISO 3745. If the ambient pressure cannot be measured, it may be computed using Formula (1).

Some ITT equipment emits high-frequency noise in the 16 kHz octave band. Depending upon the nature of noise emissions, Table 4 shows how to handle each situation.

For the determination of A-weighted sound power levels from band levels, this Standard does not extend the frequency range of interest to include the 16 kHz octave band.



For equipment which emits discrete tone(s) in the 16 kHz octave band, each frequency and level of the tone(s) that is (are) within 10 dB of the highest tone level in the band shall be determined in accordance with the procedures specified in ECMA-108 (see Table 4). The derived levels are not frequency weighted.

**CAUTION** — The 16 kHz octave band contribution is not included in the determination of A-weighted level.

# 8 Method for determination of emission sound pressure levels at defined operator and bystander positions

### 8.1 General

The method specified in this clause defines the conditions for determination of the emission sound pressure levels of ITT equipment at the work station (operator position) and, if there is no operator position, at the bystander positions in an essentially free field over a reflecting plane in accordance with ISO 11201, accuracy grade 2 (engineering method). It applies to equipment which radiates broad-band noise, narrow-band noise, noise which contains discrete frequency components, or impulsive noise.

NOTE The determination specified in this clause is historically based on the engineering method.

Table C.1 identifies whether the types of equipment identified in Annex C shall be measured at the operator position or bystander positions. If the equipment under test is not specifically included in Annex C (or in Table C.1), the requester of the test shall specify whether or not the equipment is considered operator-attended. If so, an operator position shall be defined in accordance with 8.6.2; if not, bystander positions shall be defined in accordance with 8.6.3.

This determination does not apply to sub-assemblies. However, where desired for sub-assemblies, determine an emission sound pressure level from a previously obtained sound power level using  $Q = Q_1 = 8$  dB in accordance with ISO 11203. This value of Q corresponds to a radial distance of 1 m from a small sub-assembly radiating hemispherically; for uniformity this value of Q is applicable to all sub-assemblies. Optionally, actual emission sound pressure levels may be determined at operator or bystander positions, as described in the following.

Determination of whether the noise at the operator position or at the bystander positions contains prominent discrete tones is specified in Annex D. The method is applicable to both ITT equipment and sub-assemblies.

Determination of whether the noise at the operator position or at the bystander positions contains prominent tonalities is specified in Annex G based on the hearing model approach in Annex F. The method is applicable to both ITT equipment and sub-assemblies.

### 8.2 Measurement uncertainty

Measurements carried out in accordance with this method yield standard deviations of reproducibility for the frequency range of interest of this Standard which are equal to, or less than, those given in Table 6.



Table 6 — Typical upper bound values of the standard deviation of reproducibility in determining emission sound pressure level at the operator and bystander positions in an essentially free field over a reflecting plane in accordance with Clause 8

Octave-band centre frequencies Hz	One-third-octave-band centre frequencies Hz	Standard deviation of reproducibility, $\sigma_{R0}$ dB
125	100 to 160	3,0
250 to 500	200 to 630	2,0
1 000 to 4 000	800 to 5 000	1,5
8 000	6 300 to 10 000	2,5

NOTE 1 For most ITT equipment, the A-weighted emission sound pressure level is determined by the emission sound pressure levels in the 250 Hz to 4 000 Hz octave bands. The A-weighted emission sound pressure level is determined with a standard deviation of approximately 1,5 dB. A larger standard deviation can result when the emission sound pressure levels in other bands determine the A-weighted emission sound pressure level.

NOTE 2 In free-field conditions over a reflecting plane, the standard deviations of reproducibility,  $\sigma_{R0}$  (see 3.3.2), given in Table 6, reflect the cumulative effects of all causes of measurement uncertainty, including variations from laboratory to laboratory, but excluding variations in the emission sound pressure level from equipment to equipment or from test to test which can be caused, for example, by changes in the installation or operating conditions of the equipment. In quantitative sense, the repeatability,  $\sigma_{\Gamma}$  (see 3.3.1), of the test results for the same piece of equipment and the same measurement conditions can be considerably better (i.e. smaller standard deviations) than indicated by the values given in Table 6.

NOTE 3 If the method specified in this clause is used to compare the emission sound pressure levels of similar equipment that are omnidirectional and radiate broad-band noise, this comparison yields a standard deviation which is less than that given in Table 6, provided that the measurements are carried out in the same environment.

# 8.3 Test environment

# 8.3.1 General

The measurements shall be carried out in a qualified environment in accordance with ISO 11201, accuracy grade 2 (engineering method). For convenience, the measurements may be carried out in conjunction with those performed in accordance with Clause 7.

**CAUTION** — Installation conditions are not always identical between Clause 7 and Clause 8.

# 8.3.2 Meteorological conditions

The requirements of ISO 11201, accuracy grade 2 (engineering method) shall be followed.

The following conditions are recommended:

- a) ambient pressure: 86 kPa to 106 kPa;
- b) ambient temperature: within the range defined by the manufacturer for the equipment, if a range is defined; if no range is so defined by the manufacturer, the recommended range is 15 °C to 30 °C;
- c) relative humidity: within the range defined by the manufacturer for the equipment, if a range is defined; for processing of paper and card media only, if no range is so defined by the manufacturer, the recommended range is 40 % to 70 %.

For equipment whose noise emissions vary with ambient temperature in a prescribed manner (e.g. by varying the speeds of air-moving devices), the ambient temperature shall be 23  $^{\circ}$ C  $\pm$  2  $^{\circ}$ C for at least one measurement. Supplemental measurements at temperatures relevant to the equipment's expected use may be performed by controlling the ambient temperature or by simulating the equipment's operation. If there is spatial variation in



the ambient temperature, the temperature shall be measured near where the equipment is most sensitive to the ambient temperature, such as an airflow inlet.

For equipment whose noise emissions vary with altitude (i.e. ambient pressure) in a prescribed manner (e.g. by varying the speeds of air-moving devices), either the altitude of the test room shall be less than or equal to 500 m above sea level, or the equipment shall be tested under conditions simulating its operation at an altitude less than or equal to 500 m above sea level. Supplemental measurements at different altitudes relevant to the equipment's expected use may be performed at such altitudes or by simulating the equipment's operation.

NOTE 1 This variation of speed of air-moving devices does not refer to the changing speed that is already accounted for in the correction for ambient pressure described in the 8.8.1, NOTE.

NOTE 2 The altitude is identified as a determiner of some varying noise emissions for simplicity and ease of communication. However, while it is the primary factor, it is not the only factor in determining the ambient pressure, which is the root cause of such varying noise emissions. It is the ambient pressure that has a direct effect on the acoustical noise emission. Both the altitude and the ambient temperature are necessary to calculate the more precise ambient pressure.

### 8.4 Instrumentation

Instrumentation shall meet the requirements of ISO 11201, accuracy grade 2 (engineering method) and the additional requirements of 7.4.

### 8.5 Installation and operation of equipment

Equipment shall be installed and operated in accordance with the requirements of Clause 5 except for handheld and table-top equipment.

Hand-held equipment shall be installed so that the equipment is flat on a standard test table, with the front edge of the device aligned with the front edge of the table. Hand-held equipment may be optionally isolated from the surface by a small number of elastomeric feet, approximately 12 mm high.

Table-top equipment shall be installed centred on a standard test table, unless otherwise specified in Annex C. Any table-top equipment combination which includes a keyboard shall be installed such that the smallest rectangle in the plane of the table and encompassing the keyboard and other units is centred on the top of the standard test table or as specified in Annex C. Any table-top equipment combination which normally is operated with a detachable keyboard but which is tested without the keyboard shall be centred on the test table as in the preceding sentence and as if the keyboard were present, unless otherwise specified in Annex C.

For optional measurement of sub-assemblies intended for use in table-top products, install the sub-assembly in the centre of a standard test table and isolated from the surface by a small number of elastomeric feet, approximately 12 mm high. For optional measurement of sub-assemblies intended for use in other enclosures or racks, install the sub-assembly as specified in 5.1.7.

### 8.6 Microphone positions

### 8.6.1 General

8.6.2 and 8.6.3 specify the ways to define operator and bystander positions, respectively.

For equipment already standardized, Annex C specifies which position(s) is (are) applicable to each category. See Table C.1.

NOTE These requirements are in accordance with, but more specific than, those of ISO 11201, accuracy grade 2 (engineering method).



### 8.6.2 At the operator position(s)

One or more operator positions shall be specified for equipment which requires operator attention while in the operating mode.

For equipment operated from a standing position, the microphone shall be located 1,50 m  $\pm$  0,03 m above the floor [see Figure 1 a), position P1].

For equipment operated from a seated position, the microphone shall be located 1,20 m  $\pm$  0,03 m above the floor [see Figure 1 b), 2 a) or 2 b), position P2, P3 or P4].

The horizontal distance from the reference box shall be  $0.25 \text{ m} \pm 0.03 \text{ m}$ , unless this distance is not representative of the operator position; in the latter case, the representative operator position shall be described and used.

For table-top equipment which normally has a detachable keyboard and which is tested without the keyboard (e.g. a desk-top personal computer or a video display unit that is tested without a keyboard), the distance from the front end of the reference box, for purposes of determining the operator position, shall be 0,50 m  $\pm$  0,03 m [see Figure 2 b), position P4].

For optional measurement of sub-assemblies intended for use in equipment with a defined operator position, the above position shall be used for the sub-assembly measurement (i.e.  $0.25 \text{ m} \pm 0.03 \text{ m}$  if table-top equipment does not have a detachable keyboard, and  $0.50 \text{ m} \pm 0.03 \text{ m}$  otherwise from front of reference box, and  $1.20 \text{ m} \pm 0.03 \text{ m}$  above the reflecting plane).

During this measurement the operator should be absent, if possible, or move aside, so that he/she can still operate the equipment but does not significantly disturb the sound field around the microphone.

For hand-held equipment, the microphone shall be located 1,0 m  $\pm$  0,03 m above the floor, and the horizontal distance from the reference box shall be 0,125 m  $\pm$  0,01 m [see Figure 3, position P5].

NOTE If the sound pressure level at the operator position is measured on operator-attended equipment, then measurement of sound pressure level at a bystander position is not required.

### 8.6.3 At the bystander positions

For equipment which does not require operator attention while in the operating mode, an operator position may not be specified. In this case, at least four bystander positions shall be selected and specified to determine the mean emission sound pressure level (see 8.8.3). For reporting and/or declaration purposes, this mean value is applicable, rather than the value at each bystander position.

The bystander positions shall be at a horizontal distance of 1,00 m  $\pm$  0,03 m from the sides of the reference box and at a vertical distance of 1,50 m  $\pm$  0,03 m above the floor. The four preferred bystander positions are centred horizontally at the front, rear, right and left sides of the reference box. If the length of any side of the reference box exceeds 2,0 m, additional bystander positions at 1,0 m intervals should be used. For wall-mounted equipment or for equipment placed against the wall, the three preferred bystander positions are centred at the front, right, and left sides of the reference box.

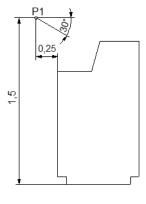
For optional measurement of sub-assemblies intended for use in equipment which does not require operator attention while in the operating mode, install the sub-assembly in accordance with 5.1.7, define the reference box and apply the provisions of the preceding two paragraphs to define the bystander positions.

### 8.6.4 Microphone orientation

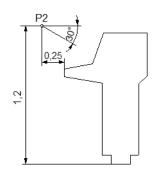
The microphones shall be oriented in such a way that the angle of sound incidence is the same as the angle for which the microphone has the most uniform frequency response. For most practical cases, the primary sound source is assumed to be either 30° or 45° below horizontal (see Figures 1, 2 and 3).



# Dimensions in metres



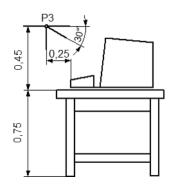
a) Standing operator



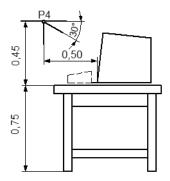
b) Seated operator

Figure 1 — Examples of microphone positions for operators of floor-standing equipment

Dimensions in metres



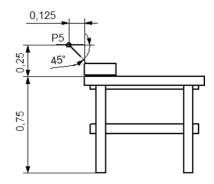
a) Seated operator for table-top equipment (case 1: with keyboard)



b) Seated operator for table-top equipment (case 2: without keyboard)

Figure 2 — Examples of microphone positions for operators of table-top equipment

Dimensions in metres



Operator for hand-held equipment

Figure 3 — Example microphone position for operators of hand-held equipment



### 8.7 Measurement of sound pressure levels

### 8.7.1 General

Measurements of the sound pressure level required by this clause shall be carried out at the microphone positions specified in 8.6 with A-weighting and/or for each frequency band within the frequency range of interest. Record:

- a) the A-weighted sound pressure levels and/or the one-third-octave band sound pressure levels, for the specified modes of operation of the equipment;
- b) the A-weighted sound pressure levels and/or the one-third-octave band sound pressure levels of the background noise (including noise from support equipment).

When using a sound level meter, the person reading the meter shall not disturb the sound field at the microphone.

If spatial fluctuations occur, due to interferences or standing waves, it is recommended that the microphone be moved by approximately 0,1 m in a vertical plane around the nominal measurement position, and the average sound pressure level recorded.

In order to obtain the emission sound pressure level at a specified position, only background noise corrections  $K_1$  ( $K_{1A}$  for A-weighted sound pressure level) shall be applied to the measured sound pressure level, in accordance with the procedure of ISO 11201, accuracy grade 2 (engineering method) (see 8.7.3.); environmental corrections,  $K_2$  ( $K_{2A}$  for A-weighted sound pressure level) shall not be applied.

NOTE 1 Determination of whether the noise emission at the operator position or at the bystander positions contains prominent discrete tones is specified in Annex D. Determination of whether the noise at the operator position or at the bystander positions contains prominent tonalities is specified in Annex G based on the hearing model approach in Annex F.

Measurements of the C-weighted peak emission sound pressure level,  $L_{pCpeak}$ , shall be carried out at the microphone positions specified in 8.6 if any of the C-weighted peak sound pressure levels at the specified positions exceeds 120 dB.

NOTE 2 Some regulations require declaration of C-weighted peak emission sound pressure levels greater than 130 dB. Contemporary ITT equipment is unlikely to emit C-weighted peak emission sound pressure levels ( $L_{p\text{Cpeak}}$ ) greater than 120 dB, which is set in this Standard as a conservative threshold above which measurement and reporting are required.

NOTE 3 Depending on the purposes of the test, it may be the case that one or more repeated measurements are taken for the source under test. Provided that each of the measurements in the repeated set represent identical conditions for the source under test, and that they are each valid measurements in accordance with the requirements of this Standard, the arithmetic average of the measured sound pressure levels, in decibels, should be taken as the measurement result of this clause.

### 8.7.2 Measurement time interval

The measurement time interval shall be as specified in 7.7.2.

### 8.7.3 Corrections for background noise

The requirements of ISO 11201, accuracy grade 2 (engineering method) shall be followed.

NOTE When the background noise levels in the test room are extremely low and very controlled, it is possible that the environment satisfies the absolute and/or relative criteria for background noise in accordance with ISO 11201, accuracy grade 2 (engineering method).



### 8.8 Determination of emission sound pressure levels

### 8.8.1 Calculation of band emission sound pressure levels

The emission sound pressure level, under reference meteorological conditions, of the equipment in each one-third-octave band within the frequency range of interest (see 3.2.11) is obtained by using the procedure of ISO 11201, accuracy grade 2 (engineering method).

NOTE 1 The procedures given in ISO 11201 are used to determine the emission sound pressure level under reference meteorological conditions (ambient pressure 1,013  $25 \times 10^5$  Pa, temperature 23,0 °C, relative humidity 50 %).

For supplemental measurements of equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, the sound pressure level for each one-third-octave band within the frequency range of interest shall be determined under meteorological conditions representing the measurement by using the formula for normalizing to reference meteorological conditions in ISO 11201. (The formula in ISO 11201 will have to be applied twice, once to normalize to reference meteorological conditions and then again to convert the reference meteorological conditions to representative meteorological conditions.) If the ambient pressure cannot be measured, it may be computed using Formula (1).

NOTE 2 The meteorological corrections for the supplemental measurements will only be non-zero if the temperature or altitude was simulated during the equipment's operation.

NOTE 3 The approach for applying meteorological corrections to the sound pressure level via the formula in ISO 11201 is analogous to the sound power level correction via the approach in ISO 3745 per 6.10.1, 7.9.1, and 7.9.2.

The emission sound pressure level in the k-th octave band,  $L_{poct, k}$  in decibels, if needed, shall be based on one-third-octave band data, and calculated as per Formula (4):

$$L_{poct,k} = 10 \lg \sum_{j=3k-2}^{3k} 10^{0,1L_{p1/3,j}}$$
 (4)

where

k is an identification number of an octave band within the frequency range of interest (see Table 2);

 $L_{p1/3,j}$  is the emission sound pressure level, in decibels in the j-th one-third-octave band (see Table 3);

is an identification number lying within the range of (3k - 2) and 3k, and which identifies the three one-third-octave bands which make up the k-th octave band.

# 8.8.2 Calculation of A-weighted emission sound pressure levels from band levels

For the purpose of this Standard, A-weighted emission sound pressure levels,  $L_{pA}$ , in decibels, can be derived either directly from A-weighted sound pressure level, or by calculation from one-third-octave band data using the A-weighting values for each band in accordance with the procedures of ISO 11201, accuracy grade 2 (engineering method).

NOTE 1 The procedures in ISO 11201 are used to determine the emission sound pressure level under reference meteorological conditions (ambient pressure 1,013  $25 \times 10^5$  Pa, temperature 23,0 °C, relative humidity 50 %).

For supplemental measurements of equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, the A-weighted emission sound pressure level shall be determined under meteorological conditions representing the measurement by using the approach described in ISO 11201. If the ambient pressure cannot be measured, it may be computed using Formula (1). (The formula will have to be applied twice, once to normalize to reference meteorological conditions and then again to convert the reference meteorological conditions to representative meteorological conditions.)



NOTE 2 The meteorological corrections for the supplemental measurements will only be non-zero if the temperature or altitude was simulated in the equipment's operation.

NOTE 3 The approach for applying meteorological corrections to the sound pressure level via the formula in ISO 11201 is analogous to the sound power level correction via the approach in ISO 3745 per 6.10.1, 7.9.1, and 7.9.2.

In the latter case, the A-weighted emission sound pressure level,  $L_{pA}$ , in decibels, shall be based on the applicable frequency range of interest, and calculated as per Formula (5):

$$L_{pA} = 10 \lg \sum_{i=1}^{21} 10^{0,1(L_{p_1/3,j} + A_j)}$$
 (5)

where

 $L_{p1/3i}$  is the emission sound pressure level, in decibels, in the *j*-th one-third-octave band;

 $A_j$  is the A-weighting value corresponding to the j-th one-third-octave band from Table 3;

j is an identification number of one-third-octave band within the frequency range of interest.

Some ITT equipment emits high-frequency noise in the 16 kHz octave band. Depending upon the nature of noise emissions, Table 4 shows how to handle each situation. For the purposes of Clause 8, "sound power level" or "level" in Table 4 shall be replaced by "emission sound pressure level". The derived levels are not frequency weighted.

For the determination of A-weighted emission sound pressure levels from band levels, this Standard does not extend the frequency range of interest.

For equipment which emits discrete tone(s) in the 16 kHz octave band, each frequency and level of the tone(s) that is (are) within 10 dB of the highest tone level in the band shall be determined in accordance with the procedures specified in ECMA-108 (see Table 4).

CAUTION — The 16 kHz octave-band contribution is not included in the determination of the A-weighted level.

### 8.8.3 Calculation of the mean emission sound pressure level at the bystander positions

If bystander positions are defined, the mean A-weighted emission sound pressure level,  $L_{pA}$ , and the mean band emission sound pressure levels,  $L_p$ , in decibels (reference: 20  $\mu$ Pa), if required, at bystander positions defined in 8.6.3, shall be calculated as specified in Formula (6):

$$L_p = 10lg \left[ \frac{1}{N} \sum_{i=1}^{N} 10^{0.1 L_{pi}} \right]$$
 (6)

where

 $L_{pi}$  is the band emission sound pressure level, in decibels (reference: 20  $\mu$ Pa), resulting from measurement at the *i*-th bystander position;

N is the number of bystander positions.

For the A-weighted emission sound pressure level, the symbols  $L_p$  and  $L_{pi}$  are replaced by  $L_{pA}$  and  $L_{pA_i}$ , respectively.



# 9 Measurement uncertainty

The uncertainties of sound power levels,  $u(L_W)$ , in decibels, and emission sound pressure levels,  $u(L_p)$ , in decibels, determined in accordance with this Standard are estimated by the total standard deviation,  $\sigma_{\text{tot}}$  in decibels, as given in Formulae (7) and (8):

$$u(L_W) \approx \sigma_{\text{tot}}$$
 (7)

$$u(L_p) \approx \sigma_{\rm tot}$$
 (8)

This total standard deviation is obtained by using the modelling approach described in ISO/IEC Guide 98-3<sup>[13]</sup>. This requires a mathematical model, which in case of lack of knowledge, can be replaced by results from measurements, including results from round robin testing.

The guidance on the development of information on measurement uncertainty contained in the relevant clauses of ISO 3741, ISO 3744 and ISO 11201 (only engineering method), as applicable, can be used for this Standard.

In this context, the total standard deviation,  $\sigma_{\text{tot}}$ , is expressed by the standard deviation of reproducibility of the method,  $\sigma_{R0}$ , in decibels, and the standard deviation,  $\sigma_{\text{omc}}$ , in decibels, describing the uncertainty due to the instability of the operating and mounting conditions of the equipment under test in accordance with Formula (9):

$$\sigma_{\rm tot} = \sqrt{\sigma_{R0}^2 + \sigma_{\rm omc}^2}.$$

For determination of the total standard deviation, see Table 7.

Table 7 — Parameters to determine the total standard deviation,  $\sigma_{\mathrm{tot}}$ 

Measurement method	Quantity to be determined	Standard deviation of reproducibility, $\sigma_{R0}$	Uncertainty due to the instability of the operating and mounting conditions of the equipment under test, $\sigma_{\rm omc}$
Clause 6	Sound power level	See Table 1ª	See relevant clause and annex of ISO 3741
Clause 7	Sound power level	See Table 5ª	See relevant clause and annex of ISO 3744 or ISO 3745, as applicable
Clause 8	Emission sound pressure level	See Table 6ª	See relevant clause and annex of ISO 11201 (engineering method only)
<sup>a</sup> For details of the values of Tables 1, 5 and 6, see Reference [19].			

If the uncertainty of measurement is to be reported, the expanded measurement uncertainty, U, in decibels, can be calculated from  $\sigma_{\text{tot}}$  as per Formula (10):

$$U = k\sigma_{\text{tot}} \tag{10}$$

The value of U depends on the degree of confidence that is desired. In general, it is 95 %, and the practical examples are as follows:

- For a normal distribution of measured values, there is 95 % confidence that the true value lies within the range  $(L_W U)$  to  $(L_W + U)$  [or  $(L_p U)$  to  $(L_p + U)$ ]. This corresponds to a coverage factor of k = 2.
- If the purpose of determining the sound power level or emission sound pressure level is to compare the result with a limit value, it can be more appropriate to apply the coverage factor for a one-sided normal distribution. In that case, the coverage factor k = 1,6 corresponds to a 95 % confidence level.

NOTE For each quantity to be determined (see Table 9), the details of determination of the value of U (including statistical concepts, such as confidence level, coverage factor, normal distribution, etc.) are explained in each of the relevant clause and annex of the basic noise emission standards (i.e. ISO 3741, ISO 3744, ISO 3745 or ISO 11201), as applicable.



# 10 Information to be recorded and reported

### 10.1 Information to be recorded

### 10.1.1 General

The information specified in 10.1.2 to 10.1.5 shall be recorded, when applicable. In addition, any deviation from any requirement in this noise test code or from the basic noise emission standards (i.e. ISO 3741 for Clause 6, ISO 3744 or ISO 3745 as applicable for Clause 7, or ISO 11201 for Clause 8) upon which it is based shall be recorded together with the technical justification for such deviation.

All requirements for recording and reporting specified in the basic noise emission standards are also requirements of this Standard. That is, the requirements below are necessary but not sufficient.

### 10.1.2 Equipment under test

The following information shall be recorded:

- a) a description of the equipment under test (including main dimensions; name, model and serial number of each unit; name, model and serial number of noise-producing components and sub-assemblies in the equipment under test);
- b) a complete description of the idle and operating modes, including operating speed, data medium used and the test programme in terms that are meaningful for the type of equipment being tested;
- c) if applicable, the ambient temperature, in degrees Celsius, relative humidity, as a percentage, and altitude, in metres, representing a simulated measurement;
- d) a complete description of the installation and mounting conditions;
- e) the location of the equipment in the test environment;
- f) the location and functions of an operator, if present;
- g) the nominal power line frequency, in hertz (e.g. 50 Hz), and the measured power line voltage, in volts;
- h) a sample of typical hardcopy output of the product being tested, which, when applicable, should be filed as part of the recorded data;
- i) a statement as to whether the noise emission is known or reasonably likely to vary with ambient temperature and/or altitude in a prescribed manner, if known.

The following information is given for recording the time signal.

For each operating mode, for the operator position (if defined), otherwise for the bystander position (if defined) with the highest A-weighted sound pressure level, the time signal of sound pressure may be recorded, of at least the measurement time interval specified in 8.7.2, with relevant information of the name of the product, the test mode, the microphone position, and the A-weighted sound pressure level of the signal. Dolby¹ or other digital noise reduction features shall not be used. This Standard does not require that a separate calibration signal be recorded. The bias information used in recording shall be filed with the time signal data.

### 10.1.3 Acoustical environment

The following information shall be recorded.

- a) If the sound power level is determined in accordance with Clause 6 (ISO 3741):
  - 1) a description of the test room, including dimensions, shape, surface treatment of the walls, ceiling and floor; a sketch showing location of source and room contents;

<sup>1)</sup> Dolby is an example of a suitable product available commercially. This information is given for the convenience of users of this Standard and does not constitute an endorsement by Ecma of this product.



- 2) a description of diffusers, or rotating vanes, if any;
- 3) qualification of reverberation test room in accordance with ISO 3741;
- 4) the ambient air temperature, in degrees Celsius, relative humidity, as a percentage, and ambient pressure in kilopascals.
- b) If the sound power level is determined in accordance with Clause 7 (ISO 3744 or ISO 3745):
  - a description of the acoustical environment, if indoors, the size and acoustic characteristics of the room, including absorptive properties of the walls, ceiling and floor; a sketch showing the location of the equipment under test;
  - 2) environmental corrections,  $K_2$ , resulting from the acoustical qualification of test environment in accordance with the relevant procedure of ISO 3744, unless the environment has been qualified in accordance with ISO 3745 in the case of compliance with ISO 3745, this fact should be stated:
    - 3) the ambient air temperature, in degrees Celsius, relative humidity, as a percentage, and ambient pressure, in kilopascals.
- c) For emission sound pressure level at the operator and bystander positions in accordance with Clause 8 [ISO 11201, accuracy grade 2 (engineering method)]:

NOTE 1 The type of information below is the same as for sound power level determination, just described, but the values can differ from those recorded for sound power level. If the information recorded for sound power level determination in accordance with the preceding paragraph is applicable here, it is sufficient to so note in the test file.

- a description of the acoustical environment, if indoors, the size and acoustic characteristics of the room, including absorptive properties of the walls, ceiling and floor; a sketch showing the location of the equipment under test;
- 2) environmental corrections,  $K_2$ , resulting from the acoustical qualification of test environment in accordance with the relevant procedure of ISO 3744, unless the environment has been qualified in accordance with ISO 3745; in the case of conformance with ISO 3745, this fact should be stated;

NOTE 2 Environmental corrections  $K_2$  are not intended to be used to modify the measured values but is included as part of the test record as an indication of the quality of the measurement.

3) the ambient air temperature in degrees Celsius, relative humidity as a percentage, and ambient pressure in kilopascals.

### 10.1.4 Instrumentation

The following information shall be recorded:

- a) equipment used for the measurements, including name, type, serial number and manufacturer;
- b) bandwidth of frequency analyser [including a digital Fast Fourier Transform (FFT) analyser, if used in Annex D];
- c) frequency response of the instrumentation system;
- d) method used for daily checking of the calibration of the microphones and other system components;
- e) the date and place of any required periodic calibrations;
- f) the test method used for determination of:
  - 1) the mean time-averaged sound pressure level in accordance with ISO 3741; or the surface time-averaged sound pressure level in accordance with ISO 3744;
  - 2) the mean value of the emission sound pressure level at the operator or bystander positions, as applicable, in accordance with ISO 11201;

### 10.1.5 Acoustical data

The following information shall be recorded.

a) If the sound power level is determined in accordance with Clause 6 (ISO 3741):



- 1) location and orientation of the microphone traverse (path) or array (a sketch should be included if necessary);
- 2) the corrections, if any, in decibels, applied in each frequency band for the frequency response of the microphone, frequency response of the filter in the passband, background noise, etc.;
- 3) the values of the difference between the sound power and sound pressure levels produced by the reference sound source ( $L_{WT} L_{pr}$ ), in decibels, as a function of frequency;
- 4) the band pressure level readings, in decibels, to at least the nearest 0,1 dB for the calculations in accordance with ISO 3741;
- 5) the sound power levels in decibels (reference: 1 pW) in octave and/or one-third-octave bands, tabulated or plotted, rounded to the nearest 0,1 dB;
- 6) the sound power level in decibels (reference: 1 pW), in octave and/or one-third-octave bands, tabulated or plotted to the nearest 0,1 dB under reference meteorological conditions or, for equipment that has varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
- 7) the A-weighted sound power level in decibels (reference: 1 pW) rounded to the nearest 0,1 dB;
- 8) the A-weighted sound power level in decibels (reference: 1 pW), rounded to the nearest 0,1 dB under reference meteorological conditions or, for equipment that has varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
- 9) the date, time and place that the measurements were carried out, and the name of the person who carried out the measurements.
- b) If the sound power level is determined in accordance with Clause 7 (ISO 3744):
  - the shape of the measurement surface, the measurement distance, the location and orientation of microphone positions (including both key microphone positions and additional ones, if required) or paths used plus, if traversing microphones were used, the maximum traversing speed along a path and microphone orientation;
  - 2) the area, S, in square metres, of the measurement surface;
  - 3) the corrections, if any, in decibels, applied in each frequency band for the frequency response of the microphone, and the frequency response of the filter in the passband;
  - 4) the background noise correction,  $K_1$  (A-weighted or in frequency bands), for the surface time-averaged sound pressure levels:
  - 5) the background noise level measured at each point and the average background sound pressure levels;
  - 6) the environmental corrections,  $K_2$  (A-weighted and in frequency bands), and the method by which they were determined in accordance with one of the procedures of ISO 3744;
  - 7) the A-weighted surface time-averaged sound pressure level and the band surface time-averaged sound pressure level,  $\overline{L_p}$ , for each frequency band of interest, rounded to the nearest 0,1 dB;
  - 8) the sound pressure levels,  $L_{pi}$  (A-weighted or in frequency bands), at each measuring point, i;
  - 9) the A-weighted sound power level,  $L_{WA}$ , and the band sound power level,  $L_{W}$ , for each frequency band of interest, rounded to the nearest 0,1 dB under reference meteorological conditions or, for equipment that has varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
  - 10) the A-weighted sound power level,  $L_{WA}$ , and the band sound power level,  $L_{W}$ , for each frequency band of interest, rounded to the nearest 0,1 dB under reference meteorological conditions or, for equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
  - 11) the date, time and place that the measurements were carried out, and the name of the person who carried out the measurements.
- c) For emission sound pressure levels at the operator or bystander positions, as applicable, in accordance with Clause 8 [ISO 11201, accuracy grade 2 (engineering method)]:
  - 1) the measurement positions and microphone orientations (preferably including a sketch);



- 2) if one or more operator positions are defined in accordance with 8.6.2, the A-weighted emission sound pressure level  $L_{pA}$ , the band emission sound pressure levels, if required, and the C-weighted peak emission sound pressure level,  $L_{pC,peak}$ , if greater than 120 dB, measured at the operator position(s), for both the idle and operating modes, in decibels, rounded to the nearest 0,1 dB;
- 3) if bystander positions are defined in accordance with 8.6.3, the A-weighted emission sound pressure levels at the bystander positions, the mean A-weighted emission sound pressure level  $L_{p\text{A}}$ , and the mean band emission sound pressure levels, if required, calculated in accordance with 8.8.3 and the C-weighted peak emission sound pressure level  $L_{p\text{Cpeak}}$ , if greater than 120 dB (see NOTE 2 to 8.7.1) at the bystander position with the highest A-weighted emission sound pressure level, for both the idle and operating modes, in decibels, rounded to the nearest 0,1 dB;
- 4) all emission sound pressure levels, in decibels, under reference meteorological conditions or, for equipment that has varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
- 5) optionally, the frequency, in hertz, of any prominent discrete tones identified in accordance with the procedures of Annex D and the value of the tone-to-noise ratio  $\Delta L_T$  and/or prominence ratio  $\Delta L_P$  as applicable, in decibels, associated with that prominent discrete tone, or the frequency, in Hertz, of prominent tonalities identified in accordance with the procedures of Annex G and the corresponding psychoacoustic tonality value;
- 6) A-weighted background noise levels and background noise correction,  $K_{1A}$ , at each specified position, and as required, background noise levels and correction,  $K_{1}$ , in frequency bands;
- 7) the date, time and place where the measurements were carried out, and the name of the person who carried out the measurements.

# 10.2 Test report

The test report shall contain at least the following information:

- a) A statement of whether the sound power levels and the emission sound pressure levels at operator or bystander positions, as applicable, have been obtained in full conformity with the procedures specified in this Standard, i.e. ECMA-74:2019, and ISO 3741, ISO 3744 or ISO 3745, as applicable, and ISO 11201. Any deviation from any requirement of these International Standards shall be reported, together with the technical justification for such deviation;
- b) A statement that these sound power levels are expressed in decibels (reference: 1 pW) rounded to the nearest 0,1 dB and that these emission sound pressure levels are expressed in decibels (reference: 20 μPa), rounded to the nearest 0,1 dB;
- c) A statement that "Measured values in this report are for use in planning or in determining declared values. They are not to be confused with the declared values".
- d) If applicable, a statement indicating that the noise emission is known or reasonably likely to vary with ambient temperature and/or altitude in a prescribed manner;
- e) The ambient temperature, in degrees Celsius, relative humidity, as a percentage, and altitude, in metres, at the time of the measurement;
- f) If applicable, the ambient temperature, in degrees Celsius, relative humidity, as a percentage, and altitude, in metres, representing a simulated measurement;
- g) The name(s) and model number(s) of the equipment under test;
- h) The A-weighted sound power level,  $L_{WA}$ , in decibels, for the idle mode and the operating mode(s) (reference: 1 pW), under reference meteorological conditions or, for supplemental measurements of equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
- i) The sound power levels,  $L_W$ , in decibels, in octave or one-third-octave bands, if required, for the idle mode and the operating mode(s) (reference: 1 pW), under reference meteorological conditions or, for supplemental measurements of equipment that have varying noise emissions in a prescribed manner



due to the ambient temperature and/or altitude, using representative meteorological conditions; the bandwidth used shall be stated;

- j) If one or more operator positions are defined in accordance with 8.6.2, the highest A-weighted emission sound pressure level,  $L_{pA}$ , and if required, the band emission sound pressure levels, in decibels (reference: 20 µPa), at the operator position(s) for the idle and operating modes, under reference meteorological conditions or, for supplemental measurements of equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
- k) If bystander positions are defined in accordance with 8.6.3, the mean A-weighted emission sound pressure level,  $L_{pA}$ , and, if required, the mean band emission sound pressure levels in decibels (reference: 20  $\mu$ Pa), at the positions specified in 8.6.3 around the equipment for the idle and operating modes, under reference meteorological conditions, or for supplemental measurements of equipment that have varying noise emissions in a prescribed manner due to the ambient temperature and/or altitude, using representative meteorological conditions;
- I) A detailed description of operating and installation conditions of the equipment being tested with reference to the specific subclause of Annex C (including publication date and edition), if applicable (e.g. "operating and installation conditions in accordance with C.20 of ECMA-74:2019, 16<sup>th</sup> edition"). If additional, or substitute, operating conditions or operating modes have been defined in accordance with 5.3, these shall be clearly described in the report.
- m) For each of the reported sound power levels or emission sound pressure levels, respectively, if the uncertainty of measurement is required, the corresponding expanded measurement uncertainty can be reported according to Formula (10).

NOTE 1 To avoid confusion between emission sound pressure level in decibels (reference:  $20 \mu Pa$ ) and sound power levels in decibels (reference: 1 pW), sound power level can be expressed in bels, using the identity 1 bel = 10 decibels.

NOTE 2 For the determination of declared noise emission values for ITT equipment in accordance with ECMA-109 a positive number is added to the average measured value in decibels of sound power level based on statistical considerations to account for both random measurement errors and production variations; the sum is divided by 10 and expressed in bels.

Information in a) to j) may be supplemented by one of the following statements, which describe the character of the noise as determined in accordance with Annex D:

- 1) no prominent discrete tones;
- 2) prominent discrete tones;

Items 1) and 2) shall be supplemented with a statement of the method used to identify prominent discrete tones. Additional statements on the character of the noise in accordance with Annex G may also be given:

- a) no prominent tonalities;
- b) prominent tonalities

NOTE 3 Some regulations require the reporting of the C-weighted peak emission sound pressure level if greater than 130 dB.





# **Annex A** (normative)

# **Test accessories**

### A.1 Standard test table

The design for the standard test table is shown in Figure A.1. The top of the table shall be bonded laminated wood, 0.04 m to 0.10 m thick, having a minimum area of 0.5 m $^2$  and lateral dimensions 0.75 m - 0.05 m/+ 0.03 m. The height of the table shall be 0.75 m  $\pm$  0.03 m. The table may have a slot in its top plate to allow paper to be inserted for printers which feed the paper from underneath their bottom cover. A slot 0.015 m by 0.400 m in lateral dimensions has been found practical for most printer paper.

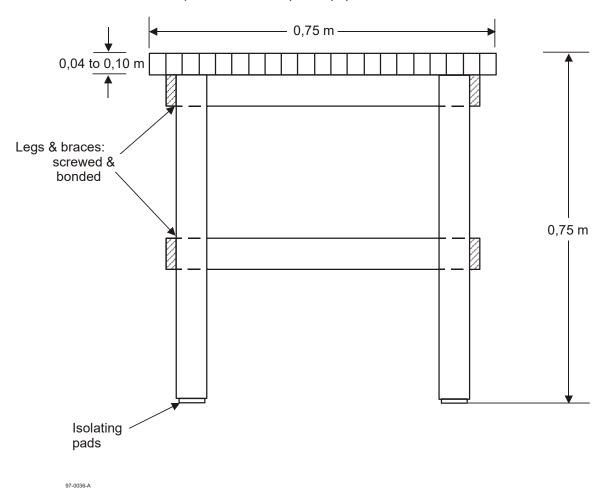


Figure A.1 — Standard test table

Dimensions in metres



# A.2 Typing robot

The typing robot shall be designed to operate a keyboard in the manner specified in this Standard. The robot here described uses eight solenoids, each being individually adjustable to operate one of the selected keyboard keys.

The requirements for this robot are:

- a) the noise of the robot shall meet the requirements for background noise of this Standard;
- the stroke of each solenoid plunger shall fully release the key in its upper position and push it completely down to its stop; a total stroke of 6 mm to 7 mm should be sufficient for most types of keyboards including typewriters;
- c) the electrical input signal shall be a rectangular pulse of 50 ms duration, and of adjustable amplitude;
- d) the solenoid characteristics shall provide an increasing force during key-down motion, as shown in Figure A.2 a suitable design is shown in Figure A.3;
- e) the plunger mass shall be 20 g ± 1 g; its end shall be soft (e.g. closed-cell foam, 40 Shore A).

A complete operation of a single key includes the following three steps, which are shown in Figure A.4:

a) Home position

The plunger rests under its own weight with its soft end on the key.

b) Key operation

When excited by the solenoid, the plunger pushes the key down until it has reached its stop position. The adjustment of the solenoid should give a plunger clearance of 1 mm; an appropriate mark at the upper plunger end will facilitate this adjustment;

c) Key return

The plunger is returned only by the key spring. The plunger return stop shall be soft and allow a maximum overshoot of 0,5 mm; the plunger returns to its home position, resting on the key.

NOTE The specification is based on the design of the robot described in Reference [21].



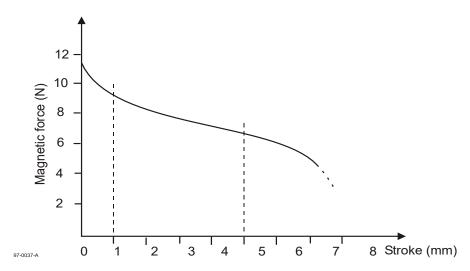


Figure A.2 — Solenoid characteristics for a plunger stroke of 4 mm

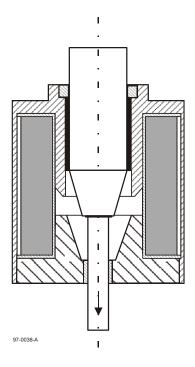


Figure A.3 — Solenoid cross section

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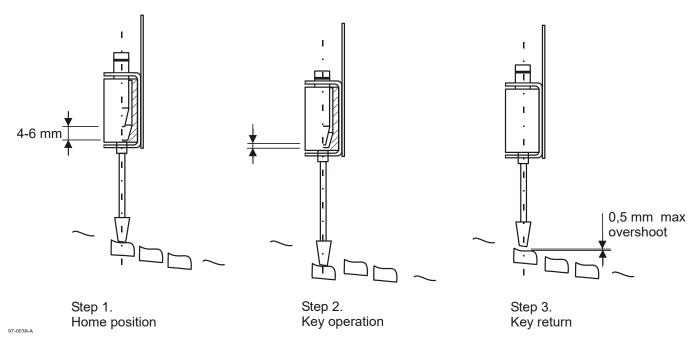


Figure A.4 — Individual steps of the solenoid operation



# Annex B (normative)

# Measurement surfaces

# **B.1** Hemispherical measurement surface

Refer to ISO 3744 for the requirements for microphone locations and geometry of the hemispherical measurement surface and microphone array, supplemented by the following additional conditions:

- a) When using fixed microphone positions, the microphone positions given in ISO 3744 for sources emitting discrete tones shall be used for all sources. The co-ordinates for this array are reproduced in Table B.1;
- b) When using the coaxial circular paths arrangement specified in ISO 3744, it is recommended that a minimum of 10 heights be used.

Other acceptable alternatives are described in the relevant annexes of ISO 3745.

Table B.1 — Co-ordinates of microphone positions for equipment emitting discrete tones

Position	x/r	ylr	z/r
1	0,16	- 0,96	0,22
2	0,78	- 0,60	0,20
3	0,78	0,55	0,31
4	0,16	0,90	0,41
5	- 0,83	0,32	0,45
6	- 0,83	- 0,40	0,38
7	- 0,26	- 0,65	0,71
8	0,74	- 0,07	0,67
9	- 0,26	0,50	0,83
10	0,10	- 0,10	0,99

For the purpose of this Standard, for small equipment which emits very low level noise, a hemispherical measurement surface with a radius less than 1 m, but at least 0,5 m, may be used, provided that the reduced radius is greater than or equal to twice the characteristic source dimension (specified in ISO 3744). If the radius is reduced below 1 m, the lower end of the frequency range of interest becomes higher. To minimize the near field effects, the 0,5 m radius would have a corresponding lower frequency limit of approximately 172 Hz (based on a requirement of one-quarter of the wavelength of sound at the lowest frequency of interest). Additional information is given in References [22], [23] and [24].

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# **B.2** Cylindrical measurement surface

### B.2.1 General

Figure B.1 illustrates the cylindrical measurement surface, having microphones located along the side and top of the cylinder. The cylinder shall be centred around the reference box with the centre of the cylinder's base corresponding to the centre of the reference box base. The dimensions of the reference box,  $l_1$ ,  $l_2$ , and  $l_3$ , and the reference distances to the cylinder,  $d_1$ ,  $d_2$ , and  $d_3$  are as shown. For the purposes of this annex, the dimensional labels shall be assigned so that  $l_1 \ge l_2$ .

### B.2.2 Selection of size of cylindrical measurement surface

The microphone positions lie on the measurement surface, a hypothetical cylindrical surface enveloping the source and having a total area S equal to the sum of the area of the top circular surface,  $S_{top}$ , and the area of the side vertical surface,  $S_{side}$  are given by Formulae (B.1) to (B.3):

$$S = S_{ton} + S_{side} \tag{B.1}$$

$$S_{\text{top}} = \pi R^2 \tag{B.2}$$

$$S_{side} = 2\pi RH \tag{B.3}$$

where

R is the radius of the cylinder, given by Formula (B.4)

$$R = \frac{l_1}{2} + d_1 = \frac{l_2}{2} + d_2 \tag{B.4}$$

H is the height of the cylinder, given by Formula (B.5)

$$H = l_3 + d_3. \tag{B.5}$$

Due to the fact that the microphones are associated with unequal sub-areas, both  $d_3$  and  $d_1$  may be selected arbitrarily based on the size of the equipment under test or other considerations. It is recommended that both of these be set to the same value, preferably 1 m, but neither shall be less than 0,5 m. Furthermore, none of the distances  $d_1$ ,  $d_2$ , or  $d_3$  shall be greater than 1,5 times either of the others (e.g. this condition is met for  $d_1$  and  $d_2$  provided  $d_1 \ge l_1 - l_2$ ). With  $d_3$  and  $d_1$  selected,  $d_1$  and  $d_2$  are defined and  $d_2$  defaults to

$$d_2 = R - \frac{l_2}{2}. (B.6)$$

In certain cases, such as for large machines where  $l_1$  and  $l_2$  are of the same magnitude, the side microphones can pass too close to the machine during their traverse even when the above constraints are met. In view of this, the radius, R, shall be large enough such that the side microphones remain more than 0,25 m from any corner of the reference box.



# B.2.3 Selection of microphone positions on the cylindrical measurement surface

The microphones on the cylindrical measurement surface are associated with unequal sub-areas, as described in the following. The microphones are located along the top circular and side vertical measurement surfaces of the cylinder and may either sweep out continuous paths (circular traverses) along these measurement surfaces or be located at fixed positions on equally spaced "slices" of the cylindrical vertical surface. It is recommended that continuous paths be used for the microphones for sources emitting steady noise. Fixed microphone positions shall be used when the source emits non-steady noise. However, for either steady or non-steady noise, if fixed microphone positions are used to sample over the circular traverses, at least 12 equally spaced angular positions (i.e., at 30° spacing or less) shall be used, starting from an initial angular position perpendicular to one of the sides of the reference box. The traverses may be implemented by either rotating the microphones, keeping the source stationary, or rotating the source, keeping the microphones stationary. When fixed microphone positions are used, the number of angular positions may be reduced if preliminary investigations for a particular family of noise sources show that the surface sound pressure levels determined using the reduced number of positions deviate by no more than 0,5 dB from those using the complete set of positions. This can be practical, for example, when the pattern of sound emission from the source is symmetrical.

The following requirements govern the number of side microphones,  $N_{\text{side}}$ , the number of top microphones,  $N_{\text{top}}$ , and the associated sub-areas:

a) 
$$N_{\text{side}} \ge \frac{H}{H_0}$$
 (B.7)

where  $H_0$  is set to 0,5 m to achieve adequate vertical sampling by limiting the spacing to 0,5 m or less.

b) 
$$N_{\text{side}} \ge 4$$
 (B.8)

c) 
$$N_{\text{top}} \ge \frac{R}{R_0}$$
 (B.9)

where  $R_0$  is set to 0,5 m to achieve adequate radial sampling by limiting spacing to 0,5 m or less.

d) 
$$N_{\text{top}} \ge 2$$
. (B.10)

The vertical side microphones are associated with equal sub-areas,  $S_i$ , where  $S_i = S_{\text{side}} / N_{\text{side}}$ , and positioned such that the *i*-th microphone is at a height, from the floor,  $h_i$ , given by Formula (B.11):

$$h_i = \frac{\left(i - \frac{1}{2}\right)H}{N_{\text{side}}}.\tag{B.11}$$

The mean time-averaged sound pressure level over the side vertical measurement surface,  $\overline{L_{p, \, \text{side}}}$  is given by Formula (B.12):

$$\overline{L_{p,\text{side}}} = 10 \lg \left( \frac{1}{N_{\text{side}}} \sum_{i=1}^{N_{\text{side}}} 10^{0,1L_{p,\text{side},i}} \right)$$
(B.12)

where  $L_{p, \text{side}, i}$  is the frequency-band time-averaged sound pressure level, in decibels, measured along the *i*-th microphone traverse or at the *i*-th microphone position on the side surface.

The top microphones are associated with unequal sub-areas,  $S_j$ , and are spaced equally along the radius of the top circular measurement surface. The outer radius of the j-th sub-area is given by Formula (B.13):

$$R_j = \frac{jR}{N_{\text{top}}} \tag{B.13}$$

and the position of each top microphone is given by Formulae (B.14) and (B.15):

$$r_i = R_{i-1} + (R_i - R_{i-1}) \text{ for } j > 1$$
 (B.14)

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and

$$r_1 = \frac{R_1}{2}$$
. (B.15)

The mean time-averaged sound pressure level over the top circular surface is given by Formula (B.16):

$$\overline{L_{p,\text{top}}} = 10 \lg \left[ \frac{1}{S_{\text{top}}} \sum_{j=1}^{N_{\text{top}}} S_j 10^{0,1L_{p,\text{top},j}} \right]$$
(B.16)

where

 $L_{p,\text{top},j}$  is the frequency-band time-averaged sound pressure level, in decibels, measured along the j-th microphone traverse or at the j-th microphone position on the top circular measurement surface.

 $S_{top}$  is the total area of the top circular measurement surface.

$$S_i = \pi (R_i^2 - R_{i-1}^2) \text{ for } j > 1$$
 (B.17)

$$S_1 = \pi R_1^2$$
 (B.18)

Figure B.2 illustrates an example of the cylindrical microphone array for five vertical side microphones and four top microphones.

# B.2.4 Calculation of the mean time-averaged sound pressure level over the cylindrical measurement surface

The mean time-averaged sound pressure level from the array of microphones over the cylindrical measurement surface, for the chosen mode of operation of the equipment under test, is given by Formula (B.19):

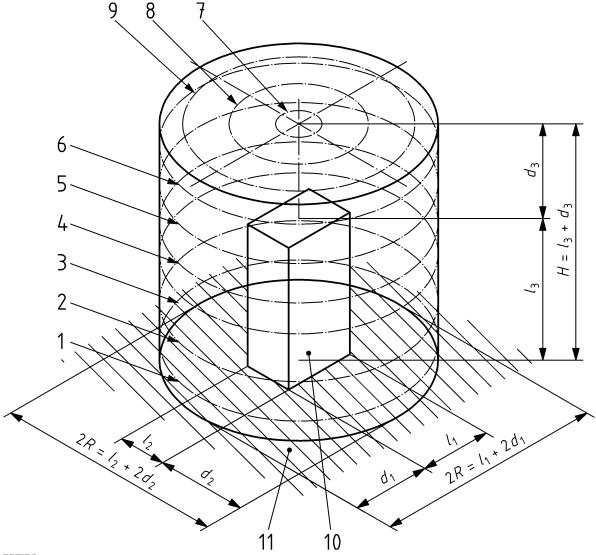
$$\overline{L_p} = 10 \lg \frac{1}{s} \left[ S_{\text{top}} 10^{0.1 \overline{L_{p,\text{top}}}} + S_{\text{side}} 10^{0.1 \overline{L_{p,\text{side}}}} \right]$$
(B.19)

where S,  $\overline{L_{p,\text{top}}}$  and  $\overline{L_{p,\text{side}}}$  are given by Formulae (B.1), (B.16) and (B.12), respectively.

NOTE 1 The quantity  $\overline{L_p}$  above is equivalent to the quantity  $\overline{L'_{p(\text{ST})}}$  in ISO 3744; i.e. the quantity that is subsequently corrected for background noise and the test environment before computing the surface time-averaged sound pressure level.

NOTE 2 Additional details about the cylindrical measurement surface can be found in References [25], [26] and [27].





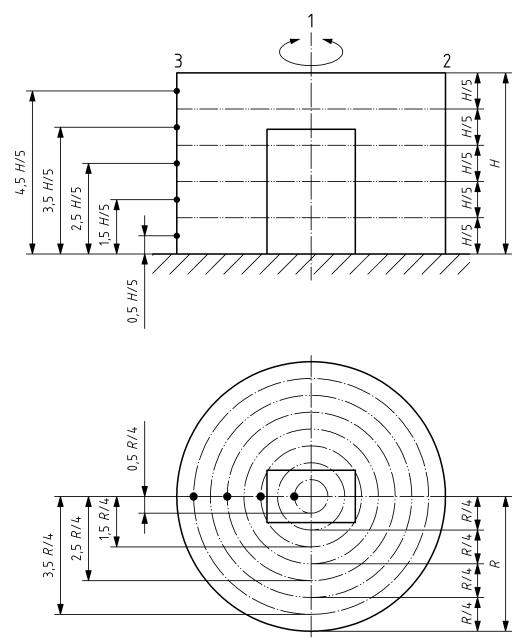
KEY	• •
1 to 6	side microphone paths
7 to 9	top microphone paths
10	reference box
11	reflecting plane
$d_1, d_2, d_3$	reference distances to the cylinder
H	cylinder height

 $l_1, l_2, l_3$  reference box dimensions

R cylinder radius

Figure B.1 — Example 1: Illustration of the cylindrical measurement surface and circular microphone traverses showing the arrangement using six side microphones and three top microphones.





# **KEY**

- 1 axis of rotation of microphone traversing mechanism
- 2 dimensions of corresponding areas of cylinder
- 3 locations of microphone traverses
- H cylinder height
- R cylinder radius

Figure B.2 — Example 2: Illustration of the cylindrical measurement surface and microphone array showing an arrangement using five side microphones and four top microphones.



# Annex C (normative)

# Installation and operating conditions for specific equipment categories

### C.1 General

This annex specifies installation and operating conditions for many specific categories of Information Technology and Telecommunication (ITT) equipment. During testing of such equipment, the specified conditions shall be satisfied in order to be in compliance with this Standard. In general, the conditions specified in this annex are considered to be typical of average end use. Because the noise emission levels of the equipment covered by this annex may vary significantly depending on how the equipment is installed and operated during the tests, the primary purpose of specifying the installation and operating conditions is to ensure that the acoustical measurements are taken uniformly across different laboratories testing the same type of equipment. Reported noise emission levels for ITT equipment measured in compliance with this Standard may then be compared or otherwise assessed without having to know the specific details of the installation and operating conditions used during the tests.

For categories of equipment not covered in this annex, the actual installation and operating conditions used during the test shall be described and justified (e.g., as to their representation of typical operating conditions) and test conditions used shall be described and justified (e.g., as to their representation of typical operating conditions) in the test report.

The operating conditions are strictly the same for the determination of both sound power levels and emission sound pressure levels at specified positions (see Clause 3 for definitions of these quantities).

The following categories of equipment are included:

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C.2	Typewriters
C.3	Character- and line-printers
C.4	Teleprinters
C.5	Keyboards
C.6	Copiers (duplicators)
C.7	Card readers and card punches
C.8	Magnetic tape units
C.9	Disk units and storage sub-systems
C.10	Visual display units and terminals
C.11	Electronic units
C.12	Microform readers
C.13	Facsimile machines (Telecopiers) and page scanners
C.14	Cheque processors
C.15	Personal computers and workstations
C.16	Single-function printers (SFP)
C.17	Self-service automatic teller machines
C.18	Rack-mountable units and rack-enclosed systems
C.19	CD- and DVD-ROM drives
C.20	Data projectors
C.21	Multi-function printers (MFP)
C.22	Hand-held computing and media playback devices
C.23	Digital media recorders and playback units for consumer use
C.24	Large format printers

For equipment capable of performing the functions of more than one category, for example printing and facsimile transmission, see 5.3.

When emission sound pressure level information is needed for the above categories of equipment, Table C.1 shall be used to determine whether an operator position or bystander positions measurements are required.



Table C.1 — Equipment measurement position(s) for the determination of emission sound pressure level  $^{\rm a}$ 

	Equipment categories	Operator position	Bystander positions
C.2	Typewriters	Х	
C.3	Character- and line-printers		X
C.4	Teleprinters		X
C.5	Keyboards	Χ	
C.6	Copiers (duplicators)		X
C.7	Card readers and card punches		X
C.8	Magnetic tape units		X
C.9	Disk units	X	
	Storage sub-systems		X
C.10	Visual display units and terminals	Χ	
C.11	Electronic units		X
C.12	Microform readers	Χ	
C.13	Facsimile machines (Telecopiers) and		X
	page scanners		
C.14	Cheque processors		X
C.15	Personal computers and workstations	Х	
C.16	Single-function printers (SFP)		X
C.17	Self-service automatic teller machines	X	
C.18	Rack-mountable units and rack-	Хp	Χþ
	enclosed systems		
C.19	CD- and DVD-ROM drives		
	- In case of use in end use equipment	X	
	- In case of sub-assembly		X
C.20	Data projectors		X
C.21	Multi-function printers (MFP)		X
C.22	Hand-held computing and media playback devices	X	
C.23	Digital media recorders and playback units for consumer use		Х
C.24	Large format printers		Х

<sup>&</sup>lt;sup>a</sup> Reporting emission sound pressure levels from other positions is optional.

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<sup>&</sup>lt;sup>b</sup> Either operator or bystander positions shall be used. Both operator and bystander positions may be used if desired. See C.18.1.



Fans, also called "air moving devices", are often incorporated into the design of ITT equipment to provide airflow for cooling. To measure such a fan as a component, for example as part of the process of selection for design use in a computer, refer to ISO 10302-1 and ISO 10302-2.



# C.2 Equipment category: Typewriters

# C.2.1 Description

This category covers equipment with a keyboard for manual information entry. The information is either keyed-in and immediately printed on paper character-by-character (manual typing), or keyed-in and stored for word or line editing with following automatic print-out (interactive operations). Typewriters which are equipped with a full-page storage are considered as typewriters during manual typing and as printers (see C.3) during automatic print-out on a full page.

#### C.2.2 Installation

### C.2.2.1 General

The typewriter shall be placed in the centre of the top plane of the standard test table. For measurements in accordance with Clause 7, the measurement surface terminates on the floor. Alternatively, the typewriter may be placed on a hard reflecting floor. The condition used shall be reported.

### C.2.2.2 Type font

If the typewriter allows the use of different type fonts or different type elements, a fine line typestyle (e.g. pica, elite, and not bold) shall be used with a character pitch of 10 characters per 25,4 mm.

### C.2.2.3 Paper

Single sheets of paper of grammage 70 g/m² to 80 g/m² in the ISO A4 or equivalent format shall be used unless the typewriter is designed for special paper having a different grammage. In this latter case, the special paper shall be used. Paper shall be inserted in vertical format with the left-hand edge at zero; the leading edge of the paper sheet shall be fed through to approximately one-third of the paper length, or 100 mm lower than the trailing edge (see Figure C.1). Paper shall have been stored unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2 or 8.3.2 as applicable, for at least 24 h immediately prior to the test.

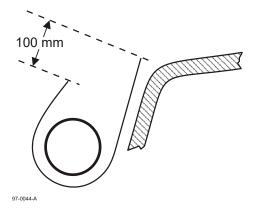


Figure C.1 — Insertion of single sheet of paper

### C.2.3 Operation

### C.2.3.1 Idle mode

The power shall be switched on. Paper shall be inserted in accordance with Figure C.1.

NOTE If the typewriter has both standby and ready mode, the idle mode corresponds to the standby mode.

If the typewriter has several idle modes, the mode(s) used for measurement shall be reported.

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### C.2.3.2 Typing mode

#### C.2.3.2.1 General

The typing mode consists of keying-in the specified character pattern and printing it on paper. Keying-in should preferably be performed with a suitable robot (see A.2) to simulate manual keystrokes. The noise level due to the operation of the robot alone shall be at least 6 dB and preferably more than 10 dB below the level of operation.

Typing shall start after the paper has been inserted, as specified in Figure C.1 and shall continue for not more than 100 mm.

NOTE If a typing robot is not available, manual typing may be used.

### C.2.3.2.2 Settings

The following settings, when applicable, shall be used.

- a) Impression control: as recommended for a single sheet of paper.
- b) Multi-copy control: set for a single sheet.
- c) Line spacing: double-line spacing.
- d) Margin: 25 mm from the edges; the end-of-line indicator (bell) shall be disconnected.
- e) Paperbail rollers: the paperbail rollers shall be set 25 mm from the edges of the paper; the others shall be equally spaced between.

### C.2.3.2.3 Character pattern

The test pattern characters shall be

etnaiv etnaiv etnaiv etnaiv...

and so on until a full printline of approximately 60 characters has been completed.

The single space between each group of six characters is required as part of the pattern. The carriage return after each line is part of the operation.

NOTE 1 A maximum of two characters may be replaced by other small letters, if there is a need for adjustment of the robot.

NOTE 2 Should small letters not be available, capital letters may be used instead; equivalent conditions may be selected for typewriters with non-Latin character sets.

# C.2.3.2.4 Operating speed

For manual operations the typing speed shall be five characters per second.

The specified characters shall be keyed in at a rate of five characters per second until the buffer is filled up; a maximum buffer capacity of one printline shall not be exceeded. The stored information shall then be immediately printed (maximum one line) at the maximum printing speed.

### C.2.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable, during the following operations.

For manual operations: measure during continuous typing over at least three full lines.



For interactive operations: measure during keying-in and printing-out until at least three full lines have been printed.

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# C.3 Equipment category: Character and line printers

# C.3.1 Description

This category covers electronically controlled equipment which prints stored information on paper in steps of character or line and is not normally keyboard-operated, and the noise output of which depends on the print pattern. The output may be obtained by means of impact printing (e.g. typebar-, train-, chain- or band-printers, printwheel, type-element or matrix printers) or by non-impact printing (e.g. electro-erosion or thermal printers) and excludes inkjet and laser printers.

For inkjet and laser printers, see C.16.

For equipment capable of printing on paper 420 mm or more in width, follow the procedures in C.24.

For equipment which offers print and any one or more of the following functions, follow the procedures in C.21 instead of the procedures in C.3:

- scan
- copy
- facsimile

### C.3.2 Installation

### C.3.2.1 General

Floor-standing printers shall be installed on the hard reflecting floor.

Printers which are normally placed on a special stand or table shall be installed on such a stand on the reflecting floor. Printers which are placed on an office table or desk and which take paper from, or stack paper on, the floor, shall, if possible, be placed in the centre of the top plane of the standard test table, using the floor to support the paper. For such measurements in accordance with Clause 7, the measurement surface terminates on the reflecting floor.

Table-top printers, which do not use the floor for the paper supply or exit stack, shall be placed on the hard reflecting floor for measurements in accordance with Clause 6 or Clause 7, and on the standard test table for measurements in accordance with Clause 8.

### C.3.2.2 Type style

For printers that support multiple type styles or type elements, a type style typical of normal use, with a pitch of 10 characters per 25,4 mm and 6 lines per 25,4 mm shall be used. If this is not possible, an adjustment as close as possible to these values shall be chosen. Condensed or extended characters shall not be used.

# C.3.2.3 Paper

Either single sheets of paper of grammage 60 g/m² to 80 g/m² or continuous, folded or rolled stationery of grammage 50 g/m² to 60 g/m² shall be used, unless the printer is designed for special paper having a different grammage. In this latter case, the special paper shall be used. The quantity of paper available for printing shall be as close as possible to the maximum capacity of the printer. The form width shall be the widest that is commonly available for the printer and shall be described in the test report. For special applications (e.g. when the material to be printed is a passbook or cheque) the material shall be typical for customer usage and shall be described in the test report.

Paper storage and unpacking shall follow the machine manufacturer's instructions. If there are no such instructions, paper shall have been stored unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2 or 8.3.2 as applicable, for at least 24 h immediately prior to the test.



# C.3.3 Operation

# C.3.3.1 Paper position

For continuous folded or rolled stationery, the paper length fed through the printer shall be at least ten times its width. For single sheet paper, the print area shall be vertically centred and span at least 60 % of the sheet length.

### C.3.3.2 Idle mode

Idle mode is a steady state condition that occurs after completion of print operation. Printers may have several idle modes, each with unique noise and duration, for example, step-down or variable speed cooling fan operation.

Idle noise shall be measured after print job completion with the power switch of the printer remaining on. The idle mode lasting at least one minute with highest noise emissions shall be measured and reported.

The measurement time interval of idle noise measurement shall be in accordance with C.3.4.

### C.3.3.3 Operating mode (Print mode)

#### C.3.3.3.1 General

Printers with single-sheet feeding devices shall be tested in best quality mode. Paper of size ISO A4 or of an equivalent format (portrait) is automatically fed.

Printers with continuous stationery shall be tested in draft mode with maximum paper width.

Printers capable of printing both single sheets of paper and continuous stationery shall be tested in both configurations.

The print mode consists of printing a character pattern specified in C.3.3.3.3.

For graphic printers whose print speed is specified in accordance with ISO/IEC 11160-1 while printing graphic mode in accordance with ISO/IEC 10561, a second operating mode shall be tested and reported: the second mode consists of printing the test pattern in ISO/IEC 10561:1999, Annex D.

# C.3.3.3.2 Settings

The following settings, when applicable, shall be used.

- a) Impression control: as recommended for a single sheet of paper.
- b) Multi-copy control: set for a single sheet.
- c) Line spacing: double-line spacing and skip 20 mm to 30 mm on each side of the paper fold.
- d) Margin: 25 mm from the edges (excluding the perforation strip) except when the printer characteristics restrict the available line length; in the latter case, typical margin length shall be used and reported.

# C.3.3.3.3 Character pattern

The full content of a 40-character test pattern is specified below. The character pattern shall be arranged in groups of five printed characters followed by five spaces. The position of the pattern should preferably be shifted by five characters on each line, using an end-around shift over the available line length. The printing area shall be left-justified and centred vertically. If the line comprises fewer characters, the left-most ones shall be used.

J1YY7 2DA90 8S8=2 6AI8Q B31AJ 5FTOE PG1TK X6D-4

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If some of the specified characters are not available, alternative characters of up to 20 % of the characters in one line may be substituted. For printers which print only non-Latin characters or numerical information a random set of characters or numbers shall be selected and reported.

NOTE The number of characters to be printed in one line depends on the printer itself and is specified in Table C.2. Examples of test patterns are shown in Figures C.2 and C.3.

### C.3.3.3.4 Operating speed

The rated speed for which the printer is designed shall be used. If several speeds are provided, the one which is typical for the majority of the uses shall be selected and described in the test report. Additional conditions may be specified for special applications and shall be described in the test report.

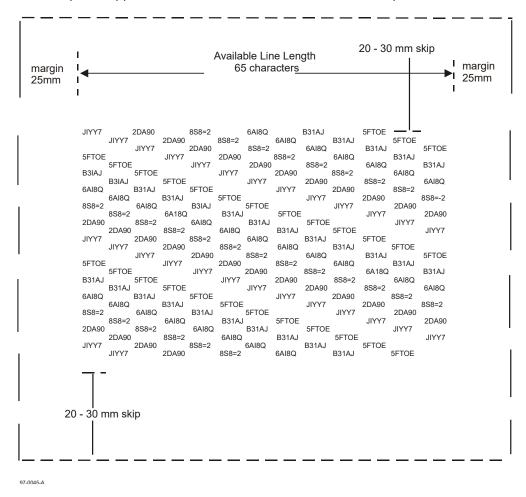


Figure C.2 — Example of the test pattern for a line length of 65 characters



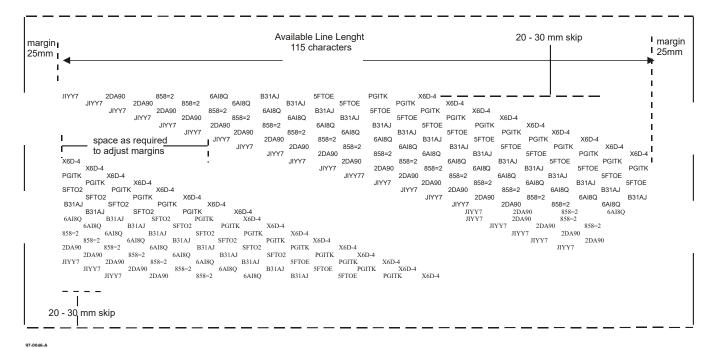


Figure C.3 — Example of the test pattern for a line length greater than 110 characters

Table C.2 — Number of characters to be used

Available line length in characters	Number of characters to be used
< 40	50 % of maximum line length between margins
40-59	20 characters
60-110	30 characters
> 110	40 characters

# C.3.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable, during the following operations:

- a) Single-page form: measure during continuous printing over at least 60 % of the page length; if the printer has an automatic paper feed mechanism, at least three pages shall be printed.
- b) Folded stationery: measure during continuous printing over at least three pages.
- c) Rolled stationery: measure during continuous printing over a length equal to at least the paper width.
- d) Passbook: measure during printing of a single line on the middle pages during a complete operation cycle from insertion to ejection (for details see C.17).



# C.4 Equipment category: Teleprinters

# C.4.1 Description

This category covers equipment operating as a send/receive machine basically comprising a keyboard, a printing unit, a mechanical or electronic send/receive unit (line control unit) and (integrated or optional) a memory unit (electronic, paper tape punch or reader, magnetic tape, disk or cassette).

Two typical uses are:

- a) Keyboard operation (when in local or transmission mode): the information is keyed-in by manual typing and immediately printed on paper and/or stored in the memory.
- b) Automatic operation (when in local or on-line mode): the machine prints automatically the information received from line network or from the memory unit.

When a teleprinter is fitted with an auxiliary unit which produces noise (e.g. paper tape punch/reader, magnetic tape, disk or cassette), the machine shall be tested with and without the unit in operation.

In some cases a teleprinter can be available in receive-only configuration (without keyboard). That machine is considered to be a character or line printer (in accordance with C.3).

#### C.4.2 Installation

#### C.4.2.1 General

For keyboard operation of the teleprinter, the general installation conditions for typewriters shall apply (see C.2).

For automatic operation of the teleprinter, the general installation conditions for printers shall apply (see C.3).

### C.4.2.2 Paper

Either single sheets of paper of grammage 70 g/m² to 80 g/m² or continuous, folded or rolled stationery of grammage 50 g/m² to 60 g/m² shall be used, unless the printer is designed for special paper having a different grammage. In this latter case, the special paper shall be used. The quantity of paper available for printing shall be as close as possible to the maximum capacity of the printer. The form width shall be the widest that is commonly available for the printer and shall be described in the test report. For special applications (e.g. when the material to be printed is a passbook or cheque) the material shall be typical for customer usage and shall be described in the test report.

If in typical use, multi-part stationery is employed, an additional test with such stationery shall be carried out and described in the test report.

Paper storage and unpacking shall be carried out in accordance with the machine manufacturer's instructions. If there are no such instructions, paper shall have been stored unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2 or 8.3.2 as applicable, for at least 24 h immediately prior to the test.

### C.4.3 Operation

#### C.4.3.1 Idle mode

The power shall be switched on and paper shall be inserted.

NOTE If the teleprinter has both standby and ready modes, the idle mode corresponds to the standby mode.



# C.4.3.2 Operating mode (Print mode)

For keyboard operation of the teleprinter, the operating conditions specified for keyboards shall apply (see C.5).

For automatic operation of the teleprinter, the operating conditions specified for printers shall apply (see C.3).

# C.4.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.

For keyboard operation of the teleprinter, the requirements specified for typewriters shall apply (see C.2.4).

For automatic operation of the teleprinter, the requirements specified for printers shall apply (see C.3.4).



# C.5 Equipment category: Keyboards

# C.5.1 Description

This category covers equipment for manual data entry fixed or connected (via a cable or other data transmission means) to other units, e.g. visual display units, computer console, hand-held calculator, etc.

#### C.5.2 Installation

Keyboards shall be installed in accordance with the relevant clauses of this Standard, except for measurements in accordance with Clause 6 or Clause 7. The keyboard may be placed in the centre of the top plane of the standard test table if required for operation, provided this is reported.

# C.5.3 Operation

### C.5.3.1 Operating mode (keying-in)

Keying-in shall be performed at a rate of five characters per second.

A suitable robot (see A.2) should be used to simulate manual keystrokes. The noise level due to the operation of the robot alone shall be at least 6 dB and preferably more than 10 dB below the level of operation.

If the keyboard has acoustical feedback, the minimum volume setting shall be used for the test.

NOTE If a typing robot is not available, manual keying-in may be used.

### C.5.3.2 Test pattern

- a) For alphanumeric keyboards, the test pattern shall be as specified for typewriters (see C.2.3.2.3).
- b) For numeric keyboards, the test pattern shall be four digits plus function key, the keys selected shall be reported.

# C.5.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable; the requirements specified for typewriters shall apply (C.2.4).

# C.5.5 Measurement uncertainty

The measurement uncertainty for determining noise emission levels for keyboard operation has not yet been verified and may be greater than those given in 6.2, 7.2 and 8.2.



# C.6 Equipment category: Copiers (duplicators)

# C.6.1 Description

This category covers equipment which can produce one or more copies from a master. Such equipment can be coupled with one or more additional attachments and features. These may be in the form of input, output or internal devices for a variety of copying needs. Input devices can be in the form of master document loading, handling and registering, or special paper feeders for continuous stationery or label printing. Output devices can be in the form of copy handlers such as sorters, automatic staplers, stackers and binders. The equipment may have an internal reversing device(s) for handling two-sided originals and producing two-sided copies; i.e. automatic duplexing. The copier may also offer full colour copying from full colour masters, or highlight colour copying.

For equipment which offers print and any one or more of the following functions, follow the procedures in C.21 instead of the procedures in C.6:

- scan
- copy
- facsimile

### C.6.2 Installation

#### C.6.2.1 General

Due to the nature of product operation, noise emitted by the copier in operating mode(s) may fluctuate significantly with time. Therefore, for this category of equipment, sound power level determination in accordance with Clause 6 (reverberation test room) may have restrictions to achieve reliable test results: only sound power level of repeated, or cyclic operations will be determined with the uncertainty stated, and a measurement time interval longer than that in free field over a reflecting plane may be required.

Floor-standing copiers shall be installed on the hard reflecting floor.

Copiers which are normally placed on a special stand or table shall be installed on such a stand or table on the reflecting floor. Copiers which are placed on a normal office table or desk and which take paper from, or stack paper on, the floor, shall, if possible, be placed in the centre of the standard test table, using the floor to support the paper. For such measurements in accordance with Clause 7, the measurement surface terminates on the reflecting floor.

Table-top copiers, which do not use the floor for the paper supply or exit stack, shall be placed on the hard reflecting floor for measurements in accordance with Clause 6 or Clause 7, and on the standard test table for measurements in accordance with Clause 8.

The same installation conditions shall be followed when the copier has attachments.

# C.6.2.2 Paper

Either single sheets of paper of grammage 60 g/m² to 80 g/m² or continuous, folded or rolled stationery of grammage 50 g/m² to 60 g/m² shall be used, unless the copier is designed for special paper having a different grammage. In this latter case, the special paper shall be used. The quantity of paper available for copying shall be as close as possible to the maximum capacity of the copier. The form width shall be the widest that is commonly available for the copier and shall be described in the test report. For special applications (e.g. when the material to be printed is a passbook or cheque) the material shall be typical for customer usage and shall be described in the test report.

Paper storage and unpacking shall be carried out in accordance with the machine manufacturer's instructions. If there are no such instructions, paper shall have been stored unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2 or 8.3.2 as applicable, for at least 24 h immediately prior to the test.



# C.6.3 Operation

#### C.6.3.1 Idle mode

Power shall be switched on and the copier shall be loaded with a suitable paper supply.

### C.6.3.2 Operating mode

#### C.6.3.2.1 General

The nominal speed for which the copier has been designed shall be used; if several speeds are provided, the one which is typical for the majority of the uses shall be employed. The copier shall be adjusted to normal exposure, and tests shall be carried out without using any reduction/enlargement facility, if provided.

Additional machine set-up conditions may be considered, as follows.

a) Copying without additional attachments

An operation cycle shall consist of continuously copying a single master.

b) Copying with additional attachments: input and output devices

When a copying system combines several features/attachments, a "full system" operation cycle shall comprise the use of the maximum number of features/attachments allowable at least once. This may include using all the features/attachments on the copier or just some of them. Where all the features/attachments cannot be used together in one operation cycle, several different operating combinations should be considered. The combination which is typical of use shall be selected and described in the test report.

### C.6.3.2.2 Input devices

### a) Automatic loading of originals

An operation cycle shall consist of placing five masters in the device input tray and making five copies of each master. Copies are ejected into a single stationery output tray.

#### b) Copying from continuous stationery

An operation cycle shall consist of feeding five pages of continuous stationery through the registering device and making five copies of each master. Copies are ejected into a single stationery output tray.

# C.6.3.2.3 Output devices

# a) Sorting

The operation shall start with an empty sorter. An operation cycle shall comprise the registering of one master and making five copies ejected into five consecutive sorter bins. (Any copies made during additional operation cycles shall be sorted into the same five consecutive bins.)

#### b) Stacking

If the copier is equipped with an integral mechanism to separate copy sets generated sequentially, it will generally be fitted with an input master loading device. The operation cycle shall comprise the placing of five originals into the device input tray and one copy of each shall be ejected into the stacker.

### c) Automatic stapling

Automatic stapling may be provided in the form of a separate output device, or being fitted as integral to a sorter or stacker. Copiers equipped with this device will generally be fitted with an input master loading device. The



operation cycle shall comprise the stapling of a set of copies from five masters for a total of five stapled sets, and ejected into the output tray.

# d) Copying on continuous stationery

An operation cycle shall comprise copying one master on five pages for folded stationery or a 2-m length for rolled stationery.

### e) Auxiliary equipment

If a copier is supplied with an accessory or integral equipment (e.g. a binder), the tests shall be carried out with and without the use of this equipment in the operation cycle.

# f) Two-sided copying

Copiers equipped with this feature can either

- 1) handle two-sided masters and produce from them one-sided or two-sided copies, or
- 2) handle one-sided masters only, and produce from them one-sided or two-sided copies.

Copiers equipped with this device will generally be fitted with an input master loading device.

An operation cycle for type 1) above shall comprise the making of two one-sided copies (one of each of the sides of the master) or one two-sided copy from one two-sided master. This operation cycle is to be repeated five times. An operation cycle for type 2) above shall comprise the making of one two-sided copy from two one-sided masters, this operation cycle is to be repeated five times.

# g) Colour copying

The operation cycle for copiers fitted with this feature shall be the copying from one one-sided full colour master; one copy is made and automatically ejected into a single stationery output tray.

# h) Highlight-colour copying

The operation cycle for copiers fitted with this feature shall be as for monochrome. (Copies should contain highlight-colour from a full text master, e.g. four lines in highlight-colour using the test pattern as specified in C.3).

# C.6.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least five operation cycles and for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.

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# C.7 Equipment category: Card readers and card punches

# C.7.1 Description

The category covers equipment which may perform a single function, such as reading the information from, or punching it into, a punched card. The two functions may also be combined in one machine which allows the use of both functions in one process or to use them separately. The number of cards processed per unit time depends for readers mainly on the nominal processing speed; for punches it may be significantly influenced by the total number of columns to be punched per card.

For equipment which performs similar functions such as card duplicating machines, card verifiers, card or document sorters and collators, code interpreters (with printing features), paper tape readers and punches, the following installation and operating conditions may also be applied.

### C.7.2 Installation

The equipment shall be installed in accordance with the relevant clauses of this Standard.

### C.7.3 Operation

### C.7.3.1 Idle mode

The power shall be switched on and the equipment shall be ready for reading or punching cards.

# C.7.3.2 Operating mode (Reading or punching mode)

If equipment of this category is capable of both reading and punching in one process, the operating mode shall consist of both punching and reading cards as specified below. If equipment allows only the use of these functions separately, the operating mode shall be punching.

The specified character pattern shall be read from, or punched into and/or read from, each card; approximately 40 % of the maximum number of columns (usually 80) shall contain information. The specified character pattern shall be arranged in groups of five characters followed by five spaces:

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# C.7.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable during processing of a random card deck of at least 10 cards.



# C.8 Equipment category: Magnetic tape units

# C.8.1 Description

This category covers equipment for writing on, and reading from, a magnetic tape wound on reels or within a cassette or a cartridge. A unit may contain one or more separately operable tape drives.

#### C.8.2 Installation

Installation shall be in accordance with the relevant clauses of this Standard.

### C.8.3 Operation

### C.8.3.1 Idle mode

#### C.8.3.1.1 Idle unloaded mode

The power shall be switched on and the tape shall not be in the tape path.

#### C.8.3.1.2 Idle loaded mode

The power shall be switched on and the tape shall be loaded and the equipment shall be ready to receive and respond to control line commands to any drive. In multiple drive units, all drives shall be loaded and ready.

### C.8.3.2 Operating modes

### C.8.3.2.1 General

One of the modes specified below shall be used as applicable.

In multiple drive units, only one drive shall be in operating mode; all other drives shall be in the idle loaded mode.

### C.8.3.2.2 Read/Write mode

Start, read or write, stop — with command timing for capstan (or equivalent) operation as follows.

Capstan on-time, in milliseconds, is set at the time needed to pass 130 mm of tape at the rated tape speed, s, and is defined as (130 [mm])/(s [m/s]) rounded to the nearest millisecond.

The off-time is equal to 0,7 to 1 times the on-time.

NOTE For a magnetic tape of 12,7 mm width, 130 mm of tape corresponds to a block length of 4 096 bytes at 32 bpmm. Higher densities should use correspondingly larger block sizes, such that the total on-time for all density machines will be approximately equal. At 63 bpmm, use a block length of 8 192 bytes; at 246 bpmm, use a block of 32 768 bytes.

### C.8.3.2.3 Streaming mode

Logical forward run while writing.

### C.8.4 Measurement time interval

The time-averaged sound pressure level shall be measured, for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable, for at least twenty consecutive start/stop operations in accordance with C.8.3.2.2 or streaming operations in accordance with C.8.3.2.3.



# C.9 Equipment category: Disk units and storage subsystems

# C.9.1 Description

This category covers equipment for writing on, and reading from, one or more rotating magnetic or optical disks. Disks may be removable or non-removable. Magnetic disks may be flexible or rigid. A unit may contain one or more separately operable disk drives.

NOTE For read-only optical disk drives (e.g. CD- and DVD-ROM drives), see C.19.

#### C.9.2 Installation

Installation shall be in accordance with 5.1 and 8.5. Disk units which form part of a personal computer, rack-mounted equipment, or hand-held computing and media playback device shall be tested in accordance with C.15, C.18 or C.22 as appropriate. Disk units which are tested as sub-assemblies shall be installed as sub-assemblies in accordance with 5.1.7.

### C.9.3 Operation

#### C.9.3.1 Idle mode

# **C.9.3.1.1** Idle ready

Disk(s) shall be loaded, power on, unit ready to receive and respond to control link commands with spindle up to speed and read/write heads in track-following mode.

For systems having a single drive, the drive shall be as described above. For systems with multiple drives or for storage subsystems, the number of drives that are simultaneously operable by the host CPU shall be operated as specified above. All other drives shall be in the idle mode typical of normal use for the system.

### C.9.3.1.2 Idle standby

If power-saving modes are available, such modes may be tested and if tested shall be described in the report.

#### C.9.3.2 Operating mode

For units having a single drive, the drive shall be operating as described below.

For units with multiple drives, or for storage subsystems, the number of drives that are simultaneously operable by the host CPU shall be operated as specified below. All other drives shall be in the idle mode, typical of normal use for the system.

Randomly select a cylinder/track to be sought in such a way that every cylinder/track has equal probability of being selected. (If the drive incorporates an algorithm to perform seeks in a more efficient non-random order, then this algorithm may be used. In this case the drive should be given a command or commands to read or write a random selection of files, and the drive algorithm will decide the order in which the commands are executed. The file length shall be adjusted to achieve the seek rate defined below). Seek to that track, then delay for a time period  $t_D$  achieving the required seek rate  $n_s$  within  $\pm$  10 % in accordance with the following formula:

$$n_{\rm S} = \frac{0.4}{t_T + t_L} \tag{C.2}$$

$$t_D = 1.5t_T + 2.5t_L \tag{C.3}$$

where



- $n_s$  is the average seek rate, expressed in seeks per second;
- $t_T$  is the manufacturer's published time, in seconds, to seek from one random track to another without including rotational latency;
- $t_L$  is the time, in seconds, for the drive to rotate by half a revolution.

Repeat the seek process. No other intentional delay while selecting the cylinder is allowed. The average number of seeks per second along with the seek algorithm shall be reported with the acoustical data.

If the drive is operating in a system and if the system is not capable of achieving the required seek rate, the drive shall be operated at the maximum seek rate achievable.

If the drive is operating in a multiple drive system in a Redundant Array of Inexpensive Disks (RAID) environment, the drive shall be operated at the maximum seek rate achievable compatible with the system RAID level in use.

# C.9.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.

NOTE Acoustical "beating" in multi-drive arrays can occur over periods of time that are long relative to the requirements of 6.7.2, 7.7.2 or 8.7.2. The resulting variation in sound pressure level at microphone positions can have a significant effect on the variability of A-weighted sound power level determined for the equipment. This variability can be reduced by increasing the measurement time to include several beating cycles.



# C.10 Equipment category: Visual display units and terminals

# C.10.1 Description

This category covers equipment which displays information on a screen, and which may be equipped with a keyboard for information entry. The keyboard may be fixed to the display unit or connected to it by means of a cable or other means of data transmission.

The units in this category may emit significant noise in the 16 kHz octave band. For equipment which emits sound in the 16 kHz octave band, the procedures specified in ECMA-108 for reporting sound power levels shall be used (see Table 4).

### C.10.2 Installation

Installation shall be in accordance with the relevant clauses of this Standard.

### C.10.3 Operation

#### C.10.3.1 Idle mode

The power shall be switched on and the equipment shall be in a steady-state condition, with air-moving device(s), if any, running and the representative pattern shall be displayed on the screen. The keyboard shall not be operated.

Preliminary tests should be run to determine if the emissions are significantly sensitive to the pattern displayed on the screen. If so, a pattern representative of maximum emission values for a typical user shall be determined. If not, the representative pattern shall be defined to be a full character set displayed on the screen and repeated until all positions on the screen are used. The representative pattern used shall be documented and reported.

# C.10.3.2 Operating mode (Typing mode), if applicable

The typing mode consists of keying-in the information specified for keyboards (see C.5).

### C.10.3.3 Power saving mode

If power saving modes are available, such modes may be tested in addition to the modes defined in C.10.3.1, described and reported.

# C.10.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.



# C.11 Equipment category: Electronic units

# C.11.1 Description

This category covers equipment such as processors, electronic memories and controllers, containing only electronic circuits, power supplies but no moving mechanical parts except those associated with cooling.

#### C.11.2 Installation

Installation shall be in accordance with the relevant clauses of this Standard.

# C.11.3 Operation

### C.11.3.1 Operating mode

Operate in the steady-state condition with normal load on all cooling devices, power supplies, and distributed power supply elements. For electronic units, the idle and operating modes are deemed to be the same.

# C.11.3.2 Power saving mode

If power saving modes are available, such modes may be tested in addition to the modes defined in C.11.3.1, described and reported.

### C.11.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.

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# C.12 Equipment category: Microform readers

# C.12.1 Description

This category covers equipment to display micro-images. Microform readers may differ from each other, depending on the different types of microforms to be used, such as microfiche, aperture cards and rollfilm.

#### C.12.2 Installation

Installation shall be in accordance with the relevant clauses of this Standard.

# C.12.3 Operation

### C.12.3.1 Idle mode

The power shall be switched on and the equipment shall be ready to display.

# C.12.3.2 Operating mode

The microform shall be inserted and the micro-image adjusted and displayed.

The following two operations may be performed with partial or full automation.

- Equipment for microfiche and aperture cards: the micro-image shall be adjusted in two diagonal corners by moving its support; an image shall be kept stationary.
- b) Equipment for rollfilm with a full reel of microfilm loaded into the device: the image approximately in the middle of the film shall be sought and adjusted; the rollfilm shall be transported automatically.

The operation used during the test shall be described in the test report.

### C.12.4 Measurement time interval

The time-averaged sound pressure level shall be measured for a minimum of three operation cycles and for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.



# C.13 Equipment category: Facsimile machines (telecopiers) and page scanners

# C.13.1 Description

### C.13.1.1 Facsimile machines

This category covers equipment operating as a send/receive machine, basically comprising a numeric keyboard, a paper feeding device, a scanner, a print unit and an electronic send/receive control unit. Telecopiers are used for transmitting text, drawings and graphic information via public transmission networks.

### C.13.1.2 Page scanners

This category covers equipment operating as a scanner which detects text, drawing and graphical information from full sheets of paper and comprises a paper feeding device and a scanning mechanism.

For equipment capable of print and any one or more of the following functions, follow the procedures in C.21 instead of the procedures in C.13:

- scan
- copy
- facsimile

#### C.13.2 Installation

#### C.13.2.1 General

Floor-standing machines shall be installed on the hard reflecting floor.

Machines which are normally placed on a special stand shall be installed on such a stand on the reflecting floor. Machines which are placed on an office table or desk and which take paper from, or stack paper on, the floor, shall, if possible, be placed in the centre of the top plane of the standard test table, using the floor to support the paper. For such measurements in accordance with Clause 7, the measurement surface terminates on the reflecting floor.

Table-top machines, which do not use the floor for the paper supply or exit stack, shall be placed on the hard reflecting floor for measurements in accordance with Clause 6 or Clause 7, and on the standard test table for measurements in accordance with Clause 8.

# C.13.2.2 Paper

For sheet stationery operations, sheet stationery of grammage 60 g/m² to 80 g/m² shall be used in accordance with machine manufacturer's instructions. A4 sheets shall be used whenever possible; otherwise, a sheet size characteristic of typical use shall be used.

For continuous stationery operations, continuous folded or rolled stationery of grammage  $50 \text{ g/m}^2$  to  $60 \text{ g/m}^2$  characteristic of typical use shall be used in accordance with machine manufacturer's instructions.

Paper storage and unpacking shall follow the machine manufacturer's instructions. If there are no such instructions, paper shall be unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2 or 8.3.2 as applicable, for at least 24 h immediately prior to the test.

The paper tray shall be filled as close as possible to its maximum capacity.

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# C.13.3 Operation

#### C.13.3.1 Idle mode

Idle mode is a steady state condition that occurs after completion of sending, receiving or scanning. Facsimile machines and page scanners may have several idle modes, each with unique noise and duration, for example, step-down or variable speed cooling fan operation.

Idle noise shall be measured after send, receive or scan job completion with the power switch of the machine remaining on. The idle mode lasting at least one minute with highest noise emissions shall be measured and reported.

The measurement time interval of idle noise measurement shall be in accordance with C.13.4.

### C.13.3.2 Operating modes

#### C.13.3.2.1 General

Machine operations shall use the pattern of Figure C.8. For monochrome printers, the monochrome mode shall be tested. For colour capable machine with different colour and monochrome speeds, both colour and monochrome modes shall be tested. For colour capable Machine with identical colour and monochrome speeds, the colour mode shall be tested.

NOTE The pattern in Figure C.8 is based on JBMS-74-1:2005<sup>[17]</sup>.

The default resolution and the default speed shall be used for all functions, whether monochrome or colour.

Operation of facsimile machine or page scanner shall begin after warm-up periods have expired and all moving parts are located in their home position.

### C.13.3.2.2 Operating modes

Send and receive operations shall be measured and reported for facsimile machines. Printing of transmission receipts shall be included if such printing is the default for send operation. Scan operation shall be measured for page scanners.

#### C.13.3.2.3 Single sheet machines

One-sided sheet operation shall be measured unless two-sided operation is the default, in which case two-sided operation shall be measured.

# C.13.3.2.4 Continuous folded or rolled stationery machines

One-sided operation shall be measured. A page shall consist of the test pattern of Figure C.8 scaled to fit to the maximum printable or scannable area of the machine, as appropriate to the operation.

### C.13.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.

- Single-sheet machines (equipped with feeding device): at least three (3) sheets
- Continuous folded or rolled stationery machines: at least one (1) page

These measurement time intervals are applicable to both send and receive operations of facsimile machines and scan operations of page scanners.



# C.13.5 Reporting

Noise emissions of idle and default operations shall be reported. Noise emissions of operations other than the default operations may be reported. The description "idle" shall accompany noise emissions reported for idle. The following shall accompany the noise emissions reported for operations other than idle:

- Operation: "scan", "facsimile send", "facsimile receive"
- Rendering: "mono" or "colour"
- Quality: "best", "normal", "draft", etc.
- Sidedness: "simplex" or "duplex"
- Input method: "ADF" or "flatbed"
- Media: format ("folded", "rolled" or "sheet"), "paper size" and "grammage"

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# C.14 Equipment category: Cheque processors

# C.14.1 Description

The category covers equipment which may perform a single function such as printing (or encoding) information onto cheques, reading information from cheques, printing lists, storing/retrieving information from a flexible disk cartridge, or sorting cheques.

#### C.14.2 Installation

#### C.14.2.1 General

The equipment shall be installed in accordance with the relevant clauses of this Standard.

### C.14.2.2 Paper

### C.14.2.2.1 Cheque stock

Typically, a large variety of cheque sizes and grammage of paper are used. To allow a standard method, the following specification defines the properties of the cheques to be used.

a) Length: 140 mm to 160 mm.

b) Height: 70 mm to 90 mm.

c) Grammage: 90 g/m<sup>2</sup> to 100 g/m<sup>2</sup>.

### C.14.2.2.2 Printer paper

If in typical use, multiple-part stationery is employed, an additional test with such stationery shall be performed and reported.

# C.14.3 Operation

# C.14.3.1 Idle mode

The power shall be switched on and the equipment ready for use (i.e. stand-by mode).

### C.14.3.2 Operating mode

When a cheque-processing system combines several features, a full system operation cycle shall comprise the use of each of those features at least once as described below under their respective operation cycle.

### a) Reading

Random alpha-numeric data shall be read from the cheques in this mode and any additional operations which typically form part or are a result of this mode shall be performed (e.g. autofeed, listing, storing on flexible disk cartridge and sorting cheques). Repeated read cycles shall be performed at a rate typical of that expected in use.

# b) Printing (or encoding)

Equipment of the type described in this category will in some cases contain a number of print mechanisms within one piece of equipment. The equipment shall be operated in a manner most typical of the expected use, with all print mechanisms operating in the proper sequence. Any additional operation which typically form part or result from this mode of operation shall be performed (e.g. autofeed, listing, storing on flexible disk cartridge



and sorting cheques). The information to be printed by each type of printing mechanism (where appropriate) is defined in Table C.3.

Repeated print cycle shall be performed at a rate typical of that expected in use.

# c) Printing (listing)

Repeated cycles of the character pattern shown below shall be printed at a rate typical of that expected in use. The full content of a 40-character pattern is given; if the line contains fewer characters, the left-most ones shall be used.

The characters shall be arranged in groups of five followed by five spaces and each subsequent line shall be rotated five spaces to the right.

J1YY7 2DA90 8S8=2 6AI8Q B31AJ 5FTOE PG1TK X6D-4

Any additional operations which typically form part or are a result of this mode shall be performed.

# d) Storing/retrieving from disk

Consecutive seeks shall be carried out to a random track. Any additional operations which typically form part or are a result of this mode shall be performed.

### e) Sorting

The cheques shall be sorted sequentially from the lowest numbered pocket to the highest numbered pocket and this sort pattern repeated as necessary for the measurement time interval.

Table C.3 — Cheque processor printer types and corresponding print patterns

Printer type	Characters to be printed Print details
Encoder	*000000085124* (amount field only)
Programmable endorser	J1YY7 2DA90 8S8=2 6AI8Q
Fixed endorser	any character

### C.14.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable. For the operating mode, the measurement time interval shall be at least that of eight complete operation cycles.

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# C.15 Equipment category: Personal computers and workstations

# C.15.1 Description

This category covers small systems such as personal computers, workstations and word processors, which include a keyboard, visual display unit, and a processor unit which itself may contain combinations of one or more flexible, rigid and/or optical disk drives, magnetic tape units or printers.

For equipment which emits sound in the 16 kHz octave band, the procedures specified in ECMA-108 for sound power levels shall be used (see Table 4).

#### C.15.2 Installation

The constituent units of the system may be tested individually and reported accordingly. In this case the installation conditions are as in 5.1, 8.5 and the relevant clauses of this annex.

Alternatively the equipment may be tested as a complete system. In this case for the measurement of sound power levels, the equipment shall be mounted on the hard reflecting floor and the setup used recorded.

For the measurement of emission sound pressure levels at operator position, the separate enclosures which comprise the system shall be arranged in a set-up that is typical of actual use. Solely table-top systems shall be installed on the standard test table with all equipment front faces parallel to the front edge of the table. A "flat" table-top system (i.e. the system's width is greater than its height) shall be centred left to right on the test table (Figure C.4a) if the system is intended to physically support a monitor, it shall be treated as a small tower table-top system for placement.

A small tower table-top system (system's height is greater than its width) shall be placed 0,05 m from the right edge of the test table (Figure C.4b). If a monitor is placed on the table alongside the small tower, then a gap of 0,05 m shall be left between the monitor and the small tower. The keyboard shall be 0,05 m from the front edge of the table. If the system has a detachable keyboard, the system shall be 0,30 m from the front edge of the table. The operator position microphone then is 0,25 m in front of the keyboard or 0,50 m from a system with a detachable keyboard in accordance with 8.6.2.

Notebook computers shall be centred left to right on the test table and placed 0,05 m from the front edge of the test table. It is recommended that the screens of notebook computers be adjusted to be perpendicular to an imaginary line passing from the microphone at the operator's position to the centre of the screen.

If parts of the system are floor-standing and others are table-top, the floor-standing equipment shall be installed on the floor to the operator's right of the test table and oriented such that the front face of the equipment is parallel to the front edge of the table and even with the table and in the same vertical plane (Figure C.4c). Equipment adjacent to the table shall be spaced 0,075 m away from the vertical plane formed by the edge of the top of the table. The table-top equipment shall be installed on the test table with all front faces parallel to the front edge of the table. For non-parallelepiped equipment, the orientation shall represent typical use and shall be documented in detail. If the processor is tested individually without the presence of keyboard or monitor, the processor shall be installed in accordance with this paragraph and Figure C.4a, C.4b, or C.4c.

All-in-one systems, where the display, processor, and storage functions are contained within a single unit, shall be placed on the test table in accordance with Figure C.4c and Figure C.4d; in the case of Figure C.4c, the all-in-one system shall be placed at the monitor position. The screen of an all-in-one system shall be aligned according to Figure C.4d or as close thereto as allowed by the design of the unit. The distance to the operator position shall be measured from the farthest forward portion of the system when the screen is aligned according to Figure C.4d.



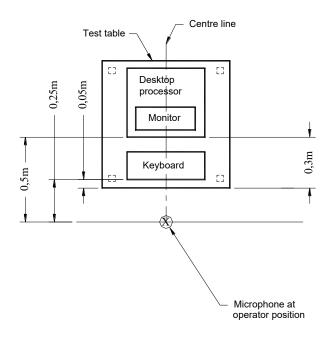


Figure C.4a — Installation for system comprising "flat" table-top equipment

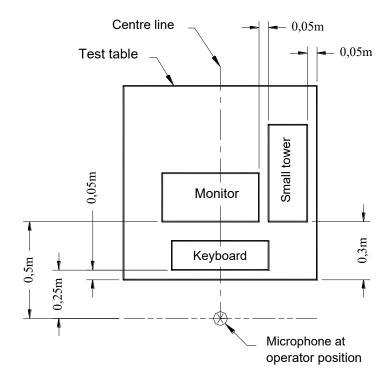


Figure C.4b — Installation for a small tower table-top system



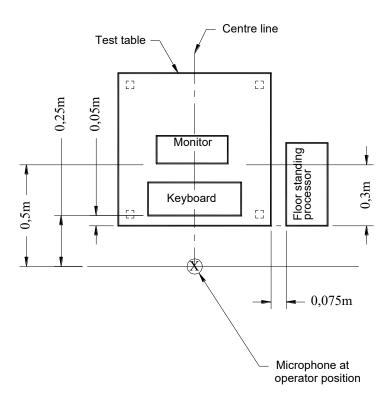


Figure C.4c — Installation for a floor standing system or all-in-one system (at the monitor location)

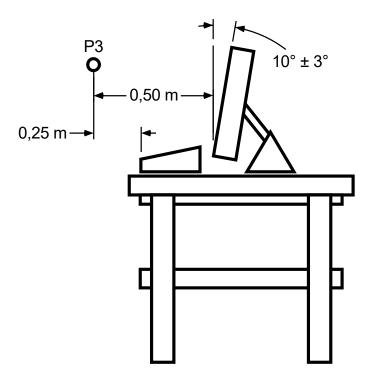


Figure C.4d — Screen angle for all-in-one system



# C.15.3 Operation

#### C.15.3.1 General

Operating conditions as required by 5.3 are described in this equipment category. Installation shall follow 8.5. The modes of operation were designed to represent typical use of the whole system.

NOTE 1 The operating modes in previous versions of this equipment category were defined in terms of operation of the individual subsystems rather than the whole system. Methods to measure such subsystems are still available in Annex C. For equipment with flexible disk drives and rigid disk drives as specified in C.9. For combinations of rigid and flexible disk drives, the operating mode is defined as one rigid disk drive operating, and all other drives idle as specified in C.9. For equipment with magnetic tape units as specified in C.8. For equipment with built-in character and line printers as specified in C.3; For equipment with optical drives as specified in C.19.

In addition to the idle mode specified in C.15.3.2, at least two (2) of the other operating modes as described C.15.3.3 shall be measured for the system under test. The operating modes selected shall represent the most common intended use cases for the system under test. The tested modes shall be reported, and workload details shall be documented as outlined in C.15.3.2 and C.15.3.3. The workloads in C.15.3.3 represent typical use for that operating mode, and they are relatively steady state in nature. If any of the specified workloads in C.15.3.3 are not officially natively supported for the system under test, a custom workload or script may be developed and used for that workload. Such a workload shall be similar in tasks, operations and sequence to the specified workloads, and the procedure shall be documented in the test report. Any such custom workload and/or scripts shall be made available for acoustic testing and verification purposes.

For each of the operating modes in C.15.3.3, an acoustical steady state should be attained before measurement. This generally coincides with thermal steady state, i.e., when air mover speed is stable. The system under test shall begin in an idle mode prior to running in each operating mode. Monitoring of acoustical output, air mover speeds and temperature sensors may be required to ensure such a steady state is attained.

NOTE 2 Generally, steady state may be attained by the third consecutive application of the operating mode workload.

NOTE 3 The system is made to idle before running each operating mode to approach system behaviour in a consistent manner with respect to a hysteresis or similar system control algorithms.

Because system performance and acoustic noise levels are correlated, the system power management and performance settings shall match the settings used to measure and report system performance. If no performance testing was done, factory defaults shall be used. If multiple factory default power management configurations exist, or if non-matching settings are used, the system power management and performance settings, as selectable by a consumer, shall be selected and reported.

#### C.15.3.2 Idle mode

Power shall be switched on, the equipment shall be in a steady-state condition, and the user shall have logged in with the screen displayed in its default settings and the system is ready to respond to user input.

### C.15.3.3 Operating mode(s)

### C.15.3.3.1 Web browsing mode

From idle operating mode, a web browsing application shall completely fill the display, not including any operating system control bar or menu bars, and by use of automated scripting, navigate to multiple popular websites. The browser shall have at least 6 tabs open with a mix of content, including news, social media, media streaming and a marketplace site. The script shall simulate user scrolling activity while viewing web content through short intermediate scroll inputs to mouse buffer, interspersed with clicks on links within pages, in a continuous loop to allow thermal stabilization of system on standard test table in chamber prior to acoustic measurement. Measurement is to be taken with web browsing automation script active. According to 5.3, audio playback shall be muted for measurement of noise emissions.



NOTE 3 Examples of websites include CNN, New York Times and Washington Post for news, Facebook and Twitter for social media, YouTube for media streaming, and Amazon for a marketplace.

### C.15.3.3.2 Office productivity

For this operating mode, the most recent version of PCMark or SYSmark Productivity suite shall be used. The test report shall indicate which of these workloads, and what version, was used. After running the suite multiple times, the workload shall be re-started and then the acoustical measurement is taken.

#### C.15.3.3.3 Media content creation

For this operating mode, the Cinebench R20 "all cores", SYSmark Creativity or Prime 95 suite shall be used. The test report shall indicate which of these workloads, and what version, was used. After running the suite multiple times, the workload shall be re-started and then the acoustical measurement is taken.

### C.15.3.3.4 Power user & gaming

For this operating mode, the 3DMark Timespy, Unigen Heaven or Luxrender suite shall be used. The test report shall indicate which of these workloads, and what version, was used. After running the suite multiple times, the workload shall be re-started and then the acoustical measurement is taken.

### C.15.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable. According to 5.3, the duration of the workload should be such that the measurement concludes before the workload ends.



# C.16 Equipment category: Single-function printers (SFP)

# C.16.1 Description

This category covers equipment which produces printed output from computers and includes inkjet (e.g. thermal- or piezoelectric- inkjet), laser and solid ink printers. SFP usually are graphic capable, may be duplex capable, and may have peripheral equipment such as staplers, binders, cutters, envelope feeders, sorters, and special paper feeders. For equipment capable of printing by mechanical impact, requiring temperature-sensitive or electro-erosion paper follow the procedures in C.3 instead of the procedures in C.16.

For teleprinters, see C.4.

For equipment capable of printing on paper 420 mm or more in width, follow the procedure in C.24.

For equipment capable of print and any one or more of the following functions, follow the procedures in C.21 instead of the procedures in C.16:

- scan
- copy
- facsimile

# C.16.2 Installation

#### C.16.2.1 General

Floor-standing printers shall be installed on the hard reflecting floor. Printers which are normally placed on a special stand or table shall be installed on such a stand or table on the reflecting floor. Printers which are placed on a normal table or desk and which take paper from, or stack paper on, the floor, shall, if possible, be placed in the centre of the top plane of the standard test table, using the floor to support the paper. For such measurements in accordance with Clause 7, the measurement surface terminates on the reflecting floor.

Table-top printers, which do not use the floor for the paper supply or exit stack, shall be placed on the hard reflecting floor for measurements in accordance with Clause 6 or Clause 7, and on the standard test table for measurements in accordance with Clause 8.

### C.16.2.2 Paper

For sheet stationery operations, sheet stationery of grammage 60 g/m² to 80 g/m² shall be used in accordance with machine manufacturer's instructions. ISO A4 sheets shall be used whenever possible; otherwise, a sheet size characteristic of typical use shall be used.

For continuous stationery operations, continuous folded or rolled stationery of grammage 50  $g/m^2$  to 60  $g/m^2$  shall be used in accordance with machine manufacturer's instructions, unless the printer is designed for special paper having a different grammage. In this latter case, the special paper shall be used.

Paper storage and unpacking shall follow the machine manufacturer's instructions. If there are no such instructions, paper shall be unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2, or 8.3.2 as applicable, for at least 24 h immediately prior to the test.

The paper tray shall be filled as close as possible to its maximum capacity.



# C.16.3 Operation

#### C.16.3.1 Idle mode

Idle mode is a steady state condition that occurs after completion of print operation. Page printers may have several idle modes, each with unique noise and duration, for example, step-down or variable speed cooling fan operation.

Idle noise shall be measured after print job completion with the power switch of the printer remaining on. The idle mode lasting at least one minute with highest noise emissions shall be measured and reported.

The measurement time interval of idle noise measurement shall be in accordance with C.16.4.

### C.16.3.2 Operating mode (Print mode)

### C.16.3.2.1 General

Printers shall be operated using the pattern of Figure C.8. For monochrome printers, the monochrome mode shall be tested. For colour capable printers with different colour and monochrome speeds, both colour and monochrome modes shall be tested. For colour capable printers with identical colour and monochrome speeds, the colour mode shall be tested.

NOTE The pattern in Figure C.8 is based on JBMS-74-1:2005<sup>[17]</sup>.

For printers whose maximum paper width capability is less than the A4 sheet width of 210mm, the print pattern of Figure C.8 shall be uniformly scaled to span the print area width. The print area width is the paper width reduced by the left and right margins, each of which may span up to 10% of the paper width.

The nominal default resolution and the nominal default speed shall be used for all functions, whether monochrome or colour.

One-sided printing shall be measured unless two-sided printing is the default, in which case two-sided printing shall be measured.

### C.16.3.2.2 Operation cycle with features

When a printing system combines several features, a full system operation cycle shall comprise the use of each of the features at least once as described under the respective operation cycle.

### a) Sorter

The sorting operation shall start with an empty sorter. An operation cycle shall comprise the sorting of one page in one bin. Pages printed during additional cycles shall be sorted into consecutive bins.

### b) Stacking

If the printer is equipped with an accessory or integral mechanism to separate jobs generated sequentially, an operation cycle shall comprise two jobs and print one page for each of them.

### c) Auxiliary equipment

If the printer is supplied with auxiliary equipment (e.g. a mechanism for cutting continuous forms), the tests shall be carried out with and without the use of such equipment in the operation cycle.

### C.16.4 Measurement time interval

For each set-up the time-averaged sound pressure level shall be measured, for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable, and as follows:



 Single sheet printers: at least three sheets (three pages) for one-sided simplex printing; at least three sheets (six pages) for two-sided duplex printing. Ramp-up and ramp-down motion before and after repetitive print cycles shall not be measured.

When the printer has a print carriage and spends over 30 seconds printing one sheet (e.g. printing at high quality mode) for one-sided simplex printing, it may be allowed that the measurement time interval is reduced to one sheet. In this case, it is recommended that the measurement time should extend from when one sheet has completed printing including being output to its paper tray until the next sheet is completely printed and output to its paper tray due to increase measurement reproducibility. However, if those printers have an overlap operation which overlapped the previous printed paper ejection and next paper feed, then the measurement time interval shall be three operation cycles as stipulated.

• Printing with auxiliary features: at least one (1) sheet.

# C.16.5 Reporting

Noise emissions of idle and default operations shall be reported. Noise emissions of operations other than the default operations may be reported. The description "idle" shall accompany noise emissions reported for idle. The following shall accompany the noise emissions reported for operations other than idle:

Operation: "print"

Rendering: "mono" or "colour"

• Quality: "best", "normal", "draft", etc.

Sidedness: "simplex" or "duplex"

Media: format ("folded", "rolled" or "sheet"), "paper size" and "grammage"



# C.17 Equipment category: Self-service automatic teller machines

# C.17.1 Description

The category covers equipment mainly used in banking environments and provides various services to customers, such as cash dispense, funds transfer between accounts, account balance inquiry, balance statement issuing and envelope deposit.

Depending on the purpose of the equipment, a variety of different functions can be performed and combined in one machine. Typical examples for operating modes are specified in C.17.3; it is not assumed that these conditions apply to all cases, therefore, the test conditions used shall be described in the test report.

### C.17.2 Installation

The equipment shall be installed in accordance with the relevant clauses of this Standard.

# C.17.3 Operation

#### C.17.3.1 Idle mode

The power shall be switched on and the equipment shall be ready for use.

# C.17.3.2 Operating mode

The operating mode which is typical for average customer usage shall be defined and reported. For some equipment, examples are defined as follows:

# a) Money dispenser

Operation comprises card insertion, key-in personal identification number (PIN), task selection (e.g. cash issue), selection of amount of money, issue card, open cash gate, issue cash, issue receipt and close cash gate.

# b) Passbook operation

Operation comprises

- insert passbook, read magnetic stripe data, key-in PIN, print one line in passbook, write and verify magnetic stripe data and issue passbook, or
- insert passbook, read magnetic stripe data, key-in PIN, task selection (e.g. cash issue), selection of amount, write and verify magnetic stripe data, issue passbook and issue cash.

# c) Banking information print-out

Operation comprises check card insertion, key-in PIN, task selection (e.g. statement of account), issue card, print output and issue output.

# d) Cash envelope deposit

Operation comprises card insertion, key-in PIN, task selection (e.g. cash deposit), key-in amount of deposit, insert envelope into depository device, remove card and receipt.

### C.17.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable. For the operating mode, an average value shall be determined for at least three typical transactions, during which manual access may be needed, which however shall not be intentionally delayed.



# C.18 Equipment category: Rack-mountable units and rack-enclosed systems

# C.18.1 Description

This category covers both rack-mountable units (see 3.1.13) and rack-enclosed systems (see 3.1.14).

Rack-enclosed systems take several forms, including single- and dual-rack enclosed systems. A system of rack-mountable units provided without rack/enclosure may be tested as individual units or as a rack-enclosed system. When tested as a rack-enclosed system, the individual units shall be assembled into a rack/enclosure according to manufacturer instructions.

For rack-enclosed systems that are available in more than one configuration of rack-mountable units, the particular configuration to be measured is usually governed by the purposes of the test and is thus not specified in this Standard. However, if the configuration has not been otherwise specified prior to the test, and if practical, it is recommended that a typical configuration be measured as a minimum, possibly supplemented by other identifiable configurations (e.g., minimum configuration or maximum configuration, or both). In any event, the configuration(s) of the system shall be described in the test report in sufficient detail to uniquely identify the unit under test.

For rack-mountable units and rack-enclosed systems, either the bystander or operator sound pressure level shall be measured and reported, see Table C.1. Operator positions are described in C.18.2.1 and C.18.2.2. Bystander positions and calculations are described in 8.6.3 and 8.8.3, respectively. Both the bystander and operator sound pressure levels, as well as sound pressure levels for multiple operator positions, may be reported if desired; see C.18.7.

NOTE Operator sound pressure level is representative of the noise experienced by personnel next to a rack-mountable unit or rack-enclosed system equipment for installation, configuration, maintenance, or service [77]. Measurement and reporting of operator sound pressure level is recommended when concern over noise level close to the equipment exists or when personnel approaching the equipment are likely to interact physically with the equipment.

### C.18.2 Installation

In general, the requirements of 5.1.1 and 5.1.5 shall be met. Specific installation requirements are given below.

Rack-mountable units that are not designed for a specific rack-enclosed system (e.g., units that may be used in a variety of industry-standard racks) shall be tested outside of a rack and treated as "sub-assemblies" for the purposes of this Standard (see 3.1.12 and 5.1.7).

NOTE 1 In addition to the above requirements, such units may optionally be tested installed in a rack in accordance with the following paragraphs.

Rack-mountable units that are designed as part of, or intended to be installed in, a specific rack-enclosed system shall be tested in that specific rack enclosure. The unit shall be installed as specified by the manufacturer or requestor of the test, including the vertical position in the rack enclosure. If no position is specified, the unit shall be mounted at approximately the same height as that required for sub-assemblies (see 5.1.7). If the specific rack enclosure is fully- or partially-enclosed, then all other positions in the rack shall either be filled with blank rack panels or populated with unpowered rack-mountable units. If the specific rack enclosure is of an open-frame design, then filling the empty positions in the rack is not required and the unit may be installed alone in the rack. Only the rack-mountable unit under test shall be powered on, and only the noise emission levels of this unit shall be reported, together with its position in the rack enclosure.

NOTE 2 Individual rack-mountable units should be installed no lower than the minimum height for subassemblies (see 5.1.7) [77].

If the above rack-mountable unit requires power, cooling, or other facilities from other units in the rack enclosure for its operation, then one of the following approaches shall be used.



- (i) The rack-mountable unit shall be measured along with the other units required for its operation and the results reported as the overall noise emission levels for the units taken together. The report shall describe the units that were tested together.
- (ii) The rack-mountable unit shall be measured along with the other units required for its operation and the results reported as an upper bound for the noise emission levels for the particular unit under test (e.g., when the levels of the auxiliary units are much lower than the unit under test). The report shall describe the units that were tested together.
- (iii) If practical, first the auxiliary units shall be measured together by themselves with the rack-mountable unit under test powered off, and second the measurement shall be repeated with the rack-mountable unit powered on. Appropriate computations (e.g., similar to the corrections for background noise in ISO 3741) shall be carried out to "subtract out" the noise level of the auxiliary units, and the results reported as an estimate for the noise emission levels for the particular unit under test. The report shall describe the units that were tested together and the procedure used to determine the estimated noise levels of the unit under test.

When measuring operator sound pressure level of rack-enclosed systems or rack-mountable units tested in rack-enclosed systems, any access doors or covers shall be opened or removed according to the manufacturer's instructions for servicing while the equipment remains operable. Any extendible components, assemblies, or subsystems on slide rails or equivalent shall be fully retracted.

### C.18.2.1 Operator positions for rack-mountable units

Rack-mountable units, including units treated as a subassembly according to 5.1.7, are tested in a 0.25m vibration isolating test stand or a rack-enclosed system, see Figure C.5.

Front and rear operator positions apply to rack-mountable units. The operator positions are centred across the width of the rack- mountable unit at a horizontal distance of  $0.50~\text{m} \pm 0.03~\text{m}$  from the nearest face of the unit (not the vibration isolating test stand or the rack) and vertically at the median height of the unit above the floor. See Figure C.5.



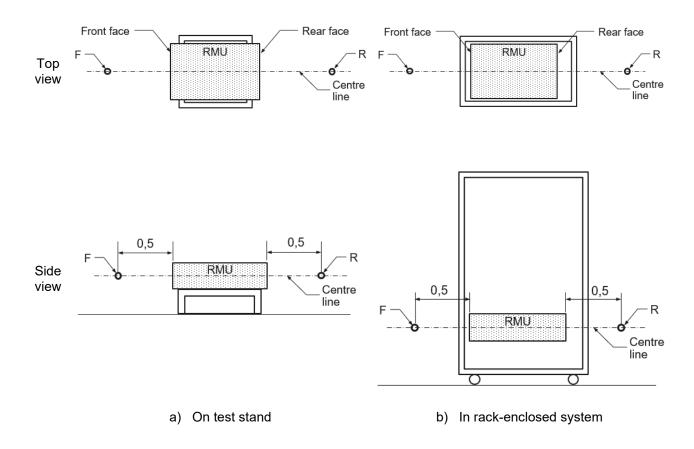


Figure C.5 — Front (F) and rear (R) operator positions for rack-mountable units (RMUs)

# C.18.2.2 Operator positions for rack-enclosed systems

Standing and crouched operator positions apply to each accessible face of a rack-enclosed system. The operator positions are centred across the width of the rack-enclosed system at a horizontal distance of 0,50 m  $\pm$  0,03 m from the nearest face of the rack-enclosed system (not the rack-mountable units within the system). The standing operator position is 1,50 m  $\pm$  0,03 m above the floor. The crouched operator position 1,00 m  $\pm$  0,03 m above the floor. See Figure C.6.

When multiple rack-enclosed systems are side by side, operator positions apply to each rack-enclosed system, as shown for the dual-rack configuration in Figure C.7.

NOTE: The number of operator positions for each rack-enclosed system ranges from two to eight, depending on the number of accessible faces. Rack-enclosed systems are typically accessible from their front and/or rear faces and sometimes from a side face.



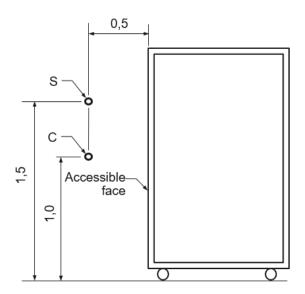


Figure C.6 — Standing (S) and crouched (C) operator positions for rack-enclosed systems

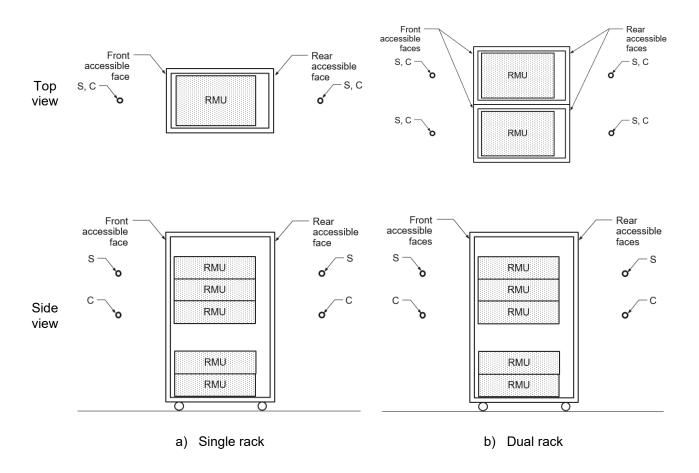


Figure C.7 — Examples of rack-enclosed systems containing rack-mountable units (RMUs) showing the standing (S) and crouched (C) operator positions



# C.18.3 Operation

In general, the requirements of 5.3 shall be met. Specific operating requirements are given below for the following modes of operation.

#### C.18.3.1 Idle mode

The power shall be switched on, and all rack-mountable units shall be in idle mode ready to receive command signals from the system CPU.

# C.18.3.2 Operating mode

The operating modes for the equipment covered by C.18.1 are defined as follows. The system under test shall begin in an idle mode prior to running in each operating mode.

NOTE 1 The system is made to idle before running each operating mode to approach system behaviour in a consistent manner with respect to a hysteresis or similar system control algorithms.

One or more of the following operating modes shall be used as applicable:

- For equipment with rigid and flexible disk drives as specified in C.9;
- For equipment with magnetic tape units as specified in C.8;
- For equipment with built-in character and line printers as specified in C.3; equipment with single-function printers as specified in C.16;
- For equipment with a central processing unit: the operating mode shall be the typical workloads described below to best represent the noise levels that a majority of customers may encounter. The central processing unit may include microprocessors, memory modules and add-in cards (for example, graphics card), herein referred to as "subsystems" of the central processing unit. If operation of a particular subsystem below does not result in an increase in fan speed(s) or an otherwise increase in noise level, that subsystem does not need to be tested. Operating of each subsystem shall follow:
  - Microprocessors subsystems: Typical workload of all microprocessors shall be taken as half of the maximum load using microprocessor centric performance testing applications. If multiple microprocessors are included in a central processing unit, this typical workload shall be evenly distributed across all microprocessors, as far as practical.
- NOTE 2 If load-scalable microprocessor-centric performance testing applications, such as Specpower, MaxPower or ThermNow are used, then the acoustic measurement should be done at the 50 % of the maximum load setting as specified above. However, if load non-scalable applications, such as Linpack and Prime95 are used, the load between maximum and idle may be modulated to approximate the 50% typical workload condition. Modulation should be adjusted such that a steady-state noise emission condition is measured.
  - 2) Memory subsystem: A memory subsystem consists of all memory modules within the central processing unit, whether installed on a motherboard, or via multiple riser cards. Typical workload for the memory subsystem shall be taken as half of the attainable platform performance bandwidth of the memory subsystem, with bandwidth equally distributed over all memory modules, as far as practical.
- NOTE 3 Attainable platform performance bandwidth may be obtained by running a load-scalable memory performance application at the maximum performance bandwidth setting. The acoustical testing should then be done at 50 % of this maximum performance bandwidth setting.
  - 3) Other identified subsystems: The workload for any other subsystem of the central processing unit not described above shall be representative of the typical end-use workload for that subsystem and clearly defined and documented in the report, if tested.



 For equipment with other components not listed above, the operating mode shall be representative of typical end-use operation for that component and clearly defined and documented in the report.

NOTE 4 Measurements on individual disk drives should be made at the seek rate typical of the multiple-drive configuration if system limitations do not allow the seek rate specified in C.9. This is necessary so as not to overestimate the system noise emission levels as calculated in accordance with C.18.5 from individual measurements.

#### C.18.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable, and as further required in this annex for the operation of the rack-mountable units.

# C.18.5 Calculation of the system A-weighted sound power level and system A-weighted emission sound pressure level from individual rack-mountable unit sound levels

The system A-weighted sound power level, in decibels, shall be calculated using the following formula:

$$L_{WA,SVS} = 10 \lg \sum_{i=1}^{n} 10^{0.1 L_{WAi}}$$
 (C.4)

where

 $L_{WA,sys}$  is the system A-weighted sound power level, in decibels;

 $L_{WAi}$  is the A-weighted sound power level of the *i*-th rack-mountable unit installed in a rack enclosure;

n is the number of rack-mountable units.

The system A-weighted emission sound pressure level, in decibels shall be calculated using the following formula:

$$L_{p\text{A.SVS}} = 10 \lg \sum_{i=1}^{n} 10^{0.1 L_{p\text{A}i}}$$
 (C.5)

where

 $L_{pA,sys}$  is the system A-weighted emission sound pressure level, in decibels;

 $L_{pA_i}$  is the A-weighted emission sound pressure level of the *i*-th rack-mountable unit installed in a rack enclosure;

*n* is the number of rack-mountable units installed and tested.

NOTE The calculations in C.18.5 may be used by enclosures other than "rack enclosed systems", such as, a server, PC, or storage arrays. In this case the individual units are "sub-assemblies" instead of "individual rack-mountable units" in C.18.5.

# C.18.6 Calculation of A-weighted sound power level and A-weighted emission sound pressure level for low noise level rack-mountable units

In some cases the noise level of rack-mountable units may be within 6 dB of the background noise level which would preclude an accurate value if measured individually. In this case enough identical rack-mountable units shall be tested and measured in the enclosure, so that the noise level of the n rack-mountable units is sufficiently greater than the background noise level (it may be convenient to test the maximum number allowed).

The rack-mountable unit A-weighted sound power level, in decibels, shall be calculated from the following formula:

$$L_{WA,s} = L_{WA,sn} - 10 \lg n \tag{C.6}$$



#### where

 $L_{WA,s}$  is the averaged individual rack-mountable unit A-weighted sound power level, in decibels;

 $L_{WA,s_n}$  is the total A-weighted sound power level for n identical installed rack-mountable units, in decibels;

n is the number of rack-mountable units installed and tested.

The rack-mountable unit A-weighted emission sound pressure level, in decibels, shall be calculated from the following formula:

$$L_{pA,s} = L_{pA,sn} - 10 \lg n \tag{C.7}$$

where

 $L_{pA,s}$  is the rack-mountable unit A-weighted emission sound pressure level, in decibels;

 $L_{pA,sn}$  is the total A-weighted sound pressure level for n identical installed rack-mountable units, in decibels:

*n* is the number of rack-mountable units installed and tested.

NOTE The calculations in C.18.6 may be used by enclosures other than "rack enclosed systems", such as, a server, PC, or storage arrays. In this case the individual units are "sub-assemblies" instead of "individual rack-mountable units" in C.18.6.

## C.18.7 Reporting

All reported operations shall be clearly described. Sound power level and either bystander sound pressure or operator sound pressure shall be reported. If desired the bystander and operator sound pressure levels may both be reported.

For bystander sound pressure level, the mean emission sound pressure level shall be reported. Bystander microphone positions and calculations are defined in 8.6.3 and 8.8.3, respectively.

For operator sound pressure level, the highest sound pressure level measured at the operator positions described in C.18.2.1 and C.18.2.2 shall be reported, as applicable to rack-mountable units or rack-enclosed systems. If desired, the sound pressure level at multiple operator positions may additionally be reported.

NOTE It is recommended to report the highest operator sound pressure level at each accessible face.



## C.19 Equipment category: CD-and DVD-ROM drives

### C.19.1 Description

The category covers equipment for reading electronic information from a rotating read-only optical disk (for example, CD-ROM or DVD-ROM) or other optical media operated in a substantially sequential access manner.

#### C.19.2 Installation

#### C.19.2.1 General

Installation shall be in accordance with 5.1 and 8.5. A drive which forms part of a personal computer or rack mounted equipment shall be installed in accordance with C.15 or C.18 as appropriate. A drive which is tested as a sub-assembly shall be installed as a sub-assembly in accordance with 5.1.7.

#### C.19.2.2 Media

The unbalance  $U_d$  of test media, defined in the following formula, shall be 2,5 g·mm ± 10 %.

$$U_d = m_d \cdot r \tag{C.8}$$

where

 $m_d$  is the mass of the disk, in grams (g),

r is the distance between the centre of gravity and the geometrical centre of the disk, in millimetres (mm)

NOTE 1 More detailed and specific information on the disk media is available in Reference [30]. Since (1) the measurement of unbalance is not an objective of this Standard, (2) test media satisfying this requirement is commercially available from several sources<sup>2</sup>, and (3) it is not possible for most users of this Standard to adjust media to meet the criteria for unbalance, while they can only measure the value, it is recommended to use a dedicated test media which has the unbalance specified above.

NOTE 2 This media unbalance requirement is based on several considerations as follows: C.1 requires that the operation be "typical of average end use". Conditions are to be "specified with a view to facilitate the operation of the equipment and to enhance the reliability of the acoustical measurements". The disk unbalance of 2,5 g-mm  $\pm$  10 % is specified as "typical of average end use" and is also consistent with reliable acoustical measurements, since this degree of unbalance avoids causing some drives to slow down. Technical details justifying this are contained in Reference [31].

### C.19.3 Operation

### C.19.3.1 Idle mode

Except for short-duration transients, idle modes are considered non-rotational and inaudible. Therefore measurement of the idle mode is not required.

In cases where the drive under test incorporates cooling assemblies for its normal operation, the cooling noise shall be measured as a part of noise of the drive.

## C.19.3.2 Operating mode

For units having a single drive, the drive shall be operating as described below.

<sup>&</sup>lt;sup>2</sup> For instance, Almedio, 2-32-13 Sakae-cho, Higashimurayama, Tokyo, Japan, offers such disks (http://www.almedio.co.jp).



For units with multiple drives the number of drives that are simultaneously operable by the host CPU shall be operated as specified below. All other drives shall be in the idle mode, typical of normal use for the system.

Start sequential read at the inner radius of the disk (or media) such that the disk spins continuously at the fastest speed sustainable with the specified media. Repeat the above read process until the measurement time interval specified in C.19.4 elapses.

## C.19.4 Measurement time interval

The time-average sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.



## C.20 Equipment category: Data projectors

## C.20.1 Descriptions

This category covers equipment driven by a computer input signal, for making an image projection, and by using a built-in light valve (see Definition C.1) or other technology.

This category does not cover equipment that is intended or designed for permanent outdoor installation.

The equipment may also have video input, but equipment having only video input is excluded.

#### **Definition C.1** light valve

a sub-system or key component of a projector which builds up an optical image from that produced electrically within the image displaying element, by casting light from another light source

NOTE Still-projectors for film media (e.g. slide, OHP etc.) are covered by ISO 10996<sup>[5]</sup>.

#### C.20.2 Installation

#### C.20.2.1 General

The equipment shall be installed in accordance with the relevant clauses of this Standard (i.e., 5.1 and 8.5 as applicable).

If the projector under test can make both front and rear screen projection (see Definitions C.2 and C.3), front screen projection configuration is applicable.

## **Definition front screen projection**

image projected on the audience side of a light-reflecting screen

## Definition C.3 rear screen projection

image projected through a light transmitting screen to the audience side of the screen

NOTE Definitions C.2 and C.3 above are consistent with those specified in IEC 61947-1:2002 and IEC 61947-2:2001, respectively.

## C.20.2.2 Warm up time

The equipment shall be operated for a sufficient period of time before proceeding with the acoustical test to allow the temperature to stabilize. If this time is unknown, the equipment shall be operated at least 30 min before the acoustical test.

### C.20.2.3 Special considerations for test personnel safety

Due to the nature of these products, a data projector emits a strong light beam. Therefore, it is necessary to pay special attention to protect the test personnel's eyes.

For the purposes of this Standard, it is strongly recommended to switch the lamp off while positioning the microphones.



## C.20.3 Operation

#### C.20.3.1 General

For the operation of this category of equipment (including idle mode), the lamp on or off are expressions based on light valve technology. For projectors based on other technology, the corresponding operations are to be defined in a similar manner to those contained below.

#### C.20.3.2 Idle mode

A stable condition in which the equipment is powered, but the lamp is not on. Transient periods, such as that immediately after switching the lamp off, are excluded. For some projectors, operation during idle mode may not be possible in which case noise measurements are not required.

#### C.20.3.3 Operating mode

A stable condition in which the equipment is powered with the lamp on. For the purposes of this Standard, if the noise emissions are dependent upon the image projected, the equipment shall project the image of Figure A.1 of IEC 61947-1:2002 or of Figure A.1 of IEC 61947-2:2001, as applicable.

NOTE IEC 61947-1 and IEC 61947-2 are applicable to projectors with fixed and variable resolution respectively.

Transient periods, such as those immediately after switching the lamp on, are excluded.

#### C.20.4 Measurement time interval

The time-averaged sound pressure levels shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.



## C.21 Equipment category: Multi-function printers (MFP)

### C.21.1 Description

This category covers equipment capable of print and any one or more of copy, scan and facsimile functions defined in C.3, C.6, C.13 and C.16. MFP may be monochrome or colour capable, or both, and may be duplex capable. MFP may have an automatic document feeder (ADF) for loading masters and output devices such as stackers, sorters, staplers, binders and cutters, which are either included in the standard product configuration or are optionally purchased.

For equipment capable of printing on paper 420 mm or more in width, follow the procedures in C.24.

#### C.21.2 Installation

#### C.21.2.1 General

The MFP shall be installed in accordance with its standard product configuration. Optionally purchased peripheral devices are not considered to be part of the standard product configuration.

Floor-standing MFP shall be installed on the hard reflecting floor.

MFP which are normally placed on a special stand or table shall be installed on such a stand or table on the reflecting floor. MFP which are placed on a normal table or desk and which take paper from, or stack paper on, the floor, shall, if possible, be placed in the centre of the top plane of the standard test table, using the floor to support the paper. For such measurements in accordance with Clause 7, the measurement surface terminates on the reflecting floor.

Table-top MFP, which do not use the floor for the paper supply or exit stack, shall be placed on the hard reflecting floor for measurements in accordance with Clause 6 or Clause 7, and on the standard test table for measurements in accordance with Clause 8.

#### C.21.2.2 Paper

For sheet stationery operations, the paper of grammage 60 g/m² to 80 g/m² shall be selected in accordance with the machine manufacturer's instructions. ISO A4 sheets shall be used whenever possible; otherwise, a sheet size characteristic of typical use shall be used.

Paper storage and unpacking shall follow the machine manufacturer's instructions. If there are no such instructions, paper shall be unpacked and exposed to the environmental conditions specified in 6.3.2, 7.3.2 or 8.3.2 as applicable, for at least 24 h immediately prior to the test.

The paper tray shall be filled as close as possible to its maximum capacity.

#### C.21.3 Operation

#### C.21.3.1 Idle mode

Idle mode is a steady state condition that occurs after completion of print or copy operation. MFP may have several idle modes, each with unique noise and duration, for example, step-down or variable speed cooling fan operation.

Idle noise shall be measured after print or copy job completion with the power switch of the MFP remaining on. The idle mode lasting at least one minute with highest noise emissions shall be measured and reported.

The measurement time interval of idle noise shall be in accordance with C.21.4.



### C.21.3.2 Operating modes

#### C.21.3.2.1 General

MFP operations shall use the pattern of Figure C.8. For monochrome printers, the monochrome mode shall be tested. For colour capable MFP with different colour and monochrome speeds, both colour and monochrome modes shall be tested. For colour capable MFP with identical colour and monochrome speeds, the colour mode shall be tested.

NOTE The pattern in Figure C.8 is based on JBMS-74-1:2005<sup>[17]</sup>.

The nominal default resolution and the nominal default speed shall be used for all functions, whether monochrome or colour.

Operation of MFP shall begin after warm-up periods have expired and all moving parts are located in their home position.

#### C.21.3.2.2 Output devices

Standard output devices shall be included in the standard product configuration for measurement.

Output devices shall be empty at the start of the measured operation.

Standard output devices representative of typical use shall be operated. If several output devices are standard, the combination of output devices representative of typical use shall be used. Output devices are used as follows:

- Binder (Stapler): An operation involves the binding (stapling) of a set of pages.
- Sorter: An operation involves ejecting pages into consecutive sorter bins.
- Stacker: An operation involves ejecting pages into a stacker.

## C.21.3.2.3 Modes of operation

At least, one mode shall be chosen and measured according to manufacturer's instruction. If there are no such instructions, at least mode a) shall be measured.

The remaining mode(s) are optional and may be measured at the discretion of the equipment manufacturer.

## a) Print

One-sided printing shall be measured unless two-sided printing is the default mode, in which case two-sided printing shall be measured.

## b) ADF copy

ADF copy shall be measured only if scanning and printing are simultaneous over some part of the copy operation. For ADF equipped MFP that simultaneously scan masters and print copies, the making of one-sided copies from one-sided masters shall be measured unless two-sided copying is the default, in which case default two-sided copying mode shall be measured. In either case, one copy shall be made for each master.

#### c) ADF scan

The ADF shall be operated while scanning. The registration of one-sided masters shall be measured unless two-sided registration is the default, in which case two-sided scanning shall be measured. The default scan resolution and the default electronic output format shall be used.



#### d) Flatbed copy

The making of a single one-sided copy from a single master involves placing a master on the flatbed of the MFP with cover closed against the master. The flatbed copy operation includes all events related to registration of the master and generation of a single copy, from start of registration to delivery of the copy.

#### e) Flatbed scan

The making of a single one-sided scan from a single master involves placing the master on the flatbed of the MFP with cover closed against the master. The flatbed scan operation includes all events related to registration of the master, from start to finish.

## f) Miscellaneous operations

Various operations may be measured at the discretion of the test requestor. Examples include:

- Alternative media, e.g. heavy paper, envelopes and transparencies
- Duplex printing, copying and scanning
- Standard output devices not representative of typical use
- Optional (non-standard) output devices
- Optional (non-standard) input devices like high capacity input trays

#### C.21.4 Measurement time interval

The time-averaged sound level shall be measured at least for the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable for the modes of operation described in C.21.3, as follows.

- <u>Print, ADF copy, and ADF scan</u>: at least three sheets (three pages) for one-sided simplex operations; at least three sheets (six pages) for two-sided duplex operations. Ramp-up and ramp-down motion before and after repetitive cycles shall not be measured.
  - When the printer has a print carriage and spends over 30 seconds printing one sheet (e.g. printing at high quality mode) for one-sided simplex printing, it may be allowed that the measurement time interval is reduced to one sheet. In this case, it is recommended that the measurement time should extend from when one sheet has completed printing including being output to its paper tray until the next sheet is completely printed and output to its paper tray due to increase measurement reproducibility. However, if those printers have an overlap operation which overlapped the previous printed paper ejection and next paper feed, then the measurement time interval shall be three operation cycles as stipulated.
- <u>Flatbed copy and Flatbed scan</u>: at least one (1) sheet. When a flatbed operation involving one sheet does not fulfill the measurement time interval, additional flatbed operations shall be measured such that the sum of the durations of the individual operations fulfills the required measurement time interval. Flatbed noise emission levels, *L* are computed as follows:

$$L = 10 \lg \left[ \frac{1}{T_{\text{tot}}} \sum_{i=1}^{k} (T_i 10^{0.1L_i}) \right]$$
 (C.9)

## where

- $T_i$  and  $T_i$  are the duration and noise emission level (sound power level or emission sound pressure level) of i-th individual flatbed copy operation,
- k is the number of repeated flatbed operations (i = 1, 2, ...k), which satisfies the measurement time interval requirement of 6.7.2, 7.7.2 or 8.7.2 as applicable,
- $T_{\rm tot}$  is the total measurement time interval of repeated flatbed operations;  $T_{\rm tot} = \sum_{i=1}^{k} T_i$ .

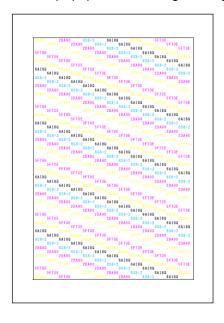


• <u>Miscellaneous operations involving output devices</u>: five (5) sets of "N" sheets, where "N" is at least three and enough to fulfill the required measurement time interval.

## C.21.5 Reporting

Noise emissions of the idle and default operations shall be reported. Noise emissions of operations other than the default operation may be reported. For the idle operation, only the operation description "idle" need be provided. For operations other than idle, the following information shall accompany the noise emissions:

- Operation: "print", "copy" or "scan"
- Rendering: "mono" or "colour"
- Quality: "best", "normal", "draft", etc.
- Sidedness: "simplex" or "duplex"
- Input method: "ADF", "flatbed", "high-capacity", etc.
- Output devices: "binder", "stapler", "sorter", "stacker", etc.
- Media: format ("folded", "rolled" or "sheet"), "paper size" and "grammage"



Colour

(https://www.ecma-international.org/wp-content/uploads/colour\_pattern.pdf)

Figure C.8 — Monochrome/colour pattern for noise emission testing of MFP (not to scale)

NOTE Figure C.8 was previously Figure C.5b.



## C.22 Equipment category: Hand-held computing and media playback devices

### C.22.1 Description

This category covers hand-held equipment for computing, office productivity software, internet browsing, digital media playback, and similar functions. Devices may run a general purpose operating system or be optimized solely for one or more of the functions listed above. Devices may be held in one or both hands during typical usage, and do not have a keyboard large enough for touch-typing.

Ultra-mobile PCs (UMPC), hand-held MP3 players, tablet or slate devices, and hand-held digital video players come under the scope of this category. Hand-held optical disk players do not come under the scope of this category.

Equipment lacking both air-moving devices and hard disk (rotating media) storage need not be measured or reported.

#### C.22.2 Installation

The device shall be installed in accordance with 5.1.6, 8.5 and 8.6.1.

## C.22.3 Operation

#### C.22.3.1 General

Operation of the equipment shall be in accordance with 5.3 and 8.5 for the following modes of operation.

Intentional sound, such as music, speech, or user interface sounds, shall not be included in equipment operations.

### C.22.3.2 Idle mode

Power shall be switched on, and the equipment shall be in a steady-state condition, including thermal equilibrium with the environment. Disk drives shall be in the idle ready mode as defined in C.9.3.1.1, and the standard user interface shall be displayed on the screen. Any air-moving device(s) shall be running as needed to cool the steady-state condition.

If power saving modes are available, such modes may be tested in addition to the above idle mode, and shall be described in the test report, if measured.

#### C.22.3.3 Operating mode(s)

One or more of the following operating modes shall be used where applicable. Noise due to keyboard operation shall not be included. Any air-moving device(s) shall be running as needed to cool the operating mode at steady state.

- a) Equipment with rigid disk drives as specified in C.9.3.2.
- b) Running a typical workload. For computing devices this may be running office productivity software or rendering web pages. For digital media playback devices, this may be playing a video file (if capable of doing so) or audio file, but with no intentional sound output.

#### C.22.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.



## C.23 Equipment category: Digital media recorders and playback units for consumer use

## C.23.1 Description

This category covers systems used to record digital media contents in the form of audio visual signals from a commercial source such as (but not limited to) cable TV or satellite TV providers. Such systems can be referred to as Personal Video Recorders (PVR), Digital Video Recorder (DVR), or Time Shifting Entertainment System.

Such systems can, and usually do incorporate some form of digital storage device for recording of programming e.g. HDD, SSD, or other future storage methods. When use of storage sub-systems and cooling fans is incorporated, the unit shall be tested as in 5.1, 8.5 and the relevant clauses of this annex.

For equipment which emits sound in the 16 kHz octave band, the procedures specified in ECMA-108 for sound power levels shall be used (see Table 4).

#### C.23.2 Installation

The constituent units of the system may be tested individually and reported accordingly. In this case the installation conditions are as in 5.1, 8.5 and the relevant clauses of this annex.

Alternatively the equipment may be tested as a complete system. In this case for the determination of sound power levels, the equipment shall be mounted on the hard reflecting floor and the setup used recorded.

#### C.23.3 Operation

#### C.23.3.1 General

Operation of the equipment shall be in accordance with 5.3 and 8.5 for the following modes of operation.

#### C.23.3.2 Idle mode

Power shall be switched on, the equipment shall be in a steady-state condition, with air-moving device(s) running, if any, optical drives, if any, in idle mode as in C.19, system operating disk drives in a "pass through" manner (neither explicitly recording nor explicitly playing back).

#### C.23.3.3 Operating mode(s)

One or more of the following operating modes shall be used where applicable.

- a) Equipment with rigid disk drives:
  - 1) Operating condition shall be determined in accordance with C.9.3.2 where  $n_s$  shall be: 12Mb/s (HD) or 2Mb/s (SD), divided by the number of user data bits per track on the HDD multiplied by the total number of read/write video streams.

If complete information for the previous paragraph is not available, the user can determine the number of tuners incorporated within the system. Once determined, simulate explicit recording of the same number of media streams as there are tuners while simultaneously explicitly playing back one media stream or however many media streams are the system's advertised capacity.

- 2) With air-moving device(s) running
- b) Equipment with optical drives.
  - 1) Operate optical drives as described in C.19.



- 2) With air-moving device(s) running
- c) Equipment with other parts with operating modes not described above: name and operating conditions shall be included in the report if a measurement is performed.

## C.23.4 Measurement time interval

The time-averaged sound pressure level shall be measured for at least the measurement time interval specified in 6.7.2, 7.7.2 or 8.7.2 as applicable.



## C.24 Equipment category- Large format printers (LFP)

## C.24.1 Description

This equipment category covers electronically controlled office equipment capable of printing pre-recorded information on sheet or roll paper stationery 420 mm or more in width. Some LFP may be capable of scan, copy or facsimile operations in addition to printing.

NOTE 1 420 mm is the smaller dimension of ISO A2 size paper

NOTE 2 Equipment not suitable for the office is excluded. Examples include equipment producing noxious fumes, or equipment requiring electrical, burn, or entrapment hazard safety training.

NOTE 3 For character printers and line printers, see C.3; for teleprinters, see C.4; forsingle-function printers, see C.16; for non-LFP multi-function printers, see C.21.

#### C.24.2 Installation

#### C.24.2.1 General

Floor-standing printers shall be installed on the hard reflecting floor. Printers which are normally placed on a special stand shall be installed on such a stand on the reflecting floor. Printers which are placed on an office table or desk and which take paper from, or stack paper on, the floor, shall, if possible, be placed in the centre of the top plane of the standard test table (see A.1), using the floor to support the paper. For such measurements in accordance with Clause 7, the measurement surface terminates on the reflecting floor.

Table-top printers, which do not use the floor for the paper supply or exit stack, shall be placed on the hard reflecting floor for measurements in accordance with Clause 6 or 7 and on the test table for measurements in accordance with Clause 8.

For the purposes of declaring A-weighted emission sound pressure level in accordance with ECMA-109, the bystander positions are applicable.

### C.24.2.2 Paper

Paper shall be representative of the typical use of the LFP. Unless otherwise specified, gloss and/or semi-gloss paper of grammage of 200-300 g/m² shall be used for LFP designed for graphics applications, and plain paper of grammage of 60-90 g/m² shall be used for LFP designed for CAD applications.

The width of the paper shall match the maximum width capability of the LFP.

When roll paper is used, the amount of paper on the roll shall be at least one-half of the amount of paper on a new roll of paper. When sheet paper is used, the paper cartridge shall be at least half full.

Paper storage and unpacking shall be carried out in accordance with manufacturer's instructions. If there are no such instructions, paper shall have been stored unpacked and exposed to the environmental conditions specified in 6.3.2 or 7.3.2 whatever appropriate, for at least 24 h immediately prior to the test.

## C.24.3 Operation

### C.24.3.1 Idle mode

Idle mode is a steady state condition that occurs after completion of print or copy operation. Several idle modes may be present, each with unique noise and duration, for example, step-down or variable speed cooling fan operation.



Idle noise shall be measured after print or copy job completion with the power switch remaining on. The idle mode lasting at least one minute with highest noise emissions shall be measured and reported.

The measurement time interval of idle noise shall be in accordance with C.24.4.

#### C.24.3.2 Operating modes

#### C.24.3.2.1 General

Operations shall use the pattern of Figure C.8 scaled according to C.24.5 and Figure C.8.

Default quality operations shall be measured. For monochrome LFP monochrome operations shall be tested. For colour capable LFP colour operations shall be tested, and monochrome operations shall also be tested if colour and monochrome operating speeds differ.

Print speed and print quality shall be at default settings for the type of paper type used.

#### C.24.3.2.2 Modes of operation

At least one mode shall be chosen and measured according to manufacturer's instructions. If there are no such instructions, at least mode a) shall be measured.

The remaining mode(s) are optional and may be measured at the discretion of the equipment manufacturer.

#### a) Print

One-sided continuous printing shall be measured unless two-sided printing is the default mode, in which case two-sided continuous printing shall be measured.

#### b) Miscellaneous operations

Various operations may be measured at the discretion of the test requestor. Examples include:

- Alternative stationery, e.g. heavy paper, envelopes and transparencies
- Duplex printing, copying and scanning
- Standard output devices not representative of use
- Optional (non-standard) output devices
- Optional (non-standard) input devices like high capacity input trays
- · Event combinations such as combined printing and paper cutting

#### C.24.4 Measurement time interval

The time-averaged sound pressure level shall be measured at least for three cycles of operation and the minimum duration specified in 6.7.2, 7.7.2 or 8.7.2 as applicable for the modes of operation described in C.24.3, as follows.

For LFP having a print carriage moving perpendicular to advancing paper, a paper advance and the associated carriage stroke(s) across the width of the paper comprise an operating cycle. For such LFP the print carriage may make one or two strokes depending on the sequence designed into the LFP.

For LFP without a moving carriage, for example printers with inkjets spanning the paper, steady-state printing of one sheet comprises an operating cycle. Other associated events like loading, cutting, and ejecting of paper may be excluded from the measurement; however, these events may be included in the measurement when their removal is not feasible because they are simultaneous or close together in time. The measurement shall exclude ramp-up behaviour at the start of a print job and shall exclude ramp-down behaviour at the end of a print job.



When an operation does not fulfil the measurement time interval, additional operations shall be measured such that their summed durations fulfil the required measurement time interval. In this case, noise emission levels L are computed using formula C.9 with the word "flatbed" replaced by the appropriate operation.

NOTE Paper loading, cutting, and ejecting tend to be less repeatable than the events comprising the operating cycle and therefore may be omitted to increase measurement repeatability. Paper eject tends to be especially non-repeatable due to the nature of the paper impacts against floor or printer structure that follow cutting, particularly for carriage equipped LFP.

## C.24.5 Colour pattern scaling

The print pattern of Figure C.8 shall be uniformly scaled to span the print area width shown in Figure C.9. The print area width is the media width reduced by a maximum 30 mm left margin and a maximum 30mm right margin.

### C.24.6 Reporting

Quality:

Noise emissions of the idle and default operations shall be reported. Noise emissions for operations other than the default operations may be reported. For the idle operation, the description "idle" shall be provided. For operations other than idle, the following information shall be reported:

Media: Paper grammage weight
Operation: "print", "copy" or "scan"
Rendering: "mono" or "colour"

"best", "normal", "draft", etc.

Print area width

Print area

Print area

Right margin

Max 30 mm

Max 30 mm

Figure C.9 — Scaling of the Figure C.9 print pattern to the print area





## Annex D (informative)

## Identification and evaluation of prominent discrete tones

## D.1 Scope

This Annex specifies two methods for determining whether or not noise emissions contain prominent discrete tones by reference to ECMA-418 "Psychoacoustic metrics for ITT equipment - Part 1 (prominent discrete tones)", which gives such details. They are referred to the tone-to-noise ratio method and the prominence ratio method.

The application of this Annex is optional and arbitrarily additional to the requirements of Clause 8. However, when applied, discrete tones occurring at any frequency within the one-third-octave bands having centre frequencies from 100 Hz to 10 000 Hz (i.e., discrete tones between 89,1 Hz and 11 220 Hz) shall be evaluated by either of the two methods in this Annex.

NOTE At the discretion of the user of this Standard, both methods may be applied to same discrete tone of interest. In such a case, it is noted that the evaluation results of the two methods are considered individual.

## D.2 Information to be reported

For each discrete tone that has been identified as prominent in accordance with this Annex, the following information shall be recorded:

- a) the frequency,  $f_t$ , in hertz, of the discrete tone;
- b) details of the method used to evaluate the discrete tone (tone-to-noise ratio or prominence ratio), together with a reference to ECMA-418-1 including its publication date and edition;
- c) if the tone-to-noise ratio method was used, the tone-to-noise ratio,  $\Delta L_T$ , in decibels or if the prominence ratio procedure was used, the prominence ratio  $\Delta L_P$ , in decibels;
- d) if the noise emissions under investigation include more than one identified prominent discrete tone, the frequency of each tone, and either  $\Delta L_T$  or  $\Delta L_P$  for each tone.





## Annex E

(informative)

# Background information on the method formerly used for the detection of impulsive noise

Since its publication of the 1<sup>st</sup> edition of 1981 September, this Standard had provided an objective test method for determining whether the noise emissions are impulsive in character, or not. The method had relied on time-weighting I specified in the well-known sound level meter's International Standard, IEC 61672-1 (or IMPULSE mode of its predecessor standards).

By the update of IEC 61672-1:2013, however, the technical specifications of time-weighting I have been removed. It is also noted that, by the previous update of IEC 61672-1 in 2002, this IEC standard, in its Annex C, mentioned the following:

"Various investigations have concluded that time-weighting I is not suitable for rating impulsive sounds with respect to their loudness. Time-weighting I is also not suitable for assessing the risk of hearing impairment, nor for determining the "impulsiveness" of a sound. Because of the possibility of obtaining misleading results, time-weighting I is not recommended for the purposes described above."

Therefore, it was a matter of time for the specification to be withdrawn. Eventually, the method of this Annex E became unable to maintain, and the technical contents have been removed. The 12<sup>th</sup> Edition ECMA-74 is the last edition to contain Annex E with an objective method for the detection of impulsive noise using the time-weighting I.

For such historical reasons and also, however, for the possibility of future development of another method for impulsive noise detection, this Annex E remains, but, the title was revised, accordingly.





# **Annex F** (informative)

## A hearing model approach to calculate psychoacoustic parameters

The reader is referred to ECMA-418 "Psychoacoustic metrics for ITT equipment - Part 2 (models based on human perception)". ECMA-418-2 Clause 5 describes the hearing model approach for determining the specific loudness of a sound. This result is used as basis for further psychoacoustic analyses. Noise data recorded per ECMA-74 are used to implement the psychoacoustic methods of ECMA-418-2.





## **Annex G** (informative)

# Identification and evaluation of prominent tonalities using a psychoacoustic tonality calculation method

The reader is referred to ECMA-418 "Psychoacoustic metrics for ITT equipment - Part 2 (models based on human perception)". ECMA-418-2 Clause 6 describes a perception-model-based procedure for determining whether or not noise emissions contain prominent tonalities, and if present, their strengths: the psychoacoustic tonality calculation method. Prominent perceived tonalities arise from a variety of causes including but not limited to prominent discrete tones: discrete tones, non-pure tones, narrow elevated noise bands, combinations of tones and narrow elevated noise bands, and combinations of these. Noise data recorded per ECMA-74 are used to implement the psychoacoustic methods of ECMA-418-2.





# **Annex H** (informative)

# Identification and evaluation of prominent roughness using a psychoacoustic roughness calculation method

The reader is referred to ECMA-418 "Psychoacoustic metrics for ITT equipment - Part 2 (models based on human perception)". ECMA-418-2 Clause 7 describes a perception-model-based procedure for determining whether or not noise emissions contain prominent roughness, and if present, their strengths: the psychoacoustic roughness calculation method. Roughness originates for example from a multiplicative combination of two vibrations – such as for example the gear mesh frequency and the rotational speed in a gear wheel – or from superposition of two or more sounds with a similar frequency. In practice, roughness often occurs in rotating components (engines, gearboxes, fans). Noise data recorded per ECMA-74 are used to implement the psychoacoustic methods of ECMA-418-2.





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